

# Nanofluidic chips for cryo-EM structure determination from picoliter sample volumes

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**Cryogenic electron microscopy has become an essential tool for structure determination of biological macromolecules. In practice, the difficulty to reliably prepare samples with uniform ice thickness still represents a barrier for routine high-resolution imaging and limits the current throughput of the technique. We show that a nanofluidic sample support with well-defined geometry can be used to prepare cryo-EM specimens with reproducible ice thickness from picoliter sample volumes. The sample solution is contained in electron-transparent nanochannels that provide uniform thickness gradients without further optimisation and eliminate the potentially destructive air-water interface. We demonstrate the possibility to perform high-resolution structure determination with three standard protein specimens. Nanofabricated sample supports bear potential to automate the cryo-EM workflow, and to explore new frontiers for cryo-EM applications such as time-resolved imaging and high-throughput screening.**

cryo-EM | specimen preparation | MEMS | nanofluidics

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## Introduction

Sample preparation of frozen-hydrated biological macromolecules continues to present a major challenge for routine structure determination by three-dimensional cryogenic transmission electron microscopy (cryo-EM). To obtain a three-dimensional structure, a thin film of an aqueous solution containing the protein of interest must be cooled so rapidly that water molecules do not crystallise but form amorphous ice. Within this layer, ideally not much thicker than the particle itself, the particles must be partitioned in random orientations. The prevailing method for making thin specimens suitable for cryo-EM has not changed substantially since its introduction several decades ago: a filter paper is pressed against one or both sides of a fenestrated support film spanning a metallic mesh grid across which a droplet of the biological sample is suspended, and then rapidly plunged into a liquid cryogen (1). A recognised shortcoming of this method is that a reproducibly thin and consistently uniform ice layer can often not be achieved (2, 3). Frequently, time-consuming parameter optimisation is required to find conditions suitable for high-resolution imaging, and these conditions are typically different for each sample. Even if such conditions are found, additional problems encountered in practice include preferential orientation of particles (4, 5), preferential interaction of particles with the support film (6) and partial denaturation of particles due

to exposure to the large air-water interface (5, 7–10).

The inefficiency of current cryo-EM sample preparation approaches to yield reproducible results has led major efforts to explore different ways to make uniformly thin films, including the development of self-wicking grids (11), spraying small-volume droplets onto holey support films (12–14) and direct thin film dispensing onto cryo-EM grids (15–17). These developments have increased the speed of sample preparation and reduced the required sample volume by orders of magnitude. Perhaps surprisingly though, the core design of fenestrated EM grid supports has remained largely unchanged. Despite the accelerated sequence from sample deposition to vitrification, the exposure of particles to the air-water interface inherent to grid-based sample supports continues to pose a major obstacle for robust sample preparation workflows (18, 19).

The detrimental effects of an air-water interface could be avoided entirely if the sample were encapsulated within an enclosure made of a substrate sufficiently electron-transparent for high-contrast imaging of weak phase objects. Liquid-phase transmission electron microscopy (LP-EM) has been widely applied to image liquids inside the vacuum of an electron microscope by enclosing them in liquid cells (20, 21). Microfabrication of LP-EM sample cells has drawn on advances in semiconductor-manufacturing processes, in particular the use of free-standing silicon nitride (SiN) membranes (22–24). This approach has also been successfully employed for room temperature LP-EM of biological macromolecular specimens (25, 26). To render liquid cells mechanically robust against elastic deformation caused by the pressure differential between the fluid-filled cell and the vacuum in the microscope column, LP-EM cells contain relatively thick (30–50 nm) SiN membranes, whose additional scattering contributes structural noise that limits the attainable resolution to about 30 Å (25).

In vitrified samples the solidified water behaves as an ultra-viscous fluid (27). In this case elastic deflection of fluidic cells under a pressure difference is negligible, which offers opportunities for employing much thinner cells and membranes. Inspired by this prospect, we set out to design a nanofluidic sample cell for cryo-EM imaging. By miniaturising a sample-containing volume into a microelectromechanical system (MEMS) with ultrathin SiN membranes,

we fabricated a cryo-EM sample support that allows cryo-EM imaging from picoliter sample volumes. We demonstrate the performance of this device by high-resolution 3D structure determination of three protein model systems, apoferritin, T20S proteasome and tobacco mosaic virus.

## Results

### A nanofluidic sample support for cryo-EM imaging.

To address common issues in cryo-EM grid preparation such as poor reproducibility of ice thickness, the destructive effect of the air-water interface and to broaden the scope of cryo-EM applications with the unique design flexibility of MEMS technology, we developed a novel cryo-EM sample support using nanofabrication techniques. We used a sacrificial polysilicon process for fabrication of a device featuring nanofluidic channels for controlled cryo-EM sample preparation and imaging [Fig. 1, Fig. S1]. The nanochannels are enclosed by ultrathin membranes made from silicon-rich nitride ( $\text{SiN}_x$ ) that allow for transmission of the electron beam when a thin film containing the sample is encapsulated in the space between them. The core design of this device, which we refer to as cryoChip, consists of a 2 x 2 mm silicon base with 100  $\mu\text{m}$  thickness [Fig. 1a]. A hollow microcantilever extends over the side of the chip base for sample application via capillary action. An aperture in the center of the silicon base exposes a 50 x 50  $\mu\text{m}$  free-standing  $\text{SiN}_x$  membrane containing parallel rows of nanochannels that are connected to the central supply and exit channels via multifurcations. Transversal silicon oxide layers provide mechanical stability and generate a regular grid of observation windows that are 6x4  $\mu\text{m}$  in size [Fig. 1b]. Each observation window exposes a segment of the nanochannel for TEM imaging [Fig. 1c]. CryoChips differ in several fundamental aspects from grid-based sample supports: Instead of wicking a suspended droplet to a liquid film thin enough for transmission imaging, sample thickness in cryoChips is controlled by the geometry of electron-transparent nanochannels itself. The closed channel architecture avoids the air-water interface, which is replaced by a solid-liquid interface between the  $\text{SiN}_x$  membrane and the sample solution. With minimal adaptations, cryoChips are fully compatible with the most frequently used cryo-EM sample carrier cartridges [Fig. S2].

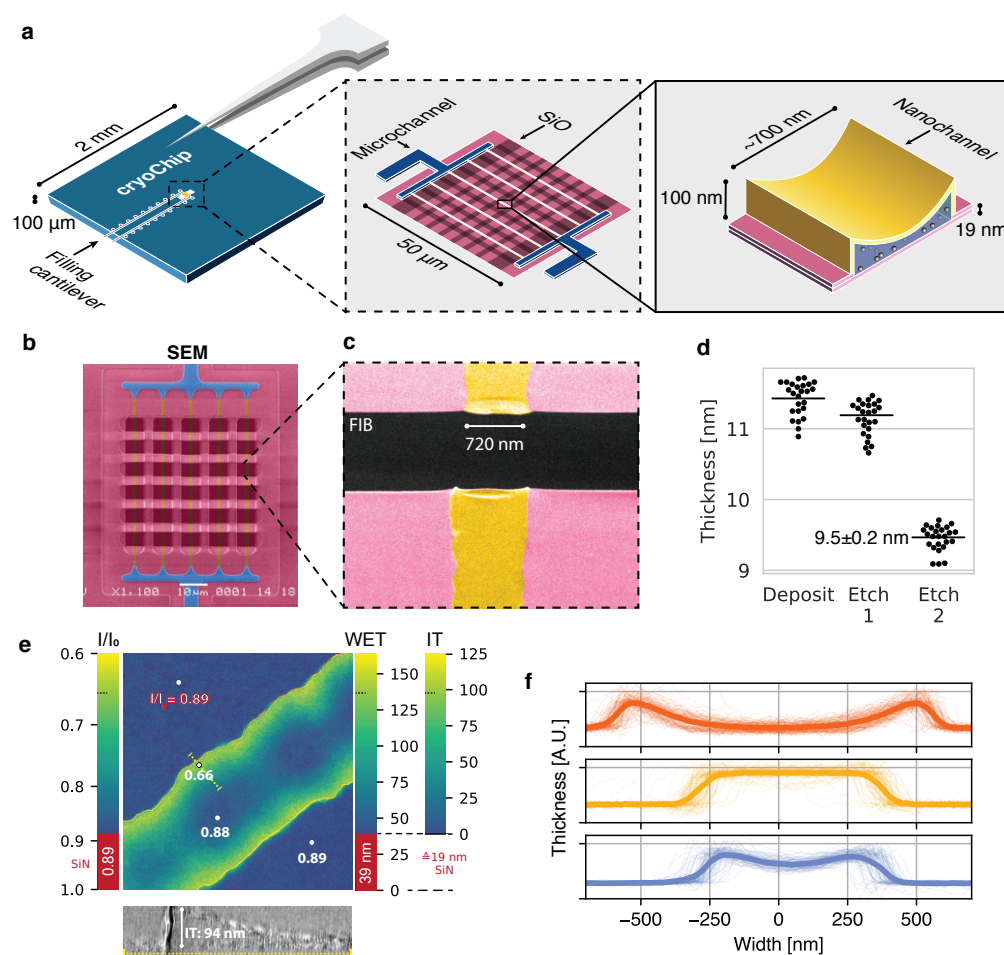
### Geometric control of ice thickness.

Control over ice thickness is a critical step for cryo-EM sample preparation. In standard blotting-based sample preparation, parameters such as blot force and time, absorbent properties of the filter paper, as well as relative humidity and temperature of the sample environment need to be tightly controlled. Despite the availability of robotic vitrification systems, achieving good reproducibility of these parameters has remained difficult and substantial across-grid and grid-to-grid variation of ice quality are common (2). MEMS-based nanofabrication provides a means to control sample thickness directly through channel geometry,

obviating the need for a particular sample environment and optimisation of blotting conditions. To quantify the reproducibility of ice thickness in cryoChip nanochannels, we first determined the average thickness of the silicon nitride layer by replicating the  $\text{SiN}_x$  deposition and etching protocol employed for device fabrication on a blank wafer area. Using ellipsometry we measured a film thickness of  $9.5 \pm 0.2$  nm for the final  $\text{SiN}_x$  layer [Fig. 1d]. We then filled the chip and used zero-loss imaging to determine the thickness of ice-filled nanochannels from the ratio of the integrated intensity of the zero-loss peak  $I_0$  relative to the integral of the whole spectrum  $I$  [Fig. 1e]. From the zero-loss log ratio of a  $\text{SiN}_x$  area adjacent to the nanochannel (0.89) and the geometric film thickness determined by ellipsometry (19 nm, corresponding to the combined thickness of top and bottom membrane), we calculated the mean free path for inelastic scattering (IMFP) at 300 keV in  $\text{SiN}_x$  as 163 nm, from which we estimate a combined water-equivalent thickness of 39 nm for the two  $\text{SiN}_x$  membranes forming the nanochannel assuming an IMFP of 320 nm for vitreous ice (28). We next mapped the apparent and absolute ice thickness at each image position. The channels display a concave profile in cross-section, leading to a gradient with a maximum thickness of  $\sim 100$  nm at the channel wall and 0 nm at the channel center. These estimates are in agreement with those obtained from a tomographic reconstruction from the same image area [Fig. 1e]. We evaluated the consistency of nanochannel geometry both across individual cryoChips and between different chips. The precision of the sacrificial layer deposition in the fabrication process permits tight control over the maximum channel height. The width of the nanochannels is consistent across individual chips, but can range from 650 nm to 1000 nm between different chips which we attribute to process variability and/or the chip position on the wafer during fabrication [Fig. 1f].

### Rapid, loss-less preparation of cryo-EM samples via microcantilevers.

To facilitate filling of the device from nanoliter sample droplets, we designed a hollow microchannel cantilever that allows sample application via spontaneous capillary flow without requirement for external appliances. The hollow microchannel cantilever extends only 100  $\mu\text{m}$  over the chip base. To allow efficient targeting of the cantilever, we built a loading station consisting of a microvolume positive displacement syringe mounted on a linear XYZ precision stage, as well as top and side-view cameras to monitor the approach of the nozzle and filling process [Fig. 2a]. The syringe nozzle is translated into close vicinity of the cantilever tip and a nanoliter droplet is formed. Manual handling of the syringe and the geometry of the nozzle currently limit the minimum droplet volume to about 10-40 nL [Fig. 2b]. The cantilever is then dipped into the nanodroplet. Upon contact with the cantilever tip, a small sample volume is drawn into the cantilever by capillary forces and subsequently distributed across the cen-



**Fig. 1. A nanofluidic sample support for cryo-EM.** (a) Schematic representation of the MEMS-based cryoChip. The 2 x 2 mm chip base features two microcantilevers for sample filling and air escape. The cantilevers are connected to microchannels leading to a free-standing observation membrane located within an aperture at the chip center (middle inset). A multifurcation connects the microchannels (blue) to an array of five parallel nanochannels (yellow) of approximately 700 nm width and 100 nm height (right-most inset). The top membrane is smoothly sagging, while the bottom membrane is flat. (b) False-colour scanning electron microscopy (SEM) image of the observation membrane. (c) False-colour SEM image of a single nanochannel with FIB-milled rectangular opening across the observation membrane (d) Ellipsometric determination of SiNx membrane thickness after deposition and etching steps. (e) Relative thickness map of an ice-filled nanochannel from zero-loss imaging. WET=water-equivalent thickness, IT=ice thickness. The thickness profile correlates with a 2D slice of a tomogram acquired of the same area (bottom). (f) Thickness cross-sections of nanochannels from three chips of the same wafer. Thin lines are individual nanochannel cross-sections measured across a whole chip, thick lines represent their mean.

tral nanochannels via the multifurcation connected to the entry microchannel [Movie SM1]. From the geometry of the overall channel design, we estimate the total filling volume to be ~4 pL (see Methods), which is about six orders of magnitude less compared to typical sample volumes of conventional blotting-based methods. Residual sample of the filling droplet can be readily recovered.

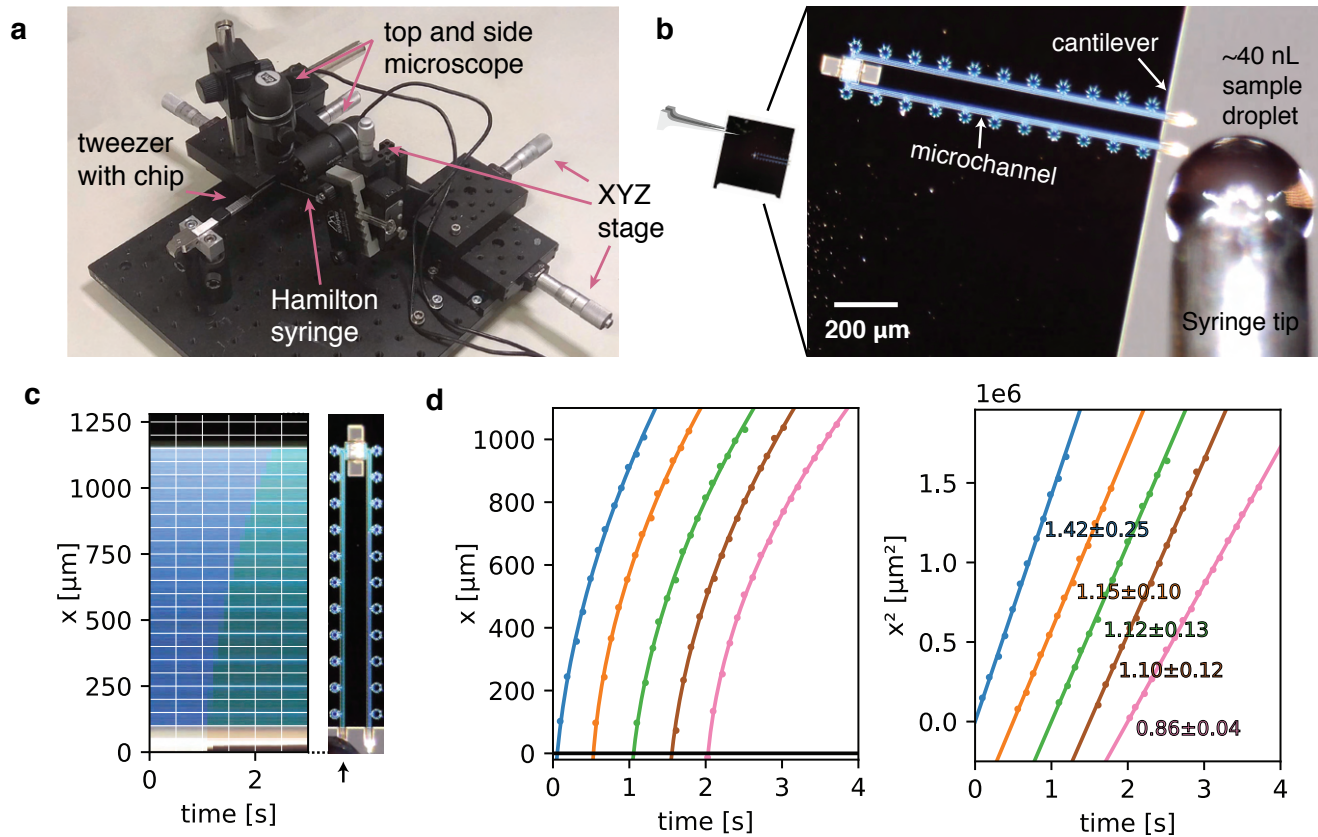
To analyse fluid kinetics in the microchannels, we filled a series of cryoChips via the sample application cantilever to generate kymographs and determined the capillary flow rate by monitoring the position of the filling meniscus over time. We observed the movement of the liquid front to be proportional to the square root of time, which is in accordance with classical Washburn kinetics for capillary flow (29). Filling is rapid and complete filling of the entry channel proceeds at an average of ~1 mm/s [Fig. 2c]. The filling speed is fast at the beginning and slows down with progression of the liquid front, as predicted by the Washburn equation. We found similar behaviour across the chips that were analysed, suggesting that we can achieve high channel-to-channel reproducibility during fabrication [Fig. 2d, Fig. S3]. The entire filling process can be executed in a lab environment without humidity control and there is no further requirement for parameter optimisation other than sample concentration. After sample filling, the chip

can be transferred to any manual or robotic vitrification device for flash cooling in liquid cryogen. In our experiments, the total time from filling to vitrification was approximately 10 seconds. This process could be readily accelerated by integrating the filling mechanism directly on a vitrification system.

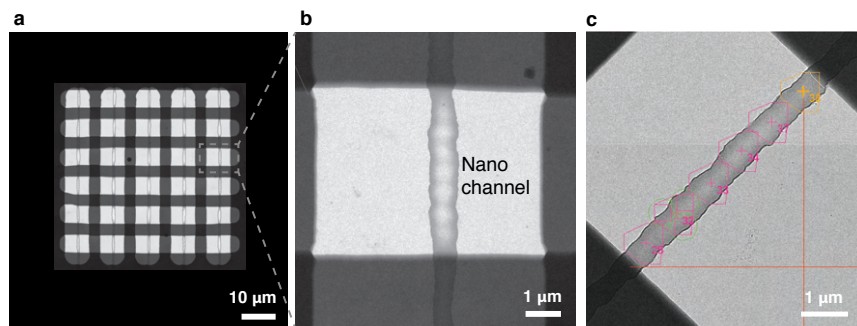
### Automated cryo-EM data collection with cryoChips.

The checkerboard pattern from the silicon oxide layers on the observation membrane structures the nanochannel array into a regular grid of 30 observation squares, each comprising a segment of an individual nanochannel and flanking areas of the SiNx membrane [Fig. 3a,b]. Due to the different layout of the cryoChip, standardised data acquisition protocols established for holey support film substrates cannot be applied without modification. To develop an automated data acquisition strategy for cryoChips we first acquired a grid map of the entire observation membrane using SerialEM. For each observation square we then selected six equally spaced acquisition points positioned linearly along the midline of the nanochannel [Fig. 3c]. We used virtual maps (33) generated from medium magnification images to accurately realign to the acquisition points during high-magnification acquisition. For each of the acquisition points, three images were acquired radi-





**Fig. 2. Sample preparation with cryoChips.** (a) Manual filling station with side view and top view microscope, microvolume glass syringe, xyz precision stages for translation of the syringe and a mount for tweezers holding a cryoChip. (b) Sample loading of a cryoChip seen with the top view microscope. One of the cantilevers is approached with a ~40 nL sample droplet. (c) Kymograph of the filling process showing the progression of the sample meniscus over time. The arrow indicates the cantilever and the supply channel. (d) Filling kinetics of cryoChips. The meniscus position and associated time value were recorded at 10 fps with the top-view microscope, revealing a decreasing filling rate with progression of the fluid front (left panel). Each graph represents data from one filling experiment. Graphs from individual experiments are spaced apart by 0.5 s for better visualisation. The squared meniscus position (right panel) displays a linear relationship with elapsed filling time in agreement with expectation from Washburn kinetics. Solid lines are non-linear fits to the data. Slopes ( $10^6 \mu\text{m}^2/\text{s}$ ) and their standard deviations from bootstrapping statistics are shown.



**Fig. 3. Automated data acquisition with cryoChips.** (a) TEM image of the observation membrane with five nanochannels. The checkerboard structure is a stiffening layer made from silicon oxide that divides the nanochannels in observation windows. (b) Close-up of inset in (a). (c) Medium magnification image of an observation square with an overlay of the SerialEM multishot acquisition scheme containing six acquisition points along the nanochannel. Each acquisition point is centered on a polygon outlining the limits of three imaging positions achieved by beam-image shift, leading to a total of 18 images per observation square.

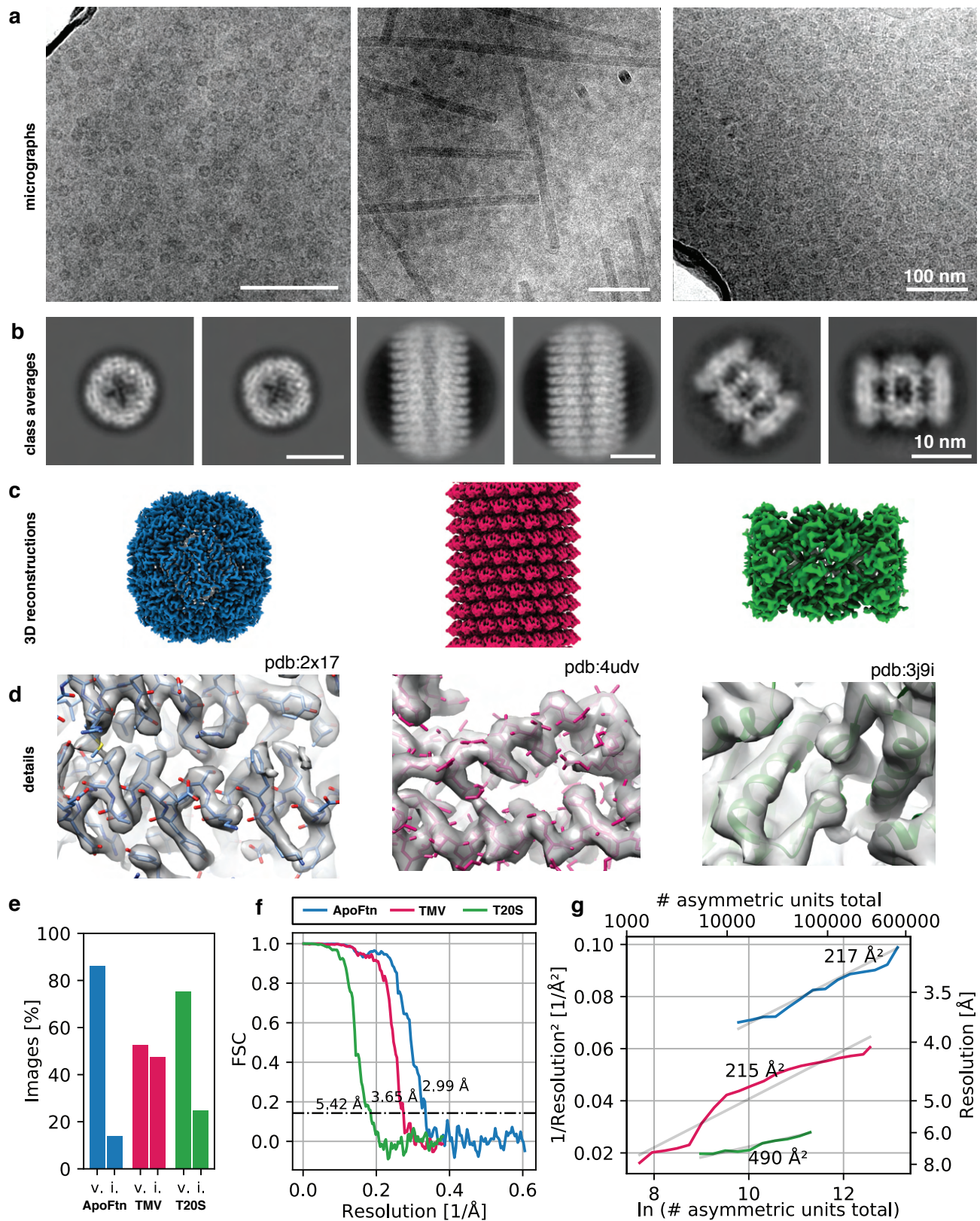
ally around the midpoint using beam-image shift, resulting in up to 540 images per cryoChip.

### 3D structure determination from cryoChip samples.

To validate the suitability of cryoChips for 3D structure determination, we collected datasets for three test specimen (*P. furiosus* ferritin (ApoFtn, 480 kDa, O), *T. acidophilum* 20S proteasome (T20S, 700 kDa, D7) and tobacco mosaic virus (TMV, 37 MDa, helical)) that we selected for differences in size, shape and symmetry. The low magnification maps revealed that most observation squares were suitable for data collection. We occasionally observed par-

tially broken or cracked membranes. Observation squares in such areas were omitted for data collection. Micrographs for all three specimens showed good image contrast [Fig. 4a]. To examine the compatibility of cryoChips with the condition to form vitreous ice, we evaluated the fraction of images containing crystalline ice by manual inspection for the presence of ice rings or crystalline reflections in the computed power spectra from all images. This led to a fraction of 815/945 86% (815/945), 75% (91/121) and 52% (43/82) of images that we classified as containing vitreous ice for ApoFtn, T20S and TMV respectively [Fig. 4e, Fig. S4]. This is consistent with convective heat-





transfer simulations of a simplified cryoChip model, suggesting that cooling below the glass-transition temperature occurs at timescales ( $<10^{-5}$ ) seconds compatible with vitrification [Fig. S5]. It is possible that the fraction of vitreous images is underestimated since we did not discriminate between ice features originating from surface contamination and those originating from crystalline ice in the nanochannels. We did not observe evidence for a correlation of the probability for forming crystalline ice and the location on the observation membrane.

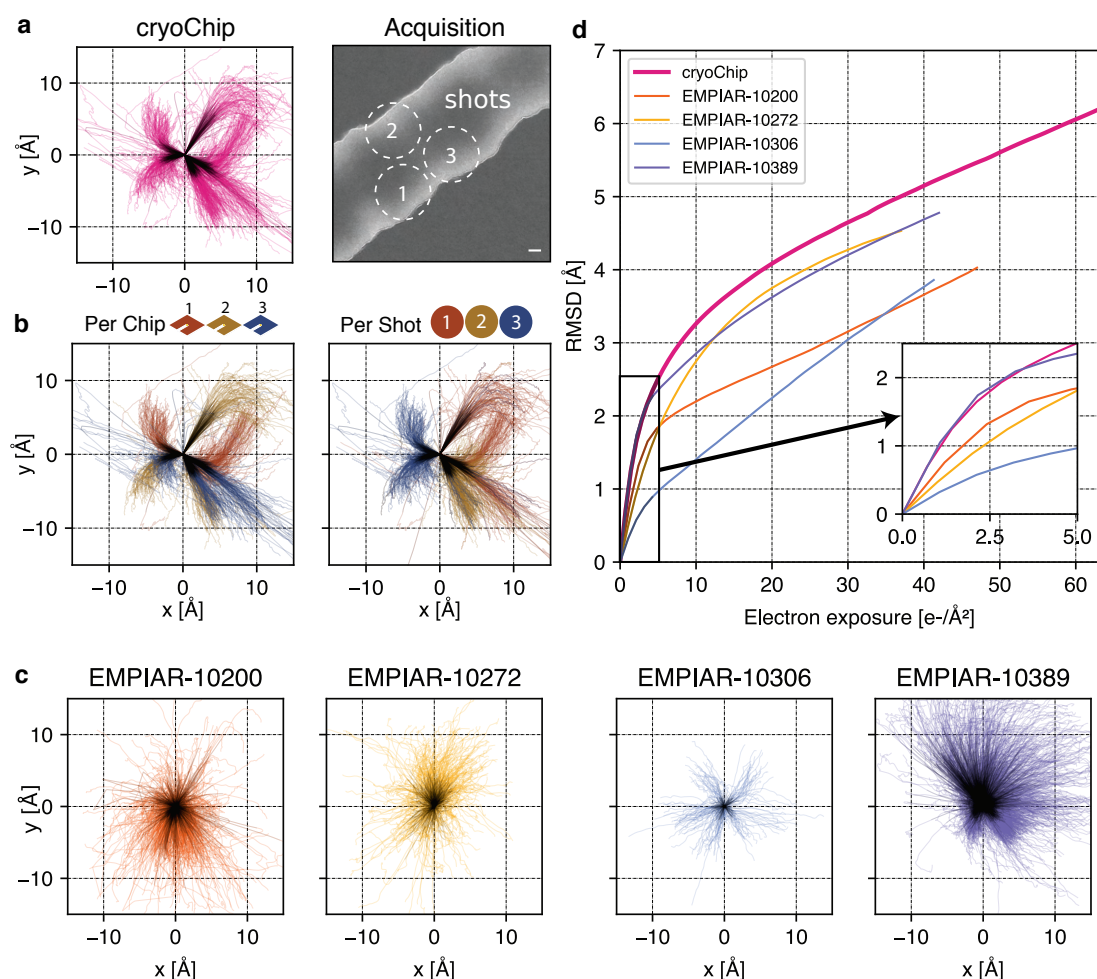
The  $\text{SiN}_x$  membrane forming the walls of the nanochannels leads to additional background noise from an increase in the fraction of electrons that are scattered inelastically. This effect is equivalent to an apparent increase in ice thickness, which even for particles in the thinnest parts of the nanochannel may lead to an (apparent) ice thickness significantly greater than the size of the particle itself. This is undesirable because it leads to a corresponding loss of useful signal in the image, thereby reducing image contrast. To test whether this additional scattering limits our ability to extract high-resolution signal for particle alignment, we used automatic particle picking in cryoSPARC 3.1(34) to extract particles (segments for TMV) and performed 2D classification. For all three specimens we observe high-contrast 2D class averages with visible features indicative of secondary structure [Fig. 4b, Fig. S6,S7,S8], suggesting that images contain sufficient contrast for high-resolution structure determination. To probe the resolution limit of data collected using the cryoChip, we merged data from three chips filled with ApoFtn acquired on a Titan Krios equipped with a post-GIF K2 camera and processed it in a standard single-particle analysis workflow. We used 2D and 3D classification to select a final set of 21,238 particles (O symmetry) from 815 micrographs and after 3D refinement obtained a reconstruction at an overall resolution of 3.0 Å displaying visible side chain densities [Fig. 4c/d, Movie SM2]. The reference model for 3D alignment was generated from the data itself using the stochastic gradient descent method [Fig. S6], suggesting that the quality of data collected from cryoChips is sufficient to allow initial model generation even for samples considered difficult for reference model generation. To demonstrate the versatility of cryoChips for structure determination from a variety of biological specimens, we also processed the datasets for TMV and T20S proteasome. [Fig. S7, S8]. These datasets were collected on a JEOL JEM3200-FSC with a K2 detector and yielded 3D reconstructions with overall resolutions of 3.7 Å and 5.4 Å obtained from 14,238 segments (20 asu/segment) and 5,750 particles (D7), respectively [Fig. 4f]. The quality of a dataset is often quantified from a plot of the inverse-squared resolution as a function of the number of particles used in the 3D reconstruction. The slope of this function is related to the Debye-Waller factor (B-factor) that describes the width of a Gaussian function used to model the loss of high-resolution information in particle images. We quantified the B-factors for each of the three datasets [Fig. 4g]. These B-factors are in the

range expected for structures determined at similar resolution using conventional sample preparation methods.

**Beam-induced specimen motion is comparable to standard cryo-EM supports.** Beam-induced motion is a major factor limiting the achievable resolution of 3D reconstructions. The highest rate of change in particle position is typically largest at cumulative exposures below  $\sim 4\text{e}^-/\text{\AA}^2$  (35), coinciding with the frames where the sample is yet least affected by radiation damage and high-resolution signal is best preserved. The fast read-out rates of direct electron detection technology have made it possible to acquire cryo-EM data as dose-fractionated movies where the total exposure is subdivided into a series of individual frames. To reduce information loss, alignment of these frames can be used to determine the overall inter-frame movement of the specimen in the micrograph during the exposure and then correct for this motion before summation of the frame stack. To investigate beam-induced sample movement in cryoChips, we computed and analysed the alignment trajectories for the ApoFtn dataset [Fig. 5a]. The calculated traces show that movement is largely unidirectional, but clusters into several distinct directions of motion. To further investigate the trajectories, we separated them either by chip or by the beam-image shift condition corresponding to the shot position in the multishot acquisition scheme for each acquisition point [Fig. 5b, Fig. S9]. For each of the chips analysed, we observe three clusters of directional motion, each associated with one of the three shot positions. While the precise origin for this clustering needs further investigation, we suggest that different thickness and geometry of the confined ice layer in the subregions for each of the multishot positions may lead to preferential directionality of specimen movement, possibly combined with microlensing effects resulting from adjacent exposures that induce the build-up of semi-static charge on the non-conductive  $\text{SiN}_x$  membrane.

To compare average specimen movement in cryoChips with other commonly used specimen supports we also computed the alignment trajectories for four datasets in the EMPIAR database (36)[Fig. 5c]. These datasets have been acquired using different specimen supports but resulted in high-resolution 3D reconstructions [Table S3]. We then computed the accumulated movement as the root mean squared deviation (RMSD) of all trajectories from the ApoFtn cryoChip dataset and the EMPIAR datasets and evaluated them over an equivalent exposure range [Fig. 5d]. The datasets show small differences in accumulated movement over the whole exposure, ranging from 3.8 (QF-R2/2) to 5.1 Å (cryoChip) RMSD over 0-40  $\text{e}^-/\text{\AA}^2$ . These movements are in the order of 0.1 pixel per frame and are therefore amenable to motion correction. These overall motions represent a combination of mechanical (stage) drift and beam-induced motion. Limiting motion in early frames is essential to maximise recovery of high-resolution detail. EMPIAR-10306 has a remarkably low initial movement of 0.7 Å, while both our dataset and EMPIAR-10389





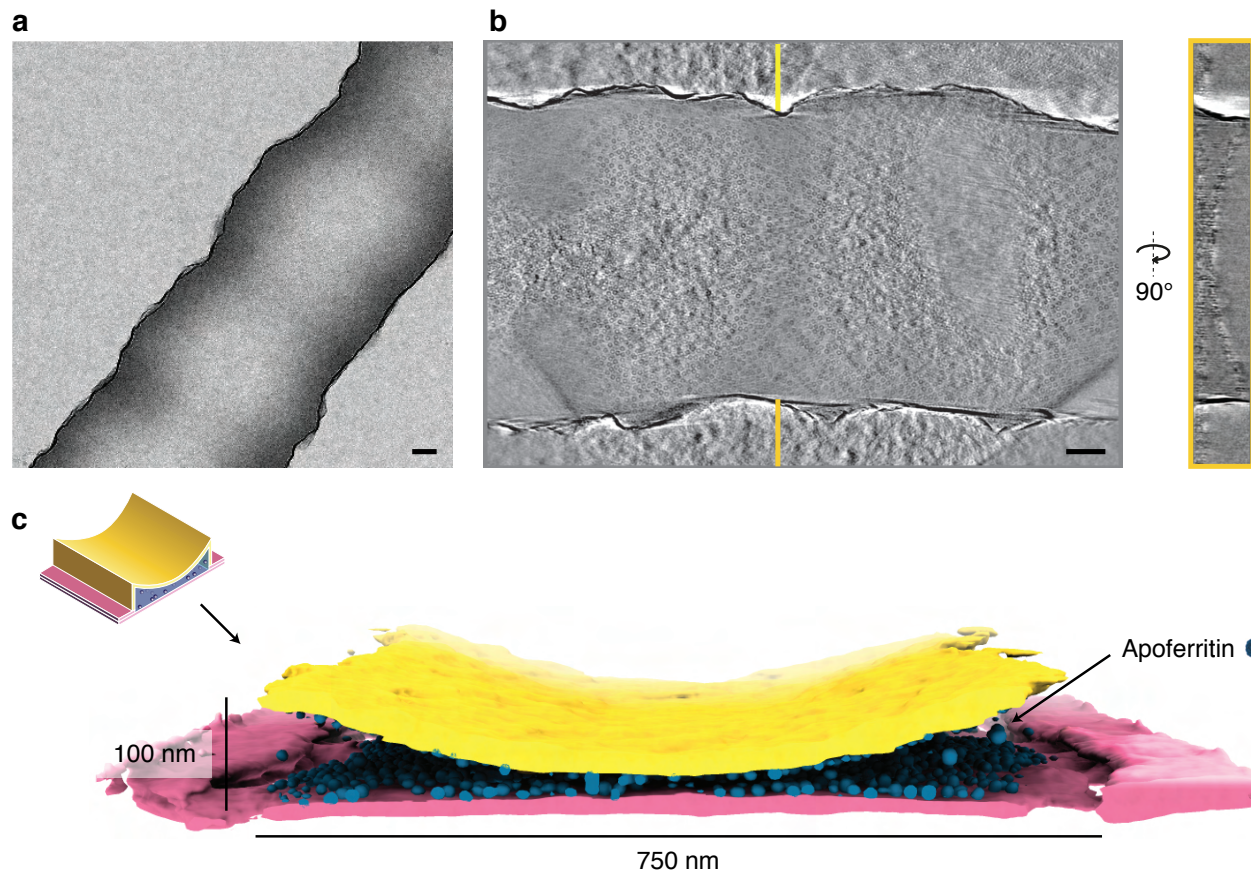
**Fig. 5. Comparison of beam-induced motion for cryoChip and reference datasets from conventional sample preparation.** (a) Whole-frame motion trajectories of dose-fractionated movies during exposure with 63 e-/Å² from three different cryoChips. (b) Trajectories coloured by chip or by imaging position in a repeating three-shot pattern. (c) Whole-frame motion trajectories of reference datasets. (d) Root-mean-square deviation (RMSD) of trajectories over electron exposure between the cryoChip dataset and reference datasets. The inset shows the first part of the exposure most critical for reconstructing high-resolution details. Scale bar in (a) is 100 nm. First five e-/Å² in trajectories are coloured in black.

display a accumulated motion of 1.8 Å. EMPIAR-10389 led to a 2.0 Å reconstruction of *Y. enterocolitica* urease, indicating that initial specimen movement of that order is not limiting for achieving resolution beyond 2.0 Å.

**Preferential partitioning to the solid-liquid interface effectively concentrates protein particles.** Interaction with the air-water interface may cause perturbation of molecular structure in thin film-based cryo-EM sample preparations. The closed sample environment of the cryoChip avoids the problems of an air-water interface, but the large surface-to-volume ratio of the nanochannels forms an extensive solid-liquid interface between the SiN<sub>x</sub> surface and the particle solution. We performed tomographic reconstructions of protein-loaded cryoChips to investigate particle distributions inside the nanochannels. The tomographic reconstructions confirm the overall geometry of the channels with an estimated height in cross-section ranging between 0-100 nm and a channel width of ~750 nm [Fig. 6a/b]. In all cases we find the majority of particles close to or associated with the SiN<sub>x</sub> membrane [Fig. 6c, Fig. S10]. Analysis of the orientation distribution showed increased abundance of views along the fourfold rotation axis for ApoFtn, indicating preferential alignment of parti-

cles with the SiN<sub>x</sub> membrane [Fig. S6]. Similarly, we find preferential abundance of side views for T20S particles [Fig. S8]. We did not observe convincing correlation of preferred orientations with the molecular electrostatic potential [Fig. S11]. We note that the current analysis is limited to particles with internal symmetry for which preferred orientations are less problematic. Further investigation will be required to conclude whether systematic effects for preferred protein adsorption to the solid-liquid interface exist and need to be addressed. Micrographs from datasets of all three specimen display particle densities exceeding those expected from conventional cryo-EM grids prepared with the same specimens and sample concentrations. To quantify this concentration effect, we estimated the particle concentration in the nanochannels by segmenting and counting ApoFtn particles, and measuring the channel volume from the reconstructed tomogram [Fig. S10]. We find 1483 ApoFtn particles within a 9.4x10<sup>6</sup> nm<sup>3</sup> volume, equivalent to a concentration of 262 μM or 126 mg/mL assuming 480 kDa molecular mass. This is a 37-fold increase in concentration compared to the initial sample concentration of 3.4 mg/mL. Interaction with the solid-liquid interface at the SiN<sub>x</sub> channel walls thus strongly affects the effective sample concentration in the nanochannels. Similar concentra-





**Fig. 6. Tomographic reconstruction of a cryoChip nanochannel filled with ApoFtn.** (a) Overview image of tomogram area of a nanochannel segment filled with ApoFtn. (b) Slice through the reconstructed tomogram and yz cross-section across the nanochannel indicated by lines. (c) Segmented reconstruction showing the nanochannel membrane (bottom: pink, top: yellow) and ApoFtn in the channel lumen (blue). The thickness of the membrane is affected by the missing wedge and not to scale. All scale bars: 100 nm.

tion effects have also been reported for traditional sample preparation methods, such as repeated sample application (37) and in the presence of very thin ice for which densely packed protein monolayers have been observed (38).

## Discussion

The process of sample preparation is widely perceived as a major bottleneck for realising the full potential of cryo-EM. All existing approaches to cryo-EM sample preparation rely on the ill-controlled formation of thin ice layers across fenestrated support films, which results in poor reproducibility and may detrimentally affect particle distribution, orientation and integrity (5, 8–10). Recent improvements to the support grids and to how the sample is applied have begun to address these issues (4, 10, 15–17, 39, 40). Despite these advances important issues remain, most prominently the hydrophobic environment of the air-water interface (18, 19). Here, we have shown that MEMS-based nanofluidic chips in which the sample is enclosed and protected from the air-water interface within electron-transparent nanochannels provide a viable alternative for cryo-EM sample preparation that mitigates some of the prevalent issues observed for grid-based sample supports. We demonstrated that biological specimens

in cryoChips can be successfully vitrified and that the thickness uniformity of the ice layer can be reproducibly controlled by channel geometry. We found the width and height of the nanochannels to be highly consistent across individual cryoChips, providing uniform imaging conditions for all parts of a chip.

The most widely applied methods for cryo-EM sample preparation typically require ~3  $\mu\text{L}$  of sample volume per grid. Assuming a final liquid film of 20–100 nm thickness spanning a 3.05 mm EM support grid, the required sample volume for imaging is only 1.5–7.0 fL, which is nine orders of magnitude less than the initial sample volume. Several recent developments are trying to reduce this gap: The Chameleon/Spotiton instrument eliminates sample waste from the blotting step by applying nanoliter sample volumes onto self-wicking grids via a piezo-electric droplet dispenser (11, 15). Similarly, the VitroJet and Cryo-writer (pin-)print sub-nanoliter volumes directly onto a small area of the cryo-EM grid (16, 17). The cryoChip presented here further reduces the required sample volume by 1000-fold to only a few picoliters, approaching the practical minimum for liquid handling in cryo-EM structure determination. The cantilever-based sample application efficiently drives chip filling via capillary action, thus allowing essentially loss-

less cryo-EM sample preparation. Together with the highly reproducible sample thickness we expect these properties to accelerate developments towards full automation of the cryo-EM sample preparation process. Notably, sample preparation using cryoChips does not require humidity control and is compatible with any standard plunger available in cryo-EM laboratories.

Despite our predictions from heat transfer simulations we observed that between 10-40% of images contain non-vitreous ice. Several factors may contribute to this discrepancy. Firstly, it is possible that cryogen is displaced by the chip base upon entering the cryogen, preventing complete wetting of the chip; or that air is trapped in the depression on the chip base below the free-standing observation membrane, preventing contact with the coolant and impeding heat transfer from the nanochannels. Secondly, the observation membrane is located at the chip center which could affect probability of vitrification, consistent with the spatial distribution of isotherms reported for standard holey film grids during immersion cooling (41). Parameters for existing plunging instruments have been optimised to maximise vitrification efficiency for holey film supports and it is conceivable that different plunging speed or depth, or jet-based cooling, may be more appropriate for cryoChips.

In standard cryo-EM sample preparation using holey support grids, the blotting process leaves a very thin layer of sample that can be imaged with high contrast and minimal secondary scattering from the particle-embedding ice layer. In cryoChips, the concave cross-sectional shape of the nanochannel produces a defined thickness gradient within which particles naturally partition into monolayers according to their molecular dimensions in the thinner parts of the channel, thus minimising background scattering from surrounding ice. The sample confinement in cryoChip nanochannels, however, comes with the penalty of additional incoherent scattering from the enclosing SiN<sub>x</sub> membranes, which results in reduced image contrast compared to ideal samples. By quantifying the additional scattering from the nanochannel membranes as an effective increase in ice thickness, we estimate the minimal scattering mass of particles that can still be successfully detected and aligned under these conditions to ~200 kDa (42, 43). This should render cryoChips suitable for imaging a wide range of relevant protein targets for cryo-EM structure determination.

We showed that cryoChips allow obtaining 3D reconstructions of biomolecular complexes at resolutions suitable for mechanistic interpretation. While we obtained 3D reconstructions with up to 3 Å resolution from ApoFtn particles imaged in nanochannels, this is lower than can be expected for an ideal ApoFtn sample imaged under similar conditions (44). Apart from incoherent scattering contributions by the SiN<sub>x</sub> membrane, several other factors

may currently limit resolution: Firstly, spectral properties of structural noise contributed by the SiN<sub>x</sub> membranes are different from those of vitreous ice, and secondly, there may be interference of signal from SiN<sub>x</sub> membranes and particles located at different focal heights within the nanochannel that may affect accuracy of CTF estimation (45). It is possible that assumptions on image statistics in current 3D reconstruction algorithms are sub-optimal for particles from cryoChips and improvements could be gained with modified software.

Another problem in cryo-EM is the degradation of image quality through electron radiation-induced particle movement (46). Beam-induced movement is assumed to be the result of a complex combination of radiolysis, charge build-up around the irradiation area and mechanical stress release during irradiation (47, 48). Several of these factors are of relevance for cryoChips. First, nanochannels are closed volumes implying that molecular hydrogen formed as a product of electron-beam induced radiolysis (49) cannot escape. Trapped gas may lead to pressure build-up inside the nanochannel and ultimately specimen movement. Second, SiN<sub>x</sub> is a poor conductor (resistivity >10<sup>14</sup> Ωcm at room temperature), suggesting that impaired charge dissipation could affect the observed specimen movement. While we found overall specimen movement in cryoChips to be higher than for modified support films, the residual particle displacement is not limiting for ~2 Å reconstructions and hence in a range suitable for high-resolution map interpretation. Just as continuous developments have pushed the limit of achievable contrast and residual specimen movement for holey support films (50), we expect that similar progress can be attained for nanofluidic supports by further improvements in electron transparency, as well as electrical and thermal conductance of the enclosing materials.

Tomographic reconstructions of sample-filled nanochannels showed that proteins preferentially partition to the solid-liquid interface of the nanochannel surface. This is consistent with observations using modified EM grids that contain surface substrates spanning the holey support film (10, 39, 51). While intuitively this appears to raise issues similar to adsorption at the air-water interface, the nature of the interaction with these surfaces is fundamentally different. The air-water interface is hydrophobic and adsorption of proteins to the interface can drive partial or complete unfolding to minimise the free energy of interaction (5, 9, 10). In contrast, similar to oxidised graphene, the polar SiN<sub>x</sub> surface is hydrophilic and adsorption of proteins is primarily mediated by the zeta potential of the interfacial electrical double layer (52). Consistently, for the three cases we investigated we do not observe that this interaction promotes denaturation or aberrant structural changes. It is entirely possible that the charge distribution between the molecular electrostatic potential and at the solid-liquid interface could promote preferential alignment

and hence carry the risk of systematic bias in particle orientation. We found modestly preferred orientation only for ApoFtn, but could not identify strong correlation with the molecular electrostatic potential.

We also observed that the strong interaction at the solid-liquid interface effectively concentrates the solute particles in the nanochannels, consistent with observations for other substrates providing solid-liquid interfaces such as hydrogenated graphene (51). While this is principally beneficial for concentrating dilute protein solutions to particle densities suitable for imaging, it also affects design considerations for the filling channels. In early design iterations of the cryoChips that featured narrow filling and exit channels, we observed apparent depletion of the protein sample before it reached the observation nanochannels. This effect was further aggravated with samples containing high surface charge densities. We attribute this to the very large surface-to-volume ratio of nanochannels, which we suspect may deplete solute proteins through interactions with the SiN walls in the filling channel, thus gradually reducing the free protein concentration in solution as they travel towards the observation membrane. The increased diameter of the filling channel in the current cryoChip design substantially improved the efficacy for reaching suitable particle concentrations in the nanochannels of the observation membrane. With solid-liquid interfaces gaining importance also for existing cryo-EM supports (10, 39, 50), further studies are needed to reveal the detailed dynamics and underlying mechanisms of particle adsorption to such interfaces, and to systematically investigate their effects on particle integrity and orientation.

We predict that the cryoChip is only the beginning of a range of future cryo-EM supports building on MEMS technology. Several immediate improvements can be achieved with minor modifications to our current design. Currently the observation membrane is 50  $\mu\text{m}$  x 50  $\mu\text{m}$ , representing less than 0.1% of the entire chip area. The imaging area can be readily extended by additional observation membranes, thus allowing fully automated collection of thousands of images with uniform ice thickness from a single chip. Parallel arrangements of observation membranes with separate filling channels will allow screening different samples on the same chip. Beyond this, the versatility of nanofabrication technology opens up possibilities to facilitate a range of new cryo-EM applications by bridging lab-on-a-chip approaches with structural biology. These include possibilities for on-chip mixing, parallelised high-throughput screening for structure-based drug discovery, time-resolved experiments, on-chip purification of complex protein mixtures and the combination of structure determination with biophysical measurements.

## DATA AVAILABILITY

The refined atomic model of ApoFtn has been deposited in the Protein Data Bank under accession number 7ohf. The cryo-EM densities of ApoFtn, TMV and T20S are available in the Electron Microscopy Data Bank under accession numbers EMD-12901, EMD-12903 and EMD-12915. Tomographic reconstructions of ApoFtn, TMV and T20S inside nanochannels are available in the EMDB under accession numbers EMD-12902, EMD-12914 and EMD-12917. Raw micrographs for all data have been deposited in the Electron Microscopy Public Image Archive (EMPIAR) with accession code 10708. Other data supporting the findings of this study are available from the authors upon request.

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## AUTHOR CONTRIBUTIONS

SH, ES, RH, WE and AJ designed and performed experiments. ES and RH performed fabrication of devices. SH expressed and purified ApoFtn and T20S, conducted and analysed cryoChip filling experiments, prepared cryo-EM samples and performed simulations. AJ purified TMV. SH, WE, FW, AJ collected; and SH, WE, and AJ processed and analysed cryo-EM data. All authors discussed the results, and SH and AJ wrote the paper with comments from all authors.

## COMPETING FINANCIAL INTERESTS

The use of microcantilevers with nanofluidic sample cells is described in a provisional patent application.



## Methods

**Chip fabrication.** The cryoChip is fabricated using a wafer-scale surface micromachining process. The fluidic components, such as hollow cantilevers, thick-walled supply- and exit channels, and thin-walled nanochannels, are all formed by sacrificial polysilicon etching techniques. The fabrication process starts on a 4 inches, <100>-oriented silicon wafer of 380  $\mu\text{m}$  thickness. The wafer is locally thinned from the backside to form silicon membranes with a thickness of 180  $\mu\text{m}$ , in which later the cryoChip membrane will be formed. The backside processing is performed by anisotropic wet etching of silicon in a 25% potassium hydroxide (KOH) solution at 75 °C. A 50 nm thick stoichiometric silicon nitride ( $\text{Si}_3\text{N}_4$ ) layer is used as the masking material for the KOH etch. After the KOH etching the masking layer is removed in concentrated hydrofluoric acid (HF 49%). On the locally thinned wafer, a 300 nm thick silicon oxide layer is deposited in a low pressure chemical vapour deposition (LPCVD) oven by pyrolysis of tetraethylorthosilicate (TEOS). The silicon oxide layer is patterned by buffered hydrofluoric acid (BHF). Silicon oxide is removed from an area where ultra-thin walled observation nanochannels will be formed. On the patterned substrate, an 11 nm silicon-rich nitride ( $\text{SiN}_x$ ) layer is deposited by LPCVD. This low-stress  $\text{SiN}_x$  layer serves as a bottom wall of the TEM observation windows, which will be created later. Next, a sacrificial layer of polysilicon with a thickness of 300 nm is deposited by LPCVD. This relatively thick polysilicon layer will be used to create the supply- and exit channels and a large fluidic channel inside the hollow cantilevers. The deposited polysilicon layer is patterned by tetramethylammonium hydroxide (TMAH). The layer is removed from a region where later the observation nanochannels will be formed. After the TMAH patterning, another sacrificial polysilicon layer with a thickness of 100 nm is deposited by LPCVD. The thickness of the second sacrificial layer determines the height of the small fluidic channels and the height of the TEM observation windows. On the other hand, the aggregate thickness of the first and the second polysilicon layer, which is 400 nm in our design, determines the height of the larger fluidic channels. After the deposition, sacrificial polysilicon is patterned by TMAH etching to define an outline of the fluidic channels. A rather thin thermally grown silicon oxide layer (40 nm) is used as an etching mask. It should be noted that both large (400 nm) and small (100 nm) fluidic channels are etched at the same time. The underetching of the mask, due to an isotropic nature of the TMAH etch process, is used to reduce the width of the fluidic channels in which the TEM observation windows will be formed. After patterning of the fluidic channels, the second silicon-rich nitride layer is deposited by LPCVD. The 11 nm thick low-stress  $\text{SiN}_x$  layer will define a top wall of the TEM observation windows. Thereafter, a 300 nm thick silicon oxide layer is deposited by TEOS pyrolysis. A multilayer of  $\text{SiN}_x$  and silicon oxide will form the walls of the hollow cantilevers and some fluidic channels. The relatively large thickness of these walls

provides mechanical stability of these components. After patterning of the second TEOS layer in BHF the TEM observation windows are completely defined. Subsequently, the TEOS/ $\text{SiN}_x$ / $\text{SiN}_x$ /TEOS multilayer is etched by reactive ion etching (RIE). In this processing step the contour of the chip and the hollow cantilevers are patterned. After the RIE etching, an access to the bulk silicon is created. By using Deep Reactive Ion Etching (DRIE) the bulk silicon is etched from the front side to a depth of 150  $\mu\text{m}$ . Finally, the wafer is placed in a 25% TMAH solution heated at 90 °C. During the TMAH etching, sacrificial polysilicon is removed through the access holes and the fluidic channels are created. These temporary access holes are automatically sealed after final drying of the samples. At the same time the bulk silicon is exposed to TMAH. A part of the bulk silicon underneath the TEM observation window is removed creating a suspended membrane with integrated thin-walled fluidic nanochannels. The bulk underneath the cantilevers is also removed and the cantilevers are released. During the TMAH etching the backside of the wafer remains unprotected. Due to the removal of silicon the cryoChip is further thinned down to its final thickness of 100  $\mu\text{m}$ .

**Filling volume.** The filling volume entering the chip through the cantilever was estimated from the chip geometry. The supply microchannel is about 1 mm long, 0.4  $\mu\text{m}$  high and 4  $\mu\text{m}$  wide, which results in an estimated volume of ~2 pL. The five nanochannels for imaging are 50  $\mu\text{m}$  long, ~750 nm wide and 100 nm high, which (assuming a parabolic profile) yields an aggregate volume of 6.25 fL, negligible compared to the microchannel volume. Assuming the liquid fills the entire entry microchannel and exit microchannel, the total filling volume is ~4 pL.

**SEM Imaging and FIB.** SEM imaging of cryoChips was performed on a Helios G4 CX DualBeam FIB/SEM system (ThermoFisher Scientific) at 35000x magnification using the TLD detector. A gallium beam was used to mill a rectangular opening in the observation membrane to image the cross-section of the nanochannel. Grayscale SEM images were coloured in Adobe Photoshop according to the schematic representations in Figure 1.

**Thickness measurements of silicon nitride.** For thickness determination of the ultrathin silicon nitride layer surrounding the nanochannels, we deposited a silicon-rich nitride layer on a dummy wafer using the same deposition parameters as used for cryoChip fabrication. The dummy wafer was annealed at 1100 °C. Next, the wafer was etched for 1 min in HF 1% solution ('etch 1'). In our fabrication process, the HF 1% dip is used to remove a native oxide layer from silicon prior to the TMAH etchings. Then the dummy wafer was etched in TMAH 25% solution at 90 °C ('etch 2'). The same etching time is used in our fabrication process to release the samples. The thickness of the  $\text{SiN}_x$  layer after deposition and both etching steps was measured on 25 positions of the wafer by ellipsometry.

For thickness determination by energy-filtered TEM (EFTEM), we acquired images of a filled nanochannel at 8000x magnification (4.706 Å/pixel) on a JEOL JEM3200-FSC operated at 300 kV (K2 detector) with and without a 20 eV slit (centered at 0 eV) inserted below the omega filter. Images were recorded on a Gatan K2 direct electron detector. The resulting images were aligned and  $I/I_0$  was computed by dividing the pixel values of the zero-loss image by those of the unfiltered image. The known total SiN thickness of 19 nm from ellipsometry measurements was used to calibrate the mean free path for inelastic scattering of silicon-rich nitride to 163 nm at 300 kV. We assumed a literature value of 320 nm (28) for the mean free path of vitreous ice. The derived quantity 'water-equivalent thickness' (*WET*) is the thickness of water/vitreous ice that would lead to the same  $I/I_0$ , and is computed as follows:

$$WET = 320 \text{ nm} \cdot \ln \frac{I_0}{I} \quad (1)$$

The quantity 'ice thickness' (*IT*) is computed by removing the contribution of the silicon nitride from *WET*:

$$IT = WET - [163 \text{ nm} \cdot \ln \frac{1}{0.89}] \quad (2)$$

*WET* cross-sections of nanochannels of whole chips were computed from grid-maps of three chips at 2500x (72.64 Å/pixel) on a TVIPS XF416 detector with and without a 20 eV slit inserted. Observation windows in unfiltered and zero-loss images were aligned by cross-correlation, and profiles across each nanochannel computed as averages over five stripes per observation window. Additionally, the average over all profiles was computed for each chip.

### Protein expression and purification.

**ApoFtn:** *Pyrococcus furiosus* apoferritin (Uniprot Q8U2T8, in pET-24d(+)) was expressed in E.coli BL21-DE3 cells using autoinduction (53). Cells were initially grown at 37°C for 4 hours after which temperature was reduced to 20°C. After 20h, cells were harvested, resuspended in lysis buffer (50 mM Tris, 300 mM NaCl, 0.1% Triton X-100) and disrupted by sonication. The lysate was cleared by centrifugation at 17,000 g at 4°C for 45 minutes. The cleared supernatant was boiled for 20 minutes at 80°C and centrifuged for 45 minutes at 17,000 g at 4°C. The supernatant was dialysed into ion exchange buffer (20 mM NaCl, 20 mM HEPES, pH=6.8) overnight and loaded onto a 1 mL HiTrap Q XL column (Cytiva). Following a wash step with 25 column volumes (cv) ion exchange buffer, bound protein was eluted with a 20-500 mM NaCl gradient over 50 cv. Fractions containing target protein in high purity were selected by SDS-PAGE and pooled. Pooled fractions were concentrated and finally purified by size exclusion chromatography on a Superdex200 10/300 column (Cytiva) in 20 mM Tris, 50 mM NaCl, pH 7.5. Fractions of the elution peak were pooled and concentrated to a final concentration of 3.4 mg/mL.

**TMV:** TMV was purified from infected tobacco leaves as described (54) and concentrated to 35 mg/mL.

**T20S:** *Thermoplasma acidophilum* 20S proteasome (pRSF-T20S, Addgene plasmid 110805) was expressed and purified essentially as described previously (55). In brief, protein was expressed in E.coli BL21-DE3 cells using autoinduction medium following the same expression protocol as for ApoFtn. After 20 hours, cells were harvested and lysed by sonication in lysis buffer (50 mM NaH<sub>2</sub>PO<sub>4</sub>, 150 mM NaCl, pH 8.0), followed by addition of three volumes of boiling lysis buffer to precipitate non-thermostable proteins. The supernatant was further purified by immobilised metal affinity chromatography (IMAC) followed by cleavage of the His-tag by TEV protease at room temperature for 48 hours. Final polishing was done by size exclusion chromatography on a Superose 6 column (Cytiva) with SEC buffer (20 mM Tris, 50 mM NaCl, 0.1 mM EDTA, pH 8.0). Fractions of the elution peak were pooled and concentrated to 1.4 mg/mL.

**cryoChip filling and vitrification.** A microvolume filling station for cryoChips was built on an optical breadboard (Thorlabs, USA). A 10 µL positive displacement micro-volume glass syringe (Hamilton) was mounted on a xyz translation stage for precise position control of a sample droplet relative to the sample application cantilever of a cryoChip. Two Toolcraft USB-microscopes (Conrad Electronics GmbH, Germany) were used for a top and side view of the filling process with video acquisition control on a computer. The transparent front cap was removed from the microscopes to increase the working distance. Both microscopes were mounted on an xy translation stage to orient the field of view. All experiments were done under ambient conditions without temperature or humidity control. A cryoChip was gripped on its edge with tweezers and positioned on a metal bearing for rapid and reproducible positioning in the field of view. Approximately 0.2 µL of sample was aspirated with the microvolume syringe. The syringe tip was dried with a tissue to avoid wetting of the tip during droplet extrusion. The syringe was mounted on the loading station and a small droplet of ~10-40 nL was extruded from the syringe. Using the xyz stage, the droplet was brought into contact with the cantilever tip. Within seconds, the liquid fills the entry microchannel, the nanochannels and parts of the exit microchannel. The liquid in the syringe was typically sufficient to fill many chips by drying the tip again with a tissue and extruding a new droplet. Approximately 2-3 sec after immersing the cantilever tip into the sample droplet, the tweezer with the chip was removed from the loading station and transferred on a Leica EM GP2 vitrification robot set to 20°C. The plunger was set to blot for zero seconds and the chip was plunged immediately into liquid ethane kept at -180°C. The time between removing the tweezer and chip from the filling station and plunge freezing was ~10 seconds.

**Electron cryo-tomography.** A cryoChip with ApoFtn at 3.4 mg/mL concentration was prepared as described above and stored in liquid nitrogen until imaging. Tilt series of cryoChips were acquired on a JEOL JEM3200-FSC with

a bidirectional tilt scheme starting from 0° to -60° and subsequently from 2° to 60°, in increments of 2° with a total exposure of 94.6 e<sup>-</sup>/Å<sup>2</sup>, a pixel size of 4.706 Å and a defocus target of 6 µm. Micrographs acquired as dose-fractionated movies of 30 frames were motion-corrected in MotionCor2 v1.0 (56) and dose-weighted according to their accumulated dose (57). The tilt series was aligned using patch tracking and reconstructed using back-projection as implemented in Etomo from the IMOD package (58). Segmentation of silicon nitride membrane and particles was done in the tomoseg program of EMAN2 using a machine learning approach (59). Segmented tomograms were visualised in ChimeraX (60). A subvolume of the segmented ApoFtn tomogram with 376 x 750 x 100 nm<sup>3</sup> channel volume was segmented in ChimeraX to count individual ApoFtn particles for concentration determination using the 'segment map' command. Tomogram acquisition and reconstruction for cryoChips with TMV and T20S were done using the same protocol, using a pixel size of 4.706 Å for TMV and 3.668 Å for T20S.

**Single-particle imaging of ApoFtn.** Three cryoChips with ApoFtn at 3.4 mg/mL were sent to EMBL Heidelberg for data acquisition. A grid map of the whole observation membrane was acquired for each chip. Acquisition points were set up to automatically acquire three images in a circle by beam-image shift in SerialEM (61) using the 'multiple Record Setup' setting. Six acquisition points were placed in the nanochannel section of each observation window, which leads to 18 images per nanochannel section. Using py-EM (33), reference maps were generated from the grid map to find back and align to the acquisition points with high precision. Coma-free alignment was performed on the collapsed silicon nitride membrane adjacent to the nanochannels. Movies of 90 frames were acquired during a 9 second exposure on a Krios (ThermoFisher Scientific) microscope with a Quantum-K2 detector. The total exposure of the image was 63 e<sup>-</sup>/Å<sup>2</sup>, the pixel size 0.8127 Å/pix and the dose rate ~2 e<sup>-</sup>/pixel/sec. The defocus range was set to -1 to -2 µm. In total 945 movies were acquired from three cryoChips.

**Single-particle imaging of T20S and TMV.** Datasets comprising 121 movies of the T20S proteasome at 1.4 mg/mL and 82 movies of TMV at 1.1 mg/mL were acquired on a JEOL JEM 3200-FSC microscope operated at 300 kV. For T20S, we used cryoChips with a slightly different design featuring orthogonal nanochannels arranged in a clover-like pattern instead of straight nanochannels (Fig. S10c). Both TMV and T20S single-particle datasets were acquired on a Quantum-K2 detector at a magnification of 30,000x (1.288 Å/pixel) and an exposure time of 10.95 seconds with a total exposure of 59.68 e<sup>-</sup>/Å<sup>2</sup> over 73 frames.

**Single-particle image processing.** 945 movies from three cryoChips filled with ApoFtn were processed in cryoSPARC 3.1 (34) [Fig. S6]. Patch-motion correction and

patched CTF estimation was followed by manual curation of micrographs to remove images with visible ice reflections in the power spectra, retaining 815 micrographs. Particles were picked with the blob-picker and subjected to 2D classification to obtain a picking reference. The reference was low-pass filtered to 20 Å and was used to pick 318,058 ApoFtn particles. After 2D classification, selection and local-motion correction in cryoSPARC, 97,431 particles were retained. Three more rounds of 2D classification were used to select for classes with visible secondary structure features, resulting in 34,102 particles. Retained particles were used for initial model generation by cryoSPARC's stochastic gradient descent method while imposing O symmetry. The resulting reference volume was low-pass filtered to 15 Å and used in homogeneous refinement, leading to a 3D reconstruction at 3.7 Å resolution. Per-particle defocus refinement and beam-tilt refinement improved the resolution to 3.0 Å. Heterogeneous refinement with 3 classes was used to further prune particles and lead to a 3.0 Å resolution reconstruction from 21,238 particles. In all cases, O symmetry was imposed during reconstruction.

82 movies from two cryoChips filled with TMV were imported in cryoSPARC 3.1 (34), followed by patch-motion correction and patched CTF estimation [Fig. S7]. 43 of 82 movies with vitreous ice were retained for further processing. Manual picking and 2D classification was used to obtain picking references. Filament tracing was used to trace and segment virus particles with a step size of 20 asymmetric units (1.41 Å each), resulting in 31,623 segments. Two rounds of 2D classification were used to prune segments. Local motion correction and re-extraction yielded 14,238 TMV segments. Helical refinement was started from a cylindrical initial model and an initial symmetry of 22.04° twist and 1.41 Å rise, while refining the symmetry. This yielded a 3D reconstruction at 4.3 Å reconstruction. Two rounds of per-particle defocus and global CTF (tilt trefoil) refinement improved the reconstruction to 3.7 Å. The final refined symmetry converged to 22.036° twist and 1.415 Å helical rise.

121 movies of T20S proteasome were processed in cryoSPARC 3.1 (34) [Fig. S7]. Patch-motion correction and patched CTF estimation were performed, followed by manual curation of micrographs to remove movies with visible reflections from crystalline ice in their power spectra. 91 movies were retained for further processing. Blob-picking and 2D classification was used to generate references for automated picking. Five reference classes were low-pass filtered to 20 Å for template picking, resulting in 47,484 particles. After two rounds of 2D classification and selection, 12,351 particles were retained and used for ab-initio 3D reconstruction imposing D7 symmetry. The initial model thus obtained was low-pass filtered to 30 Å and used for homogeneous refinement, yielding a reconstruction at 7.9 Å resolution. After heterogeneous refinement with three classes, particles in the class with highest resolution (5,750 particles) were selected and subjected to



another round of homogenous refinement yielding the final reconstruction at 6.0 Å resolution. Per-particle defocus and global CTF refinement (tilt trefoil) further improved the resolution to 5.4 Å. All reconstructions had D7 symmetry imposed.

For all final reconstructions, five independent runs of ResLog (62) analysis were performed and the results averaged for ResLog curves. Local resolution was estimated in cryoSPARC using a windowed FSC method (63) and visualised in ChimeraX (60). Map sharpening was done in cryoSPARC by applying the overall B-factor estimated from Guinier plots.

**Atomic model building.** Atomic models for TMV (PDB ID 4udv) and T20S (PDB ID 3j9i) were rigid body-fitted into the density maps and not further refined. The atomic model from an available crystal structure of ApoFtn (PDB ID 2x17) (30) was rigid body-fitted into the cryo-EM density, and real-space refinement in Phenix 1.13 (64) was iterated with manual model building in Coot 0.8.9.2 (65). Model validation statistics were retrieved from MOLPROBITY (66) as implemented in Phenix and overfitting was probed by half-map refinement.

**Beam-induced motion trajectory analysis.** Four datasets (10200 (44), 10272 (39), 10306 (67), 10389 (68)) from the Electron Microscopy Public Image Archive (EMPIAR (36)) were subjected to full-frame motion correction in cryoSPARC (34) to calculate motion trajectories and were compared with equivalently derived trajectories from the cryoChip ApoFtn dataset.

**Kymograph generation.** Movies of the filling process for each cryoChip were acquired with a Toolcraft USB-microscope (Conrad Electronics GmbH, Germany) at ten frames per second and a pixel size of 1.6 µm. A ten pixel-wide section along the supply or exit microchannels was averaged and plotted over time. For each time point coordinates of the liquid front were manually picked and individually plotted for each chip. A square root function of the form

$$x(t) = \sqrt{a(t-b)} + c \quad (3)$$

was fitted to each filling trajectory using the `curve_fit` function from the `scipy` package (69). For error estimation of the fitting parameters, a bootstrapping approach was used, performing the fit 100 times with a random set of  $n$  out of  $n$  coordinates with replacement. The parameter and its uncertainty was estimated as mean and standard deviation over the 100 fits. For the linearised plots of  $x^2$  versus  $t$ , the shift parameter  $c$  was subtracted from the curve.

**Convective heat transfer simulations.** Simulations were performed in COMSOL Multiphysics 5.4 using a simplified 2D geometry of cryoChips represented by a 2 mm x 100 µm silicon base and 50 µm x 20 nm SiN observation membrane. The initial temperature of the chip was set to room

temperature (293.15 K) and the ethane bath was at 90 K. Heat flux was modelled by a external forced convection model with 1.5 m/s fluid velocity and a plate length of 2 mm. This does not take into account geometry of the plunging process or fluid dynamics and uses an average heat flux for every surface of the chip. Temperature development over time was evaluated over a profile along the observation membrane and plotted in different time windows. Material properties were obtained from the COMSOL material library unless stated otherwise. The specific heat capacity  $c_p$  for silicon nitride was assumed as 700 J/(kg K) and its density as 3100 kg/m<sup>3</sup>. For thermal conductivity of SiN, we averaged values from (70) for thin membranes over the relevant temperature range to obtain 2.3 W/(m K). For silicon, heat capacity was assumed as 700 J/(kg K), thermal conductivity as 130 W/(m K) and density as 2329 kg/m<sup>3</sup>.

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