

1 A geometric basis for surface habitat complexity and biodiversity

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19

20 **Abstract**

21 Structurally complex habitats tend to contain more species and higher total abundances than
22 simple habitats. This ecological paradigm is grounded in first principles: species richness scales
23 with area, and surface area and niche density increase with three-dimensional complexity. Here
24 we present a geometric basis for surface habitats that unifies ecosystems and spatial scales.
25 The theory is framed by fundamental geometric constraints among three structure
26 descriptors—surface height, rugosity and fractal dimension—and explains 98% of surface
27 variation in a structurally complex test system: coral reefs. We then show how coral
28 biodiversity metrics (species richness, total abundance and probability of interspecific
29 encounter) vary over the theoretical structure descriptor plane, demonstrating the value of the
30 theory for predicting the consequences of natural and human modifications of surface
31 structure.

32

33 **Main text**

34 Most habitats on the planet are surface habitats—from the abyssal trenches to the tops of
35 mountains, from coral reefs to the tundra. These habitats exhibit a broad range of structural
36 complexities, from relatively simple, planar surfaces to highly complex three-dimensional
37 structures. Currently, human and natural disturbances are changing the complexity of habitats
38 faster than at any time in history¹⁻⁴. Therefore, understanding and predicting the effects of
39 habitat complexity changes on biodiversity is of paramount importance⁵. However, empirical
40 relationships between commonly-used descriptors of structural complexity and biodiversity are

41 variable, often weak or contrary to expectation⁶⁻¹⁰. Moreover, there are no standards for
42 quantifying structural complexity, precluding general patterns in the relationship between
43 structure and diversity from being identified in different habitats. We therefore propose a new
44 geometric basis for surface habitats that integrates and standardises existing surface
45 descriptors^{8,10}.

46

47 In theory, species richness scales with surface area according to a power law¹¹. Island
48 biogeography theory articulates that this relationship arises out of extinction and colonization,
49 as larger areas provide larger targets for species to colonize and a greater variety of habitats
50 allowing species to coexist¹². Our geometric theory builds on these ideas by exploring the
51 notion that habitat surfaces with the same rugosity (defined here as surface area per planar
52 area) can exhibit a range of different forms (Fig. 1). Total surface area is the integration of
53 component areas at the smallest scale (i.e., resolution), but it does not explain how these
54 component areas fold and fill the three-dimensional spaces they occupy. Rather, fractal
55 dimension quantifies space-filling at different scales¹³. Space-filling promotes species co-
56 existence by dividing surface area into a greater variety of structural elements¹⁴, microhabitats
57 and niches¹⁵ (e.g., high and low irradiance; small and large spaces; fast and slow flow). This
58 variety of niches allows species to coexist (e.g. different competitors, or predator and prey¹⁶)
59 and therefore enhances biodiversity^{17,18}. We posit that there is a fundamental geometric
60 constraint between surface rugosity and fractal dimension: for a given surface rugosity, an
61 increase in fractal dimension will result in a reduction of the surface's mean height (Fig. 1). As
62 the basis for a geometric theory, we mathematically derived the trade-off between surface

63 rugosity (R), fractal dimension (D) and surface height range (ΔH) as (see Methods for
64 derivation):

65

$$66 \frac{1}{2} \log(R^2 - 1) + \log\left(\frac{L}{L_0}\right)(3 - D) = \log\left(\frac{\Delta H}{\sqrt{2}L_0}\right) \quad \text{Eq. 1}$$

67

68 Where L is the surface linear extent and L_0 is the resolution (i.e., the smallest scale of
69 observation). R and D are both dimensionless, with $R \geq 1$ and $2 \leq D \leq 3$; ΔH is dimensionless
70 when standardised by resolution L_0 , with $\frac{\Delta H}{\sqrt{2}L_0} \geq 0$. When rugosity is expressed as R^2-1 (with R^2-1
71 ≥ 0) and height range as $\frac{\Delta H}{\sqrt{2}L_0}$, Eq. 1 is a plane equation. Moreover, it is clear that any one of the
72 surface descriptors can easily be expressed in terms of the other two, highlighting that any of
73 the three variables is required, but not sufficient alone, to describe the structural complexity of
74 a surface habitat.

75

76 **Results**

77 To test the theory, we examined associations among surface rugosity, fractal dimension and
78 height range across coral reef habitat patches. Coral reefs are ideal ecosystems for testing a
79 theory of surface habitats, because they are structurally complex surface habitats constructed
80 in large part by the reef-building scleractinian corals that, in turn, live upon the habitat (i.e.,
81 corals are autogenic ecosystem engineers¹⁹). Structural complexity affects biodiversity in
82 general²⁰ and of coral reefs in particular²¹. Using Structure from Motion (SfM), we estimated
83 surface rugosity (expressed as the \log of R^2-1), fractal dimension (D) and height range (as the

84 $\log \frac{\Delta H}{\sqrt{2} L_0}$) from digital elevation models (DEMs) for 591 reef patches of 4 m² at 21 reef sites

85 encircling Lizard Island on the Great Barrier Reef, Australia (see Methods). Analyses of the

86 structure of these patches reveal that while rugosity, fractal dimension and surface height

87 range are not independent, they have substantial independent variation (r^2 for pairwise

88 relationships between surface descriptors ranging between 3% and 30%, Fig. 2a-c). However,

89 when framed together, the three descriptors formed a plane, whereupon the trivially measured

90 surface descriptors, rugosity and height range, captured 98% of the variation in D (Fig. 2d). The

91 remaining 2% of the variation occurs because real surfaces do not necessarily behave like

92 fractals (i.e., are self-similar) across a wide range of scales (Extended Data Fig. 5). The

93 observation that the structure of nearly all measured reef patches fell upon a plane delineated

94 by three simple surface descriptors highlights the fundamental geometric constraints of surface

95 habitats. If fractal dimension increases, then either rugosity increases, or height range

96 decreases, or both. All three descriptors are essential for capturing structural complexity

97 because they explain different elements of surface geometry: height range captures patch scale

98 variation, rugosity captures fine scale variation (which sums to surface area), and fractal

99 dimension captures degree of space filling when transitioning from broad to fine scales

100 (Extended Data Fig. 1a).

101

102 Different reef locations, with different ecological and environmental histories, occupied

103 different regions on the surface descriptor plane (Fig. 3). For example, one site that was

104 stripped of living coral during back-to-back tropical cyclones²² largely occupied the region of the

105 plane where rugosity, fractal dimension and surface height range are all low (Fig. 3a); that is,

106 the patches at this site were closest to a theoretical flat surface. Another site also impacted by
107 the cyclones but left littered with dead coral branches, had similar levels of rugosity and height
108 range, but fractal dimension was relatively high (Fig. 3b). In contrast, a site containing several
109 large colonies of living branching coral had patches with the highest fractal dimension and
110 rugosity, yet the height range of these patches was low (Fig. 3c) reflecting the approximately
111 uniform height of living branching corals in shallow waters where water depth and tidal range
112 constrains colony growth. Meanwhile, a site containing large hemispherical *Porites* corals had
113 patches with large height ranges and high rugosity but lower fractal dimension (Fig. 3d). Three
114 sites contained patches with similar distributions of rugosities (Fig. 3b,d,f), and therefore similar
115 surface areas. However, these sites ranged from smooth reef surfaces with large holes (Fig. 3e)
116 to highly bumpy surfaces with no holes (Fig. 3b), demonstrating why rugosity alone does not
117 capture structural complexity and how varying mixtures of structural components dictate
118 habitat complexity¹⁴.

119
120 Finally, to connect the geometric variables to biodiversity, we examined how species richness,
121 total abundance and diversity (measured as the probability of interspecific encounter²³) varied
122 across the surface descriptor plane. Strong ecological feedbacks occur between coral reef
123 habitat structure and coral biodiversity metrics. Coral reef structures are largely created by
124 corals, but their structure is mechanistically affected by environmental conditions such as tidal
125 range, currents, storm impacts and wave exposure. For instance, coral larvae are poor
126 swimmers and are more likely to settle in reef patches with small-scale complexity, because
127 they get entrapped by micro-eddies²⁴. At the same time, more intricate coral structures (with

128 higher fractal dimension, D) are more likely to be damaged or dislodged during storms that
129 flatten reef patches^{25,26}. Species-area theory predicts that species richness and abundances
130 should be highest in patches with the greatest surface area¹¹ (i.e., highest rugosity). We
131 predicted that higher fractal dimension would also enhance species richness and abundance,
132 because of niche diversity (i.e., increases in surface area at different scales), and that this effect
133 would be additional to overall surface area. The surface descriptor plane allows estimating the
134 combined effects of not just area, but also niche differentiation associated with fractal
135 dimension and height range^{10,15}.

136
137 We examined geometric-biodiversity coupling for a large plot, containing 261 of the 4 m² reef
138 patches, in which 9,264 coral colonies of 171 species were recorded (see Methods). Contrary to
139 expectation, we found that all biodiversity metrics considered peaked in reef patches with
140 intermediate surface rugosities (Fig. 4a shows diversity, and Extended Data Table 2 includes
141 species richness and abundance). Indeed, several recent studies have argued that the
142 relationship should be unimodal because, as complexity increases, the amount of area available
143 for individuals to live declines^{27,28}. However, biodiversity metrics also tended to increase
144 monotonically in association with patches with higher fractal dimension and smaller height
145 range (Extended Data Fig. 7). The explanatory power of reef geometry on biodiversity metrics
146 was over 50% (Extended Data Table 1)—5 to 45% higher than any surface descriptor alone.
147 Explaining this much variation in biodiversity is striking, given the number of other, non-
148 geometric processes that govern coral biodiversity, including environmental filtering, dispersal
149 and species interactions²⁹. Because corals are autogenic ecosystem engineers, reciprocal

150 causality is likely to strengthen and shape geometric-biodiversity coupling. For instance, high
151 rugosity is often generated by large hemispherical corals (e.g., Fig. 3d) that reduce the number
152 of individuals, and hence species, per area¹⁴. Subsequently, geometric-biodiversity coupling
153 may be weaker for other surface-associated taxa, such as fishes and invertebrates, and should
154 be tested. Nonetheless, our findings have implications for resilience following disturbances and
155 for restoration efforts that aim to maximise biodiversity³⁰, specifically identifying the reef
156 structural characteristics that should be maintained (or built) to maximize biodiversity.

157

158 **Discussion**

159 A general, scale-independent geometric basis for surface habitats provides a much-needed way
160 to quantify habitat complexity across ecosystems and spatial scales. Meanwhile, creating three-
161 dimensional habitat surfaces is becoming increasingly accessible and cost effective, for example
162 using Structure from Motion^{31,32}, both underwater and on land. The importance of surface
163 complexity as a determinant of habitat condition, biodiversity, and ecosystem function is well
164 recognised³³, yet different metrics are typically used for different ecosystems, or different taxa
165 within the same ecosystem¹⁰. The general quantitative approach we propose is applicable
166 across surface habitats in both marine and terrestrial environments, allowing formal
167 comparisons examining whether geometric-biodiversity couplings differ among systems in
168 terms of both pattern and strength. The surface descriptor plane uncovered here clearly
169 defines the fundamental geometric constraints acting to shape surface habitats, and
170 consequently, how changes in surface geometry affect biodiversity. Nonetheless, there remain
171 several unknowns about the surface descriptor plane and its associations with biodiversity

172 metrics that require further exploration. These unknowns range from technical limitations (e.g.,
173 how does the theory translate from digital elevation models that exclude overhanging surfaces
174 to 3D surface meshes?) to ecological patterns (e.g., how do different types of structural
175 components, such as different mixtures of branching and hemispherical corals or live and dead
176 elements^{14,34}, mediate geometric-biodiversity coupling?).

177

178 As powerful ecosystem engineers, humans are modifying the planet through the structures we
179 destroy, both physically and indirectly via environmental change⁴, and those we construct.
180 Indeed, human-modified structures differ significantly in their geometry from nature-built
181 structures³⁵. Determining how biodiversity, conservation status and recovery rates relate to
182 habitat complexity measures is paramount in the Anthropocene. The approach we propose
183 here allows for predictions of the biodiversity consequences of these structural changes across
184 land and seascapes.

185

186 **Methods**

187 **Geometric theory for surface habitats.** The variation method for calculating fractal dimension
188 D measures the mean height range of a surface at different scales^{36,37}. At the broadest scale,
189 the linear extent L , the surface height range is ΔH (Extended Data Fig. 1a). At the finest scale,
190 the resolution L_0 , the height range (ΔH_0) is the mean of height ranges of all the component
191 areas at that scale. The slope S of the resulting log-log relationship (shown in Extended Data Fig.
192 1a) is:

193
$$S = \frac{\log(\Delta H) - \log(\Delta H_0)}{\log(L) - \log(L_0)}$$
 Eq. 2

194 Where fractal dimension is³⁷:

195
$$D = 3 - S$$
 Eq. 3

196 Rearranging Eq. 2 gives:

197
$$S = \frac{\log(\Delta H/\Delta H_0)}{\log(L/L_0)}$$
 Eq. 4

198 Surface area A can be estimated by summing areas A_0 at the finest grain L_0 . Given the mean
199 height range ΔH_0 at L_0 , we assume any finer scale detail is not observable, and we calculate A_0
200 from the minimal surface consistent with ΔH_0 (Extended Data Fig. 1b) as:

201
$$A_0 = \frac{L_0}{2} \sqrt{2\Delta H_0^2 + 4L_0^2}$$
 Eq. 5

202 And then multiply by the number of component areas ($\frac{L^2}{L_0^2}$) giving:

203
$$A = \frac{L^2}{2L_0} \sqrt{2\Delta H_0^2 + 4L_0^2}$$
 Eq. 6

204 Surface rugosity is³²:

205
$$R = \frac{A}{L^2}$$
 Eq. 7

206 Substituting A for Eq. 6 and rearranging gives:

207
$$R = \sqrt{\frac{\Delta H_0^2}{2L_0^2} + 1}$$
 Eq. 8

208 Rearranging for ΔH_0 gives:

209
$$\Delta H_0 = \sqrt{2}L_0\sqrt{R^2 - 1}$$
 Eq. 9

210 And substituting into Eq. 4 gives:

211
$$S = \frac{\log\left(\frac{\Delta H}{\sqrt{2}L_0\sqrt{R^2 - 1}}\right)}{\log\left(\frac{L}{L_0}\right)}$$
 Eq. 10

212 Leading to:

$$213 D = 3 - \frac{\log\left(\frac{\Delta H}{\sqrt{2}L_0\sqrt{R^2-1}}\right)}{\log\left(\frac{L}{L_0}\right)} \quad \text{Eq. 11}$$

214 Further rearranging gives a plane as Eq. 1 in the main text. The boundaries equations for the
215 limits of fractal dimension D are:

$$216 \Delta H_{D=2} = \sqrt{2}L\sqrt{R^2 - 1} \quad \text{Eq. 12}$$

$$217 \Delta H_{D=3} = \sqrt{2}L_0\sqrt{R^2 - 1} \quad \text{Eq. 13}$$

218

219 **Coral reef surface field study.** Twenty-one reef flat sites were selected approximately 1 km
220 apart and encircling Lizard Island on the Great Barrier Reef, Australia (Extended Data Fig. 2). The
221 spatial arrangement of the sites captured a broad range of habitats that were shaped
222 predominantly by wave exposure generated by prevailing southeast trade winds²². Mean water
223 depth across all study sites range between 2 to 3.5 meters. In 2014, at the Trimodal site, we
224 used an Iver2 Autonomous Underwater Vehicle³⁸ to collect 45,000 georeferenced overlapping,
225 stereo-pair images of an approximately 30 m by 50 m section of the reef crest (Fig. 4c). In 2016,
226 at all 21 sites, we used the spiral method³⁹, which involves swimming a camera rig that
227 unspools from a central point to capture approximately 3000 overlapping, stereo-pair images of
228 approximately 130 m² of reef crest (Extended Data Fig. 3). We used a simultaneous localisation
229 and mapping approach⁴⁰ fusing GPS, stereo imagery and altitude information to provide an
230 initial pose estimate for the cameras. We used Agisoft Metashape software to process the
231 images and produce a 3D dense cloud from which we derived a gridded digital elevation model
232 (DEM) and orthographic mosaic for coral annotation per site. The output resolution of all DEMs

233 was 0.002 m. We used DEMs in order to exclude overhanging surfaces (i.e., only one height for
234 each xy combination), because the degree to which overhangs are captured from plan view
235 photographic surveys is biased by the changing lighting conditions of the environment⁴¹ (e.g.,
236 the sun angle, cloud cover, water turbidity, etc.). On the other hand, plan view surveys were
237 preferred in order to reduce the time costs associated with capturing stereo pairs from multiple
238 view angles over large areas. The use of DEMs will underestimate surface rugosity and fractal
239 dimension; i.e., the reason why D tended to range below 2.6. However, given that overhanging
240 structures were rare at our study sites, R and D measures are likely to exhibit the correct rank
241 order for patches.

242
243 Given the lack of coral cover following the 2016 mass bleaching event on the GBR²², we used
244 the 2014 Trimodal large plot to quantify geometric-biodiversity relationships (Extended Data
245 Fig. 2). The plot was divided into a contiguous grid of 2 by 2 m reef patches (Fig. 4c, black
246 squares). Patches of the orthographic mosaic were printed on underwater paper and used as
247 reference maps for *in situ* identification of all coral colonies of diameter >5 cm to species by a
248 team of six researchers over four weeks. We focused on the reef crest and flat (shallow areas
249 in Fig. 4c) but also included reef edge and deeper reef. Colonies of unknown or hard to identify
250 species were photographed and identified in consultation with guide books and other
251 observers. Hemispherical *Porites* colonies were identified to genus due to the difficulty
252 differentiating among the few known species without collecting samples for microscopy. Colony
253 annotations were digitized over the orthographic mosaic using QGIS software (e.g., Fig. 4c,
254 white points). Only scleractinian corals were included for analyses. In total, 9,264 coral colonies

255 of 171 species were observed within the 255 reef patches censused. Diversity was calculated as
256 the probability of interspecific encounter (PIE), or $1 - \text{Simpson diversity}^{23}$.

257

258 Each of the circular DEMs had a central point, from which an 8 by 8 m square was centred
259 (Extended Data Fig. 3) and divided into 16 contiguous reef patches of 2 by 2 m. DEMs for each 2
260 by 2 m patch from both the Trimodal large plot (where corals were censused) and the 21
261 circular plots were cropped to calculate surface rugosity R , fractal dimension D and the height
262 range of the patch ΔH ; the latter being the difference between the deepest and shallowest
263 point in a patch. D was calculated using the variation method³⁷, where each patch was divided
264 into squares with sides lengths (L) of 2, 1, 0.5, 0.25, 0.125, 0.0625 and 0.03125 m capturing
265 approximately two orders of magnitude⁴². The resolution L_0 for the theory is the smallest scale
266 (i.e., 0.03125 m). The height range within each grid at each scale were calculated, and then
267 averaged for that scale to avoid weighting the many estimates at smaller scales more than the
268 fewer estimates at larger scales when calculating the slope S . S was calculated for each patch by
269 fitting a linear model to the log of scale (i.e., grid sizes) versus the log of mean height. D was
270 then calculated according to Eq. 3. R was calculated according to Eq. 8. There are many ways to
271 estimate the surface area of a DEM, so we compared surface rugosity calculated from theory
272 (Eq. 8) with estimates based on surface area calculations using the *surfaceArea* function in the
273 package *sp*⁴³. The theory underestimated surface rugosity by approximately 5% (Extended Data
274 Fig. 4), because of the minimal area assumption (Extended Data Fig. 1b), but this disparity was
275 consistent across the range of rugosities.

276

277 **Analyses.** Surface rugosity (expressed as R^2 -1) and standardised height range (expressed as
278 $\frac{\Delta H}{\sqrt{2}L_0}$) were log-transformed (base 10) as per the plane equation (Eq. 1). Species richness and
279 abundance were sqrt-transformed, and diversity arcsin-transformed, for all analyses to improve
280 model residuals. Coefficients of determination (r square) of pairwise associations of the three
281 geometric variables were estimated by squaring Pearson correlation coefficients. Reef surfaces
282 were not perfectly fractal: mean height ranges at L and L_0 anchor the theory (Extended Data Fig.
283 1a), but mean height ranges at scales intermediate to L and L_0 could shift the overall
284 relationship, albeit subtlety. Therefore, we calculated the r square for the surface descriptor
285 plane based on the deviances of empirically derived D from theory derived D (Extended Data
286 Fig. 5) (i.e., by dividing the residual sums of squares by the total sums of squares, and then
287 subtracting this value from one).

288
289 We quantified geometric-biodiversity relationships for the large plot at the Trimodal site using
290 both generalised additive models (GAMs) and linear models (LMs). We applied the default
291 smoother term to each surface descriptor for the GAMs and second-order polynomials for the
292 LMs, to allow for non-linear relationships among predictor and response variables. We
293 quantified the effect of each geometric variable separately on species richness, total abundance
294 and diversity (PIE), and then all together to assess improvement in explained variation as
295 adjusted r square values (Extended Data Fig. 7; Extended Data Table 1). We included the three
296 reef patches with no living coral, but also confirmed that removing these points had no
297 discernible influence on the geometric-biodiversity relationships. We also ran analyses
298 following the removal of the 5-6 highest rugosity patches that appeared to be largely

299 responsible for producing the hump-shaped rugosity-biodiversity relationships (red curves,
300 Extended Data Fig. 7). Smooth terms for rugosity and height range were significant, with
301 reference degrees of freedom much greater than one for all biodiversity metrics, suggesting
302 significant non-linear effects for these surface descriptors⁴⁴. Fractal dimension showed a linear
303 effect for richness and diversity, and so the smoother term was removed for these analyses.
304 Residuals for all models were approximately normal and were homogeneous when plotted
305 against predictor variables. The linear models with second-order polynomial terms gave the
306 same overall results as GAMs (Extended Data Fig. 7). That is, the polynomial term was
307 significant for the same terms that retained the smoother function in the GAMs. However, the
308 LMs had lower adjusted r square values and so we presented the final results using GAMs (Fig.
309 4a; Extended Data Table 2).

310

311 All analyses, including model selection and diagnostics and figure creation, were conducted in
312 the statistical program language R⁴⁵ and can be downloaded or cloned at GitHub
313 (https://github.com/jmadin/surface_geometry).

314

315 **Data and code availability**

316 Source data and code for data preparation, statistical analyses and figures are available at
317 https://github.com/jmadin/surface_geometry.

318

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429

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440

441 **Author contributions**

442 The study was conceptualized by JSM, DTP, MD and OP. All authors collected the data. JSM and
443 OP developed the theory and JSM ran the analyses. JSM, DTP and OP developed the software
444 pipeline for data and produced the visualizations. The investigation was led by JSM, DTP, MD
445 and OP. JSM and MD led and funded the broader project, with additional field robotics

446 resources provided by OP and SW. JSM wrote the first draft of the paper and all authors
447 reviewed at least one draft.

448

449 **Competing interests**

450 Authors declare no competing interests.

451

452 **Figure captions**

453 **Fig. 1 | Increasing fractal dimension (i.e., space filling) while keeping surface rugosity**

454 **constant results in a decline in a surface's mean height range.** A two-dimensional
455 representation of three hypothetical surface habitats with the same surface rugosities (**a**, **b** and
456 **c**). That is, the lengths of the lines **a**, **b** and **c** are the same and occur over the same planar
457 extent (black points). However, line **a** fills less of its two-dimensional space (black rectangle)
458 than does line **c**, and therefore has a lower fractal dimension.

459

460 **Fig. 2 | Comparison of the geometric theory with field data. (a-c)** Pairwise relationships

461 between the descriptors that frame the geometric theory for $n=595$ reef patches: surface

462 rugosity (as R^2-1); fractal dimension D ; and surface height range (as $\frac{\Delta H}{\sqrt{2}L_0}$). Coefficients of

463 determination (r^2) show the variance explained in the y-axis variable by the x-axis variable. (**d**)

464 When combined the three descriptors explain more than 98% of the variation in fractal

465 dimension D despite reef surfaces not being perfectly fractal (see Methods). Field data are

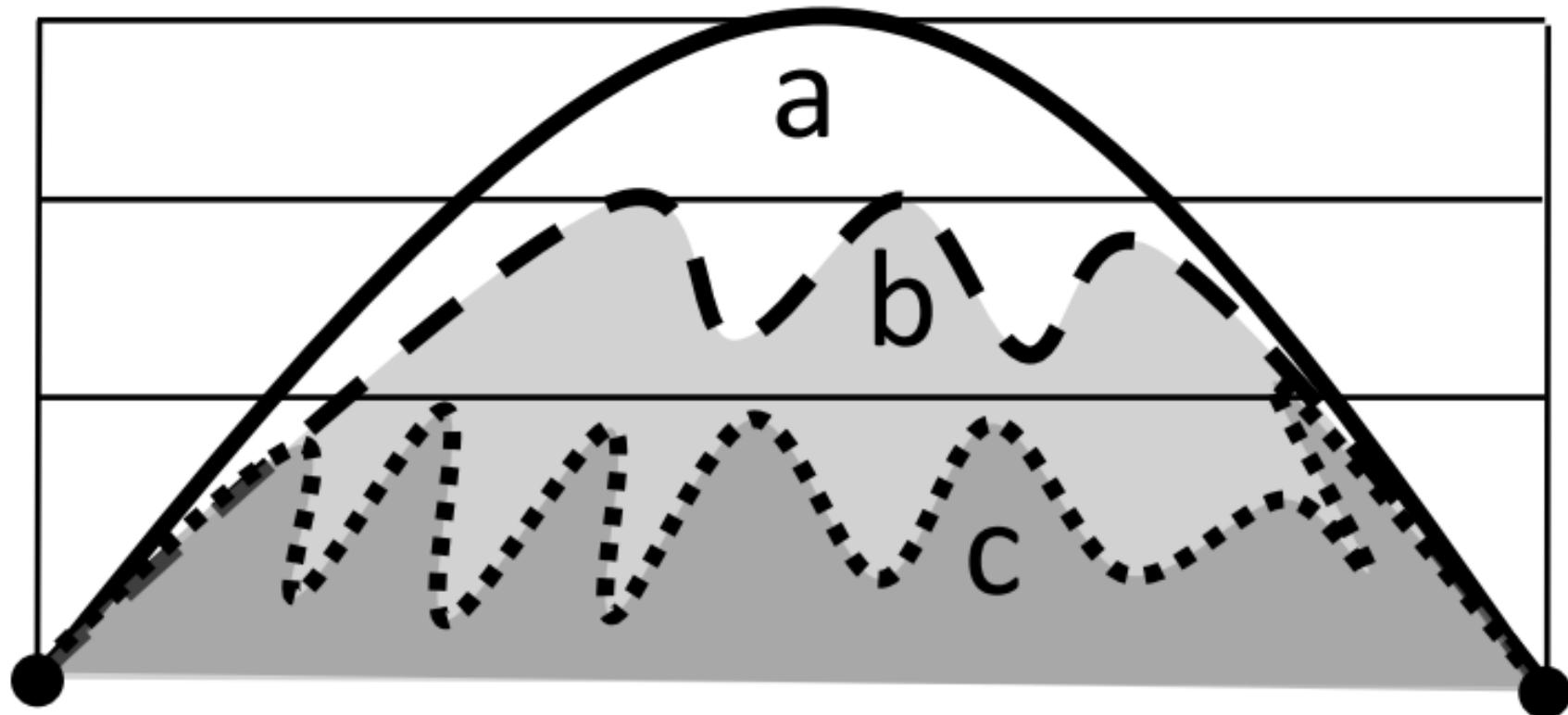
466 points, and the surface descriptor plane is coloured by fractal dimension.

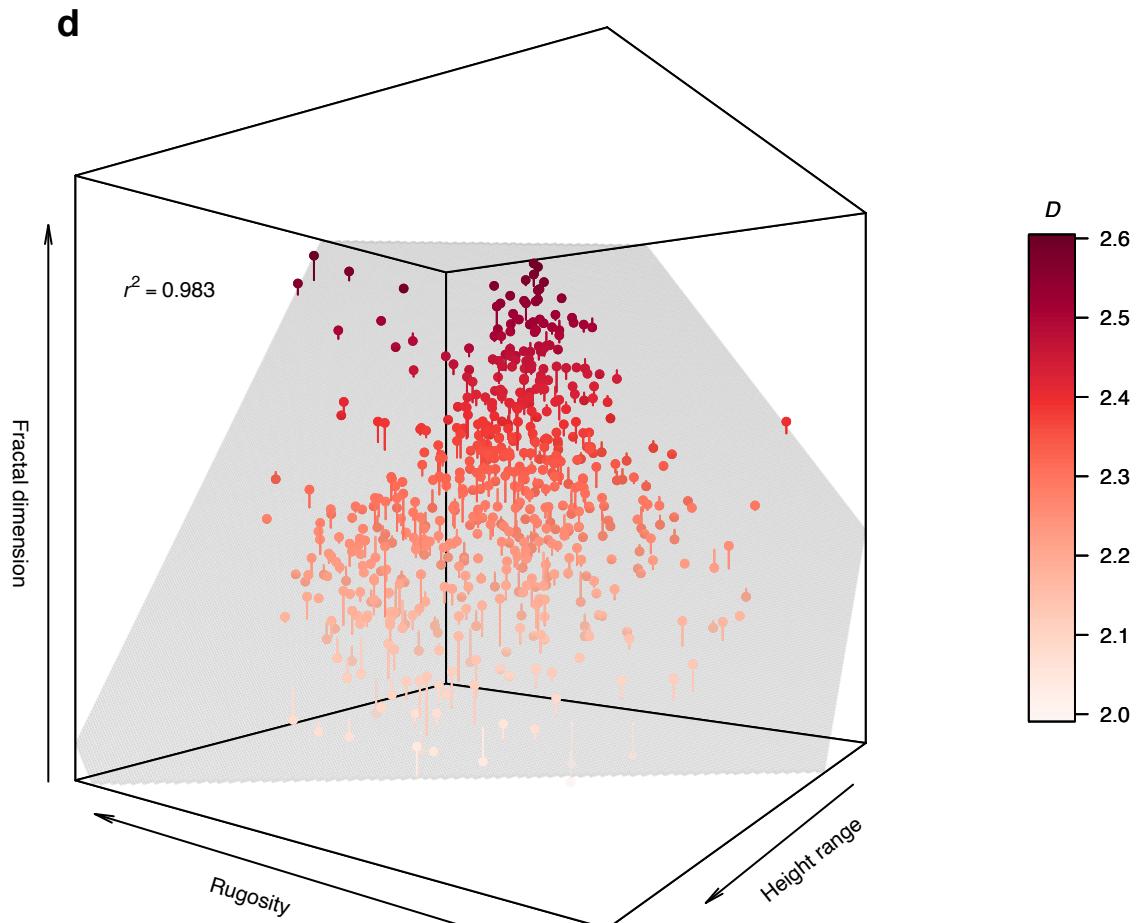
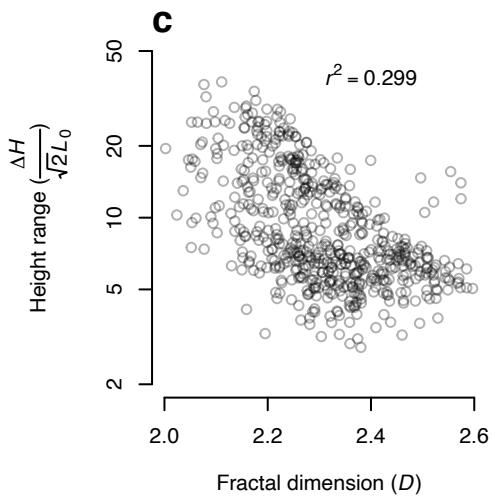
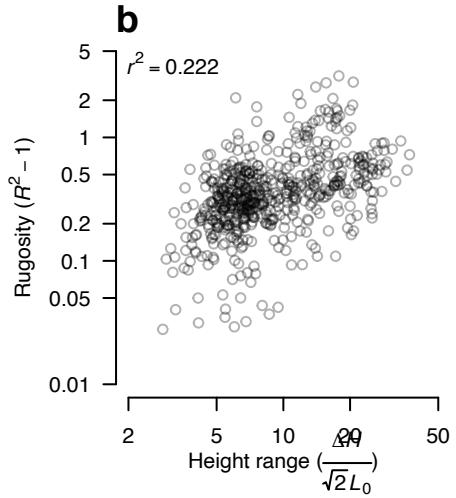
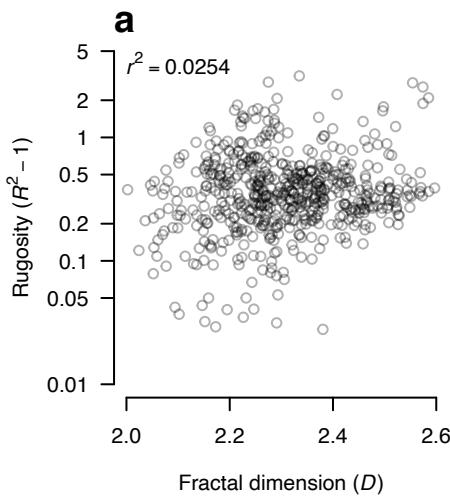
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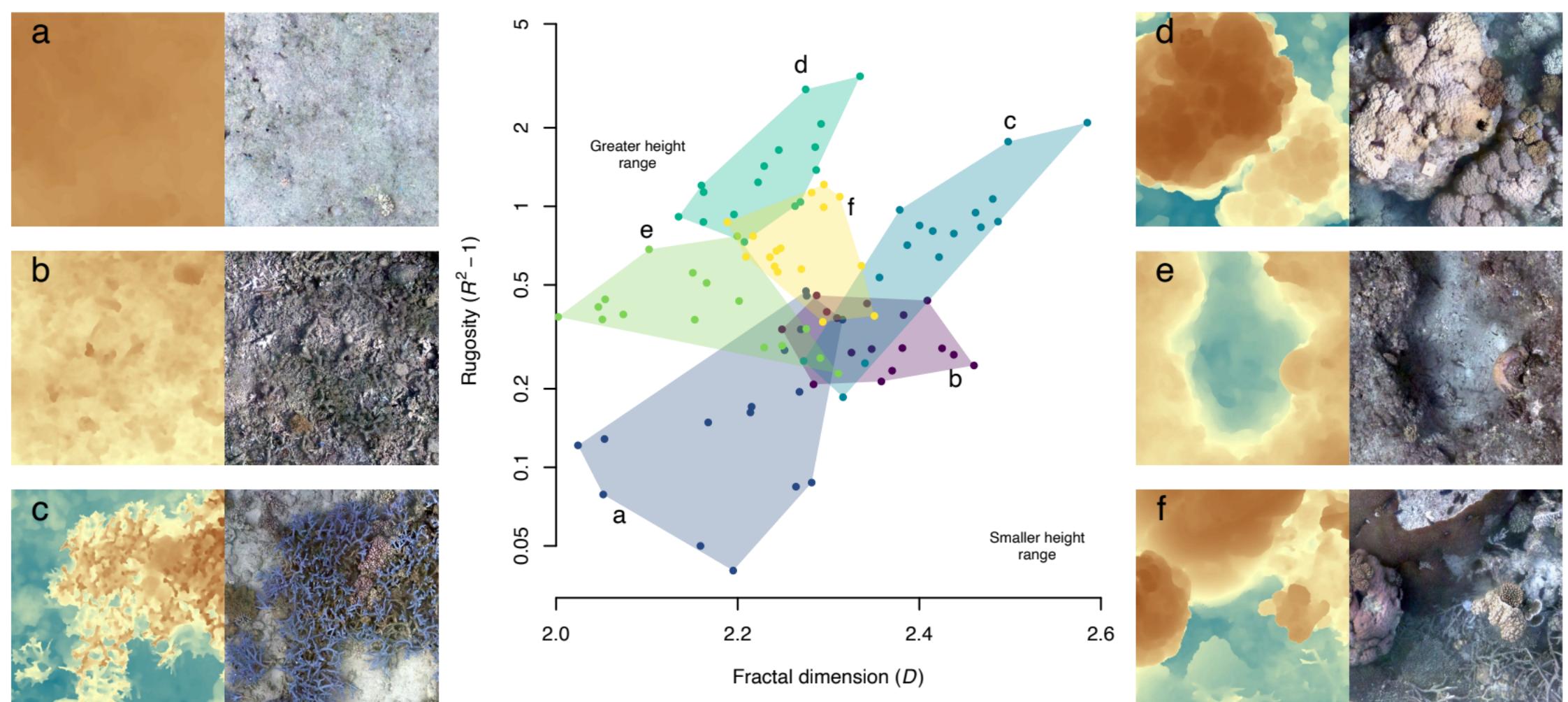
468 **Fig. 3 | The geometric diversity of coral reef habitats.** Reef patches ($n=16$) from a subset of six
469 sites are superimposed onto a two-dimensional representation of the surface descriptor plane
470 (colour used here to delineate sites). (a) North Reef; (b) Osprey; (c) Lagoon-2; (d) Resort; (e)
471 South Island; and (f) Horseshoe. Patch height range is greater in the top left corner and
472 decreases towards the bottom right corner. The corresponding DEMs and orthographic mosaics
473 show selected patches at each site to help visualise geometric differences.

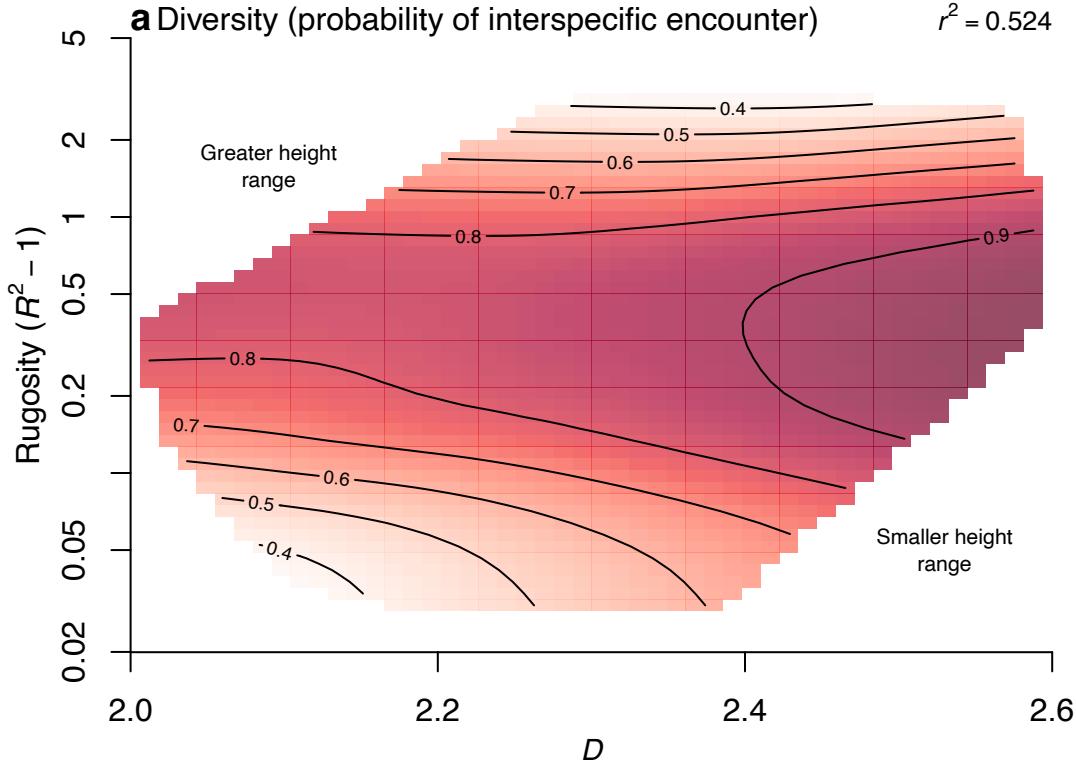
474

475 **Fig. 4 | Geometric-biodiversity coupling of coral reef habitats.** (a) Predicted coral species
476 diversity (represented as probability of interspecific encounter) when plotted upon the surface
477 descriptor plane given by rugosity and fractal dimension (height range is greater in the top left
478 and decreases towards the bottom right, as per Eq. 1). Prediction contours are from the general
479 additive model summarised in Extended Data Table 2. (b) A digital elevation model of the large
480 plot with $n=255$ contiguous 2 x 2 m reef patches (black squares) capturing 9,264 coral colony
481 annotations (white points) representing 171 species.







a Diversity (probability of interspecific encounter) $r^2 = 0.524$ **b**