

Cholecystokinin from the Rhinal Cortex Facilitates Motor Skill Learning

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Abstract

Cholecystokinin (CCK) is an essential modulator for neuroplasticity in sensory and emotional domains. Here, we investigated the role of CCK in motor learning using a single pellet reaching task in mice. Mice with a knockout of *cck* gene (CCK^{-/-}) or blockade of CCK-B receptor (CCKBR) showed defective motor learning ability; the success rate of retrieving reward remained at the baseline level compared to the wildtype mice with significantly increased success rate. We observed no long-term potentiation (LTP) upon high-frequency stimulation (HFS) in the motor cortex of CCK^{-/-} mice, indicating a possible association between motor learning deficiency and neuronal plasticity in the motor cortex. In vivo calcium imaging demonstrated that the deficiency of CCK signalling disrupted the refinement of population neuronal activity in the motor cortex during motor skill training. Anatomical tracing revealed direct projections from CCK-expressing neurons in the rhinal cortex to the motor cortex. Inactivating the CCK neurons in the rhinal cortex using chemogenetic methods significantly suppressed motor learning, and intraperitoneal application of CCK4, a tetrapeptide CCK agonist, rescued the motor learning deficits of CCK^{-/-} mice. In summary, our results suggest that CCK, which could be provided from the rhinal cortex, enables neuroplasticity in the motor cortex leading to motor skill learning.

Introduction

Learning to perform motor skills is essential for survival and high quality of life, such as hunting, running, escaping, fighting, playing music, dancing, drawing, and performing an operation. Evidence from electrical stimulation, lesions, imaging, and more targeted manipulation shows that the motor cortex is the center that controls motor behaviors and motor skill learning in the brain (Papale and Hooks, 2018). Changes among neuronal circuits, such as synaptic strength, circuit connectivity, neuronal excitability, and neuronal structure, which occur through all layers of the motor cortex, contribute to motor skills learning (Papale et al., 2018; Biane et al., 2016; Peters et al., 2014; Costa et al., 2004; Huber et al., 2012). Different layers exhibit various neuronal changes with motor skill learning, corresponding with various layer-specific inputs and descending outputs. However, it is not completely clear how neuronal plasticity in the motor cortex is regulated.

Cholecystokinin (CCK), distributed throughout the whole brain, has been suggested to be important in neuronal plasticity (Li et al., 2014; Chen et al., 2019). Activation of the CCK-B receptor (CCKBR) by infusion of agonist in the auditory cortex regulated visuo-auditory associative memory formation in awake rats (Li et al., 2014). Projections from the entorhinal cortex of the medial temporal lobe release CCK in the neocortex, hippocampus, and amygdala, enabling the encoding of long-term associative, spatial, and fear memory (Li et al., 2014; Meunier et al., 1993, 1996; Chen et al., 2019; Su et al. 2019; Feng et al. 2021). NMDA receptors in the presynaptic membrane control the release of the entorhinal CCK in the auditory

cortex (Chen et al., 2019).

Motor memory, known as procedural memory, is quite distinct from declarative memory examined in previous studies of CCK functions, but both types involve neuronal changes in the neocortex caused by task training (Squire, 2004; Ackermann and Rasch, 2014). In the present study, we investigated the role of CCK from the rhinal cortex, including the entorhinal cortex and perirhinal cortex, to the motor cortex in neuroplasticity and motor skill learning. We examined whether the motor learning ability of mice is affected by the genetic elimination of *cck* gene or the administration of the CCKBR antagonist. We adopted calcium imaging of the motor cortex to verify whether the absence of CCK function disrupts the refinement of the neuronal activation pattern during motor training. We further examined immunohistochemically the CCK-positive neuronal projections from the rhinal cortex to the motor cortex, including the laminar specificity of these projections in their target regions. In the final set of behavioral studies, we examined whether the loss-of-function by inactivating CCK neurons in the rhinal cortex suppresses motor learning ability and the gain-of-function by CCK4 administration rescues the motor learning ability of CCK^{-/-} mice.

Results

The role of CCK in motor learning

A previous study showed that CCK is a key factor regulating neuronal plasticity that enhances long-term memory formation in the auditory cortex (Chen et al., 2019).

Therefore, we introduced a single pellet reaching task to train transgenic CCK^{-/-} mice and their wildtype control (C57BL/6) to use the dominant forelimbs and obtain food rewards as the method to determine whether CCK is involved in motor learning (Figure 1A). This task, including shaping and training, has been adopted in many studies on motor skill learning and motor control systems, especially those controlling the forelimb (Figure 1B) (Xu et al., 2009; Wang et al., 2017). The performance of wildtype and CCK^{-/-} mice was evaluated based on the success rate, which requires accurate performance in aiming, reaching, grasping, and retrieval (Video 1). The success rate of CCK^{-/-} mice did not increase after six days of training, remaining at the baseline level of approximately 15% (Figure 1C, Figure S1; CCK^{-/-} mice, one-way RM ANOVA, $F[5,35] = 0.574$; $p = 0.72$; post hoc. pairwise comparison between different days, Day 1 vs. Day 3, $15.05\% \pm 4.40\%$ vs. $11.91\% \pm 3.60\%$, $p = 0.59$; Day 1 vs. Day 6, $15.05\% \pm 4.40\%$ vs. $15.59\% \pm 3.36\%$, $p = 0.924$), while wildtype mice performed much better, of which the success rate increased significantly to 30.94% on day 3 and remained at a plateau until the end of training (Figure 1C; WT mice, one-way RM ANOVA, $F[5,45] = 4.904$; $p < 0.001$; post hoc. pairwise comparison, Day 1 vs. Day 3, $14.63\% \pm 3.05\%$ vs. $30.94\% \pm 4.17\%$, $p = 0.013 < 0.05$; Day 1 vs Day 6, $14.6\% \pm 3.05\%$ vs. $32.76\% \pm 3.12\%$, $p = 0.004 < 0.01$; between WT and CCK^{-/-} mice, two-way mixed ANOVA, significant interaction, $F[5,80] = 4.03$, $p = 0.003 < 0.01$; post hoc. comparison between two groups, $F[1,16] = 7.697$, $p = 0.014 < 0.05$; WT vs. CCK^{-/-}, Day 3, $30.94\% \pm 4.17\%$ vs. $11.91\% \pm 3.60\%$, $F[1,16] = 11.239$, $p = 0.004 < 0.01$; Day 4, $28.96\% \pm$

2.90% vs. 17.37% \pm 4.35%, $F[1,16] = 5.266$, $p = 0.036 < 0.05$; Day 5, 31.90% \pm 3.50% vs. 16.56% \pm 4.51%, $F[1,16] = 7.465$, $p = 0.015 < 0.05$; Day 6, 32.76% \pm 3.12% vs. 15.59% \pm 3.36%, $F[1,16] = 13.906$, $p = 0.0018 < 0.01$). The success rates of wildtype and CCK^{-/-} mice were similar on day one, indicating that CCK did not affect the basic ability to carry out the task, although the learning ability was inhibited (Figure 1C; t-test, WT vs. CCK^{-/-}, 14.62% \pm 3.05% vs. 15.05% \pm 4.40%, $p = 0.9366$). We also evaluated the variation of trajectories of the hand movement. The deviation of the trajectories of different trials of a wildtype mouse became visibly smaller on Day 3 compared with that on Day 1, while that of a CCK^{-/-} mouse showed no visible improvement (Figure 1D). We calculated the Hausdorff distances, the greatest of all the distances from a point in one set to the closest point in the other set, to evaluate the variation of trajectories (Aydin et al., 2021). The Hausdorff distance for the trajectories of wildtype and CCK^{-/-} mice are similar at Day 1 (Figure 1E; t-test, WT vs. CCK^{-/-}, 0.53 \pm 0.04 cm vs. 0.50 \pm 0.04 cm, $p = 0.5908$). However, after 3 days' training, the Hausdorff distance for wildtype mice significantly decreased while CCK^{-/-} mice remained unchanged (Figure 1E; paired t-test, WT, Day 1 vs. Day 3, 0.53 \pm 0.04 cm vs. 0.42 \pm 0.02 cm, $p = 0.003 < 0.01$; CCK^{-/-}, Day 1 vs. Day 3, 0.50 \pm 0.04 cm vs. 0.48 \pm 0.03 cm, $p = 0.514$).

Failures in retrieving the pellets, including miss, no-grasp, and dropping, are also applied to assess specific learning defects in different movement phases of the complex task, comprising the deficiency of "success", which only indicates the final execution results (Figure 1F). "Miss", representing no touching of the food pellet in

front of the wall of the chamber, is due to inaccurate aiming and inadequate preparation of the neuronal system, especially processes involved in motor control and execution (Video 2). A "no-grasp" is a reach in which the mouse shows a defect in finger closure around food pellets for retrieval (Video 3). A "drop" is a reach in which the mouse drops the food pellet before putting it into the mouth, although the pellet was grasped correctly, indicating a defect in neurons controlling the retrieval process (Video 4). The miss rate of CCK^{-/-} mice was higher than that of wildtype mice, suggesting that CCK may affect the learning ability in aiming and preparing to execute a motor task (Figure 1G; paired t-test, WT, Day 1 vs. Day 6, 32.54% ± 6.43% vs. 11.62% ± 3.58%, $p = 0.0127 < 0.05$; CCK^{-/-}, Day 1 vs. Day 6, 30.77% ± 7.07 % vs. 22.25% ± 2.09%, $p = 0.1732$; t-test, WT vs. CCK^{-/-}, Day 6, 11.62% ± 3.58% vs. 22.25% ± 2.09%, $p = 0.0265 < 0.05$).

Further, we conducted an electrophysiology experiment on the slices of the motor cortex from wildtype and CCK^{-/-} mice to investigate the potential physiological causes for the defects in motor skill learning of CCK^{-/-} mice. We observed LTP in field excitatory postsynaptic potential (fEPSP) after HFS in the wildtype mice, but no LTP from CCK^{-/-} mice, suggesting that CCK plays a key role in neuronal plasticity in the motor cortex (Figure 1H, 1I; two-way mixed ANOVA, $F[1,24] = 3.154$, $p = 0.088$; post hoc. pairwise comparison, WT, before vs. after HFS, 100.06% ± 0.35% vs. 134.38% ± 8.61%, $F[1,20] = 17.255$, $p < 0.001$; CCK^{-/-}, before vs. after, 99.82% ± 0.48% vs. 104.62% ± 7.99%, $F[1,6] = 0.5$, $p = 0.506$).

In summary, CCK^{-/-} mice showed an impaired ability in motor skill learning in the

single pellet reaching task and a defect in the LTP induction in the motor cortex.

A CCKBR antagonist injection in the motor cortex inhibited the motor learning ability of C57BL/6 mice

As deletion of the *cck* gene in the CCK^{-/-} is general, the above experiment results could not indicate the source of CCK and their action site in the brain. We limited our manipulation of the CCK signaling in the motor cortex, targeting its primary receptor, CCKBR, in the neocortex. We have implanted a drug infusion cannula into the motor cortex contralaterally to its dominant forelimb and injected the CCKBR antagonist, L365,260 or its vehicle control to examine whether blocking the CCKBRs in the motor cortex could affect motor skill learning (Figure 2A).

We infused L365.260 to the experimental group or vehicle (ACSF + 0.1% DMSO) to the control group through the implanted drug cannula in the motor cortex every day before training. The success rate of pellet retrieval of the experimental group was not improved through the 6-day training period (Figure 2B, Figure S2A; one-way RM ANOVA, $F[5,50] = 1.959$, $p = 0.101$), while that of the vehicle control group was significantly improved to 32.30% at Day 3 and kept at this level till the end of training (Figure 2B, Figure S2B; one-way RM ANOVA, pairwise comparison, Day 1 vs. Day 3, $19.02\% \pm 4.27\%$ vs. $32.30\% \pm 3.62\%$, $F[1,10] = 5.628$, $p = 0.039 < 0.05$; Day 3 vs. Day 6, $32.30\% \pm 3.62\%$ vs. $32.90\% \pm 7.07\%$, $F[1,10] = 0.007$; $p = 0.937$). The differences in the success rate between the experimental and control groups were significant (Two-way mixed ANOVA, $F[5,70] = 1.881$, $p = 0.109$; post hoc.

comparison between Antagonist and Vehicle, $F[1,14] = 5.066$, $p = 0.041$; Day 3, Antagonist vs. Vehicle, $16.80 \pm 2.83\%$ vs. $32.30 \pm 3.62\%$, $F[1,15] = 11.266$, $p = 0.0048 < 0.01$; Day 4, $18.16 \pm 3.12\%$ vs. $32.90 \pm 5.03\%$, $F[1,15] = 6.876$, $p = 0.019 < 0.05$). This result suggests that CCK participates in motor skill learning by regulating neuronal plasticity in the motor cortex.

For the detailed reaching results, we compared the performance of the experimental and control groups on Day 1 and Day 5. The number of "miss" of the antagonist group had no significant decrease with learning, but for the vehicle group, it dropped from 35% to 10%, indicating that the aiming and advance learning abilities were significantly impaired by inactivation CCKBRs in the motor cortex (Figure 2C, paired t-test, Antagonist, Day 1 vs. Day 5, $27.34\% \pm 9.85\%$ vs. $24.75\% \pm 2.34\%$, $p = 0.794$; Vehicle, Day 1 vs. Day 5, $33.05\% \pm 6.68\%$ vs. $9.17\% \pm 6.04\%$, $p = 0.044 < 0.05$). For the "no-grasp" outcome, the vehicle group increased significantly by 12.24%, indicating that the implantation of a cannula may cause injury to the motor cortex, leading to defects in digit learning (Figure 2C; paired t-test, "no-grasp", Day 1 vs. Day 5, $26.49\% \pm 3.26\%$ vs. $38.73\% \pm 4.05\%$, $p = 0.017 < 0.05$), while that of antagonist showed no improvement increase (Paired t-test, "no-grasp", Day 1 vs. Day 5, $33.78\% \pm 3.36\%$ vs. $34.69\% \pm 4.12\%$, $p = 0.85$). The drop rate of both groups had no significant changes, indicating that the retrieval learning ability was not affected (Figure 2C). In summary, CCK plays a critical role in memory acquisition by activating the CCK receptors in the motor cortex at the overall level.

Calcium imaging of layer 2/3 of the motor cortex during motor skill learning

Based on the outcome of the above drug infusion experiment and previous studies, the motor cortex is one of the primary sites for motor skill learning (Wang et al., 2017). Previous studies found that neuronal activity patterns in the Layer 2/3 of the motor cortex were refined, exhibiting reproducible spatiotemporal sequences of activities with motor learning (Peters et al., 2014). Therefore, calcium imaging of neurons in the motor cortex layer 2/3 of C57BL/6 mice, CCK^{-/-} mice and C57BL/6 mice injected with the CCKBR antagonist was performed to determine the activities of neurons in the motor cortex during the single pellet reaching task.

We hypothesized that the CCK-enabled neuronal plasticity happens at the population level in the motor cortex. To test the hypothesis, we attached a one-photon miniscope over the motor cortex, contralateral to the dominant hand of the mouse, with an implanted high light transmission glass window in between (Figure 3B). We installed a web camera in front of the training chamber to simultaneously monitor the mouse performing the task with the neuronal activities.

We recruited three groups of mice, 1) C57BL/6, 2) CCK^{-/-}, and 3) C57BL/6 with CCKBR antagonist, to examine how CCK signaling affects neuronal activities in the motor cortex (Figure 3A). We first confirmed GCaMP6s signals in layer 2/3 of the motor cortex, as shown in the examples (Figure 3B; Video 5). The neuronal signals were extracted with CNMF-E and analyzed with MATLAB (Figure 3C). Neurons showed various temporal and spatial responses to the movements during the task.

The neuronal activity pattern, excluding the indiscriminate neurons (ranksum test, neuronal activity during reaching & not reaching, $p \geq 0.05$), in the C57BL6 group,

was refined after six days of training; the peak activity of the neurons became stronger with lower background activity (Figure 3D). These results are similar to that of layer 2/3 neurons of the motor cortex in a mouse performing a lever-press task (Peters et al., 2014). In contrast, we found no apparent changes after training for six days for groups of CCK^{-/-} and C57BL/6 mice injected with the antagonist, the neuronal activity pattern (Figure 3D).

The population activity of neurons varied with time relative to movement onset, starting to rise around 0.2 s before movement onset and reaching the peak at the time of 0.33 s after movement onset (Figure 3E and Figure S3). The activated population activity, peak activity minus baseline activity, for C57BL/6 mice increased significantly with training (Figure 3F; paired t-test, Day 1 vs. Day 6, 0.0216 ± 0.0062 vs. 0.0593 ± 0.0114 , $p = 0.044 < 0.05$). However, we observed no significant change in the activated population activity for both CCK^{-/-} and L365,260 groups (Figure 3F; paired t-test, CCK^{-/-}, Day 1 vs. Day 6, 0.0313 ± 0.0057 vs. 0.0386 ± 0.0099 , $p = 0.237$; L365,260, Day 1 vs. Day 6, 0.0218 ± 0.0094 vs. 0.0354 ± 0.0080 , $p = 0.240$).

We adopted the Pearson correlation coefficient to evaluate the recurrence of neuronal activities among reaching trials. We compared the average correlation coefficient of neuronal activities of different trials between Day 1 and Day 6. We observed a significant increase in the trial-to-trial population activity correlation on Day 6 compared with Day 1 in the C57BL/6 mice group (Figure 3G, one-way RM ANOVA, Day 1 vs. Day 6, 0.023 ± 0.01 vs. 0.12 ± 0.04 , $F[1,9] = 5.342$, $p = 0.046 < 0.05$). However, we observed no significant differences in the correlations between

Day 1 and Day 6 in the CCK^{-/-} group, nor in the L365,260 group (Figure 3G; one-way RM ANOVA, CCK^{-/-}, Day 1 vs. Day 6, 0.10 ± 0.07 vs. 0.07 ± 0.06 , $F[1,6] = 0.073$, $p = 0.796$; L365/260, Day 1 vs. Day 6, 0.12 ± 0.07 vs. 0.12 ± 0.05 , $F[1,6] = 0.005$, $p = 0.944$). The pairwise Hausdorff distance of trajectories in C57BL/6 group decreased significantly with training, while no significant changes were observed in CCK^{-/-} or L365,260 injection group, suggesting that the population activities are in line with the changes of the variation of the trajectories during motor learning (Figure 3H; paired t-test, C57BL/6, Day 1 vs. Day 6, 0.6613 ± 0.017 cm vs. 0.5588 ± 0.0227 cm, $p = 0.0075 < 0.01$; CCK^{-/-}, Day 1 vs. Day 6, 0.6787 ± 0.0470 cm vs. 0.6760 ± 0.0501 cm, $p = 0.9219$; L365,260, Day 1 vs. Day 6, 0.7012 ± 0.0594 cm vs. 0.6712 ± 0.0659 cm, $p = 0.5606$). The trial-to-trial population activity correlation in L365,260 group on Day 1 appeared to be higher than that in C57BL/6 group. This might be due to that the drug blocked the trial-to-trial learning on Day 1, suppressing the exploration of the optimal path and abandonment of bad movements that would otherwise occur in wildtype mice.

Taken together, CCK deficiency causes defects in neuronal refinement and the reproducibility of neuronal activity among different trials during motor skill learning.

CCK-expressing neurons in the lateral entorhinal cortex projecting to the motor cortex

Our next quest was to find what CCK projection is crucial in motor skill learning. We understand that CCK neurons in the entorhinal cortex, a gateway from the

hippocampus to the neocortex, play critical roles in encoding sound-sound, visuoauditory, fear, and spatial memory (Li et al, 2014; Chen et al, 2019; Feng et al, 2021; Su et al. 2019). These findings prompted us to examine whether CCK-expressing neurons in the entorhinal cortex also project to the motor cortex.

We used both anterograde and retrograde viruses to track neuronal projections in this study. We first injected a Cre-dependent, highly efficient AAV virus expressing mCherry into the rhinal cortex of one hemisphere of 8-week-old CCK Cre mice (Figure 4A). This viral vector is expected to be taken up in the soma of neurons and transported to the axon terminus. In the motor cortex, mCherry-expressing neuronal axons mainly spread in layer 2/3 or layer 6 (Figure 4B). We next injected a Cre-dependent retrograde AAV vector expressing EYFP fluorescent protein gene into the motor cortex in deep layers and superficial layers to verify the projections from the lateral entorhinal cortex to the motor cortex (Figure 4C). In the rhinal cortex, the EYFP-labeled soma spread from AP: -2.54 to AP: -4.30, and local clusters were observed in layer 4 and layer 5, where the neurons are expected to project to the neocortex (Figure 4D). Both anterograde and retrograde tracking results indicated that CCK-expressing neurons in the rhinal cortex projecting to the motor cortex were asymmetric, showing a preference for the ipsilateral hemisphere. Primary antibodies against GAD67 and CaMK2a were used for the immunostaining of the rhinal cortex sections to determine the characteristics of CCK neurons projecting to the motor cortex. None of the retrograde EYFP-labeled neurons merged with GAD67 staining but completely colocalized with CaMK2a staining, indicated by the white arrowhead,

suggesting that the neurons projecting to the motor cortex are all excitatory neurons (Figure 4E and 4F). Therefore, CCK neurons in the rhinal cortex may affect motor skill learning by regulating the plasticity of neurons in the motor cortex.

Inhibiting CCK neurons in the EC/PC suppresses motor learning

In the following experiment, we adopted chemogenetics to selectively silence the CCK projection neurons from the rhinal cortex to the motor cortex to examine their involvement in motor skill learning.

We injected a Cre-dependent AAV vector carrying hM4Di or mCherry into the rhinal cortex bilaterally in CCK-Cre mice one month before the behavior test (Figure 5A). Clozapine was intraperitoneally injected, followed by an approximately 30 min period for drugs to be taken up and transported to the brain. The drug bound to the hM4Di and inactivated the neurons (Figure 5A). The success rate of hM4Di with the clozapine injection group showed no significant increase after six days of training, while the success rate of the control group of mCherry with clozapine injection increased significantly beginning on the third day of training and remained at a high level until the end of training (Figure 5B, Figure S4A, S4B; hM4Di+Clozapine group, one-way RM ANOVA, $F[5,50] = 0.839$, $p = 0.528$; mCherry+Clozapine group, one-way RM ANOVA, $F[5,35] = 3.121$, $p = 0.02 < 0.05$; two-way mixed ANOVA, post hoc. comparison between two groups, $F[1,17] = 7.014$, $p = 0.016 < 0.05$, hM4Di vs. mCherry, Day 3, $12.92\% \pm 3.10\%$ vs. $25.99\% \pm 3.62\%$, $F[1,17] = 7.510$, $p = 0.014 < 0.05$; Day 4, $12.04\% \pm 1.84\%$ vs. $24.78\% \pm 3.34\%$, $F[1,17] = 12.804$, $p = 0.002 < 0.05$).

0.01; Day 5, 15.02% \pm 2.55% vs. 25.74% \pm 3.72%, $F[1,17] = 6.061$, $p = 0.025 < 0.05$;
Day 6, 14.41% \pm 4.01% vs. 28.42% \pm 5.64%, $F[1,17] = 4.354$, $p = 0.052$).

To exclude the possibility that hM4Di alone might regulate the neurons in this system, we administered saline as the control to the mice with the same virus vector with hM4Di injected into the rhinal cortex of CCK-Cre mice, as compared to the clozapine-administered experimental group (Figure 5A). The learning curve of the control group injected with saline showed a learning trend in the single pellet reaching task, similar to the "mCherry + clozapine" group, and the success rate was significantly different from the "hM4Di+clozapine" group (Figure 5C, Figure S4C; hM4Di + saline group, one-way RM ANOVA, $F[5,45] = 7.911$, $p < 0.001$; between groups, two-way mixed ANOVA, significant interaction, $F[5,95] = 2.813$, $p = 0.021 < 0.05$, hM4Di+saline vs. hM4Di+clozapine, post hoc. comparison between two groups, $F[1,19] = 6.193$, $p = 0.022 < 0.05$; post hoc. comparison between two groups on different days, Day 3, 24.02% \pm 3.93% vs. 12.12% \pm 3.10%, $F[1,19] = 5.013$, $p = 0.0373 < 0.05$; Day 4, 27.81% \pm 3.84% vs. 12.04% \pm 1.84%, $F[1,19] = 14.534$, $p = 0.0012 < 0.01$; Day 5, 24.54% \pm 3.05% vs. 15.02% \pm 2.55%, $F[1,19] = 5.785$, $p = 0.0263 < 0.05$; Day 6, 30.60% \pm 4.59% vs. 14.41 \pm 4.01%, $F[1,19] = 7.128$, $p = 0.0151 < 0.05$; The hM4Di+clozapine curve in Figure 5C shared that in Figure 5B). These results concluded that CCK neurons in the rhinal cortex may be crucial for motor learning.

Rescue of the motor learning ability of the CCK^{-/-} mice with CCK4

So far, we have examined the potential involvement of CCK in motor skill learning with several loss-of-function studies. We next designed a gain-of-function experiment to see whether CCKBR agonist could rescue the defective motor learning ability. A tetrapeptide, CCK4 (Trp-Met-Asp-Phe-NH₂), a CCKBR agonist that can pass through the brain-blood barrier, was chosen to regain the defective motor learning ability of CCK^{-/-} mice (Feng et al., 2021).

Firstly, we examined whether CCK4 could rescue the defective neuronal plasticity in the motor cortex of CCK^{-/-} mice. We carried out electrophysiology recording on the motor cortex of the brain slices from the CCK^{-/-} mice. After 15 minutes of stable baseline recording, CCK4 or vehicle was injected into the electrode dish and applied HFS, followed by 60 minutes of recording. We observed a significant rescuing effect by CCK4 application before the HFS compared with its vehicle control (Figure 6A and 6B; Vehicle vs. CCK4, two-way mixed ANOVA, significant interaction during -10 - 0 min and 50-60 min, $F[1,21] = 10.656$, $p = 0.004 < 0.01$; post hoc. comparison between two groups, $F[1,21] = 7.997$, $p = 0.01 < 0.05$; Vehicle, before vs. after, $100.95\% \pm 0.67\%$ vs. $95.53\% \pm 5.77\%$, $F[1,10] = 1.239$, $p = 0.292$; CCK4, before vs. after, $100.28\% \pm 0.47\%$ vs. $118.89\% \pm 6.09\%$, $F[1,11] = 11.653$, $p = 0.006 < 0.01$).

Next, we examined whether the CCK4 application could rescue the motor skill learning of CCK^{-/-} mice. We injected with CCK4 or vehicle solution intraperitoneally to CCK^{-/-} mice every day before the 6-day training (Figure 6C). The success rate of CCK4-injected group kept at the baseline level in the first three days and started to increase gradually from Day 4 to Day 6 (Figure 6D, Figure S5A; CCK4, one-way RM

ANOVA, $F[5,50] = 3.914$, $p = 0.005 < 0.01$; Day 5 vs. Day 1, $30.58\% \pm 4.18\%$ vs. $19.17\% \pm 3.03\%$, $F[1,10] = 5.680$, $p = 0.038 < 0.05$; Day 6 vs. Day 1, $31.50\% \pm 4.43\%$ vs. $19.17\% \pm 3.03\%$, $F[1,10] = 6.893$, $p = 0.025 < 0.05$). In contrast, we observed no improvement in the success rate in the vehicle control group mice (Figure 6D, Figure S5B; Vehicle, one-way RM ANOVA, $F[5,55] = 0.476$, $p = 0.793$). The between-group comparison showed that the CCK4 group had significantly higher success rate from Day 5 to Day 6 compared to the vehicle group (Figure 6D; Vehicle vs CCK4, two-way mixed ANOVA, significant interaction, $F[5,105] = 2.405$, $p = 0.043 < 0.05$; post hoc. comparison between Vehicle and CCK4, Day 5, $14.88\% \pm 2.61\%$ vs. $30.51\% \pm 4.18\%$, $F[1,21] = 10.459$, $p = 0.004 < 0.01$; Day 6, $17.76\% \pm 3.25\%$ vs. $31.50\% \pm 4.43\%$; $F[1,21] = 6.412$, $p = 0.019 < 0.05$).

We compared the detailed reaching results on Day 1 and Day 5 between the CCK4 and the vehicle groups. We found the miss rate of the CCK4 group dropped significantly at Day 5 compared to Day 1, while that of the vehicle group showed no significant change (Figure 6E; paired t-test, Vehicle, Day 1 vs Day 5, $26.12\% \pm 5.71\%$ vs. $18.71\% \pm 4.31\%$; $F[1,11] = 1.155$, $p = 0.305$; CCK4, Day 1 vs Day 5, $25.47\% \pm 4.03\%$ vs. $13.13\% \pm 2.80$, $F[1,10] = 6.643$, $p = 0.028 < 0.05$), suggesting that the CCK4 rescued the aiming in reaching. This result demonstrated that CCK4 could cross the brain blood barrier and partially rescue the motor learning ability of CCK^{-/-} mice (Figure 6E).

Therefore, CCK is the crucial signal that enables motor learning. Intraperitoneal injection of CCK4 is sufficient to rescue the motor learning ability by turning on the

neuronal plasticity of the CCK^{-/-} mice.

Discussion

CCK^{-/-} mice showed defective motor learning ability, of which the success rate of retrieving reward remained at the baseline level compared to the wildtype mice with a significantly increased success rate. We induced no LTP by HFS in the motor cortex of CCK^{-/-} mice but readily in their wildtype control, indicating a possible association between the motor learning deficiency and neuronal plasticity in the motor cortex. *In vivo* calcium imaging demonstrated that the deficiency of CCK signaling led to the defect in the population neuronal plasticity in the motor cortex affecting motor skill learning.

We found that the CCK-positive neurons in the rhinal cortex projected to the motor cortex, using both anterograde and retrograde tracing methods. Inactivating the CCK neurons in the rhinal cortex using chemogenetic methods significantly suppressed the motor learning ability. Our further gain-of-function study revealed that intraperitoneal application of CCK4 rescued the defective motor skill learning of CCK^{-/-} mice.

Neuronal plasticity of the motor cortex has been assessed by many researchers using multiple methods, such as single pellet reaching task and lever-press task (Xu et al., 2009; Peters et al., 2014). Other brain areas are also involved in motor skills learning, such as thalamus, striatum, cerebellum, and midbrain. Thalamocortical projections in the motor cortex are widely distributed in all layers, including inputs to corticospinal neurons in layer 5 (Hooks et al., 2013). With single pellet reaching task training, thalamocortical neurons are biased in activating the corticospinal neurons

that control the performance of the task, though the unbiased activation of corticospinal neurons was observed before training, suggesting that the thalamus selectively activates corticospinal neurons to generate better control of the forelimb movement with motor learning (Biane et al., 2016). The spiking of Purkinje neurons switched from more autonomous, the baseline condition, to time-locked activation or silence before reaching onset to produce a state promoting a high quality of movement, as mice learn to direct a robotic manipulation toward a target zone (Wangner et al., 2021). The ventral tegmental area (VTA) dopaminergic projection in the motor cortex is necessary for motor skill learning but not for execution. The VTA projection to the motor cortex may facilitate the encoding of a motor skill memory by relaying food reward information related to the task (Hosp et al., 2011). As the core area where dexterous motor memory is encoded, the plasticity of the motor cortex enables animals to learn complex motor tasks.

CCK produced in the rhinal cortex has been identified as the key to transforming a paired tone into auditory memory in mice and rats by regulating the plasticity of neurons in the auditory cortex (Li et al., 2014). In the present study, we found that genetic knockout of the *cck* gene caused defects in motor learning, while the success rate of wildtype mice increased to 30.94% on day 3. The success rate alone is not sufficient to describe the function of CCK in motor skill learning; therefore, the reaching result of the task is divided into four types, "miss", "no-grasp", "drop" and "success". "Miss" is caused by defects in "aiming" and "advance", indicating a low probability of hitting the pellet. Miss rate of the CCK^{-/-} mice decreased with learning

but showed less improvement than the wildtype mice, suggesting that the brain areas controlled the “aiming” and “advance” are affected by CCK partially. Besides, “no-grasp” and the “success” rate of CCK^{-/-} mice remained at the same levels after training, but the “drop” rate increased, suggesting that the improved “miss” trials finally turned to “drop”. The variation of the trajectories of the CCK^{-/-} mice is lower than that of the wildtype mice on the first day, which is consistent with the previous results that the animals with low variation in trajectories learn worse than those with wide variation in trajectories at the initiation stage (Wu et al., 2014). The reason may be that when animals perform a motor task, the wider the variation of the movement, the easier it is for the mice to find the best path to complete the task. The lack of CCK impaired the plasticity of neurons in the motor cortex, which is deemed the basis for motor learning.

The motor cortex plays the leading role in controlling motor memory encoding (Cheney, 1985; Sanes and Donoghue, 2000; Economo et al., 2018; Svoboda and Li, 2018). CCKBRs dominate CCKARs in the neocortex including the motor cortex (Crawley and Corwin, 1994; Wank, 1995). Blockade of the CCKBRs in the motor cortex suppressed the improvement in the success rate of mice in the single pellet reaching task (Figure 2B). The gradually improved success rate on Day 5 and 6 (Figure 2B) after CCKBR antagonists could be due to the lasting of the antagonists was not long enough to cover the whole training period, partially due to the diffusion of the antagonist. The performance of both the “antagonist” and “vehicle” groups was similar on the first day, indicating a similar neuronal baseline condition for each group.

Activating CCKBR by CCK agonist improves motor skill learning.

Based on the evidence that CCK is important for neuronal plasticity of the motor cortex and motor skill learning, the next question is how CCK affects the changes in neuronal activity of the motor cortex during training. An earlier study found that neuronal activities in layer 2/3 of the motor cortex were modified, exhibiting more reproducible spatiotemporal sequences of neuronal activities with motor learning (Peters et al., 2014).

In the present study, the neuronal activities related to the task in layer 2/3 of the motor cortex of C57BL/6 mice were refined with motor skill learning, the activation of neurons becoming more reproducible among trials. The reproducibility changes of neural activities are in parallel with the reduced variations in the trajectories of the C57BL/6 mice after training (Figure 1F, 1G). However, CCK^{-/-} mice generated distinct changes in the neuronal activity in the motor cortex compared with C57BL/6 mice. The pattern of the peak activity and the trial-to-trial population correlation had no significant differences after six days of motor learning, suggesting no refinement in the neuronal circuit after motor learning in CCK^{-/-} mice (Figure 3D).

In order to exclude a different background of neuronal activity due to long-term accommodation to the lack of CCK in CCK^{-/-} mice, we injected the CCKBR antagonist, L365,260 into the motor cortex of C57BL/6 mice and observed no significant changes in the pattern of the peak activity and the trial-to-trial population correlation had after six days of motor learning, similarly to the CCK^{-/-} mice.

The entorhinal cortex is crucial for learning and memory (Chen et al., 2013; Feng et

al 2021). Our group found that CCK is essential for neuronal plasticity in the auditory cortex (Li et al., 2014). In this research, we determined that CCK from the rhinal cortex may be critical for motor skill learning.

In the rhinal cortex, CCK-positive neurons that project to motor cortex are excitatory neurons (Figure 4E, 4F). The roles of both CCK and glutamate in the neuronal plasticity and the relationship between CCK and glutamate have been studied before (Bandopadhyay and Belleruche, 1991; Chen et al., 2019). In the previous study, we found that CCK is critical for HFS induced LTP, and CCK release is triggered by the activation of (N-methyl-D-aspartate) NMDA receptors that could be located in the presynaptic membrane of CCK-positive neurons (Chen et al., 2019). In the motor cortex, many CCK-positive neurons are GABAergic (γ -aminobutyric acid) neurons, in which the role CCK played is not very clear. However, evidence showed that GABA may inhibit the release of CCK in the neocortex (Yaksh et al., 1987). Many glutamatergic neurons in the neocortex also express CCK (Watakabe et al., 2012). Future study in the future is needed to investigate the role of cortical CCK-positive neurons, including inhibitory and excitatory neurons, played in neuronal plasticity and motor skill learning.

The hippocampus system, including the rhinal cortex, plays an essential role in declarative learning based on the finding of the famous patient H.M. (Corkin, 1968). However, the understanding of the role of the hippocampus system in motor skills learning is not consistent (Corkin, 1968; De et al., 2019). In the mirror tracking task, the performance of H.M. was on par with normal people, suggesting that the motor

learning ability was not affected without the hippocampus system (Corkin, 1968). But in the other two motor learning tasks, rotary pursuit and bimanual tracking, the performance of H.M. was much worse than the control. Besides, the movement of H.M. was slower when performing the task. This explanation is not enough to exclude the effects of the hippocampus system on motor skill learning. Indeed, Corkin herself thought that the H.M. could perform tasks that required less demanding motor skills, but not the tasks demanding better motor skills (Corkin, 1968; Brigard, 2019).

The single pellet reaching task is a complex and dexterous motor task requiring the neocortex and the whole motor system. Chemogenetic inactivation of CCK neurons in the rhinal cortex significantly impaired the mice's motor learning ability compared to the two control groups.

Based on the anterograde and retrograde tracing of the neurons in the rhinal cortex, projections terminals from the rhinal cortex to the motor cortex were distributed to the superficial and deep layers (Figure 4B, 4D). Previous research on both layer 2/3 and layer 5 found that motor skill learning refined neuronal activity in layer 2/3 of the motor cortices of the mice in a lever-press task. Thus, the CCK projections in the superficial layer may be where plasticity occurs (Peters et al., 2017; Heindorf et al., 2018). Two-photon calcium imaging results from previous research indicated that spine generation and elimination occurred in the apical dendrites (in the superficial layer) of neurons in layer 2/3. Still, the spines around the soma of the neurons in layer 2/3 showed no significant changes (Chen et al., 2015), consistent with the location of CCK neuron terminals projecting from the rhinal cortex.

Therefore, CCK from the rhinal cortex promotes dexterous motor skill learning by regulating the activity of the motor cortex.

Rescuing Neuroplasticity and Motor Skill Learning

Our gain-of-function experiment by injecting CCK4 to rescue the defective learning ability of CCK^{-/-} mice supported the critical role of CCK in neuronal plasticity of the motor cortex and motor skill learning. The CCKBRs of CCK^{-/-} mice were not influenced by knocking out the *cck* gene, making it possible that the exogenous CCK activates the CCKBRs (Feng et al., 2021). CCK4, a tetrapeptide, can pass through the blood-brain barrier. CCK^{-/-} mice with the defective motor learning capability improved significantly after the daily, single intraperitoneal injection of CCK4, to a comparable level as their wildtype control at Day 5. The results of the rescuing experiment imply a potential new target for facilitating motor rehabilitation.

Materials and Methods

Animal

Young adult wildtype (C57BL/6) mice and C57BL/6 background transgenic mice, CCK-Cre (CCK-ires-Cre, Stock #012706, Jackson Laboratory) and CCK^{-/-} (CCK-CreER, strain #012710, Jackson Laboratory), were used for behavior, electrophysiology and anatomy experiments. All mice were housed in the pathogen-free 12 hours light/dark cycle holding room with the temperature at 20 - 24 °C. All experimental procedures were approved by the Animal Subjects Ethics Sub-

Committee of the City University of Hong Kong.

Single pellet reaching task

The behavioral experiment, single pellet reaching task, was modified based on a previously established procedure (Xu et al., 2009; Chen et al., 2014). A clear and transparent Plexiglas chamber (5 mm thickness, dimensions 20 cm x 15 cm x 8.5 cm) was built for mice training, with three 5 mm wide slits on the front wall; one is in the middle, the other two are 1.9 cm to the side, respectively. A 1.0-cm-height exterior shelf was affixed in front of the front wall to hold the chocolate pellets (#1811223, 20 mg, TestDiet) for reward. The food pellet was placed 0.7 cm away from the front wall and 0.4 cm away from the midline of the slit, to encourage the mouse to use the dominant hand for catching (Figure 1A). The task has two periods, shaping and training. Mice were food restricted to keep approximately 90% body weight of the original weight during the whole process (Figure1B). On shaping day one, two mice from the same cage were placed into the chamber for 20 min to acclimate to the environment; on shaping day two, an individual mouse was placed into the chamber for 20 min. During shaping, 10 food pellets were feed for each mouse every day to train mice eating food pellets. On shaping day 3, a food tray full of food pellets was placed in front of the middle slit. The mouse can get the food reward by catching it through the slit with either hand. The experiment stopped when 20 times of reaching attempts were finished for each mouse. The dominant hand should be the one that shows over 70% preference. During the training period, mice reached for food pellets through the slit by the dominant hand, 40 attempts within 20 min every day. Only

attempts by the dominant hand were counted. Based on the results of the attempts, the reaching attempts show four types: miss, no-grasp, drop, and success. A "miss" means that the hand does not touch the food pellet. A "no-grasp" means that the hand of the mouse touches the food pellet, but it does not successfully grasp the pellet. A "drop" represents the mouse grasps the pellet, but it dropped due to whatever reasons during the retrieval. A "success" was a reach in which the mouse successfully retrieved the pellet and put it into the mouth of the mouse. A high-speed camera was placed on the side of the chamber to videotape the reaching behavior of mice at 60 frames per second. The success rate was calculated as the number of successful attempts / the total attempts. The miss rate, the no-grasp rate, and the drop rate were also calculated to evaluate the performance of each step of mice. Hausdorff distances, the greatest of all the distances from a point in one set to the closest point in the other set, were calculated to assess the variation of trajectories.

CCKBR antagonist injection

C57BL/6 mice were implanted a cannula in the motor cortex (coordinates: AP, 1.4 mm, ML, ± 1.6 mm, DV, 0.2 mm) contralateral to the dominant hand of the mice, followed by three days of recovery. Mice were grouped into antagonist and vehicle groups. L365,260 (CCKBR antagonist) (1 μ l, 20 μ M, Cat. No. 2767, biotechne) or vehicle (0.1% DMSO dissolved in ACSF) was injected into the motor cortex through the cannula with the flow rate of 100 nl/ min pumped by a syringe pump (Hamilton, USA), before the mice were placed into the chamber for the single pellet reaching

task training.

Chemogenetic manipulation

A Chemogenetics experiment was performed on CCK-ires-Cre mice (#012706, Jackson Laboratories). Cre-dependent hM4Di virus was injected into the rhinal cortex. Detailed coordinates and volumes were described in the virus injection part. Mice were used for single pellet reaching task training four weeks post virus injection. Thirty minutes before behavior training, clozapine (0.4 mg/kg, Sigma-Aldrich, dissolved with 0.1% DMSO) was intraperitoneally injected to inactivate the activity of the CCK-expressing neurons in the rhinal cortex. The same volume of vehicle (0.9% saline solution with 0.1% DMSO) was injected for the sham control group. A negative control virus (AAV8-hSyn-DIO-mCherry) combined with intraperitoneal clozapine injection was also carried out to exclude the influence of clozapine on motor learning ability.

Virus injection and surgical process

AAV8-hSyn-DIO-mchery, AAV8-hSyn-DIO-hM4Di-mCherry were diluted to the titer around 5×10^{12} copies/ml and AAV_{retro}-EF1a-DIO-EYFP, AAV-hSyn-CaMKII-GCaMP6s-SV40 were diluted to the titer around 1×10^{13} copies/ml and injected into the mouse cortex as previously described (Zhu and Roth, 2015; Tervo et al., 2016; Wu et al., 2020). The mice were anesthetized with pentobarbital with their fur between two ears trimmed and fixed on a stereotactic

apparatus (RWD, China). Firstly, the head skin of the mouse was cleaned and sterilized with 70% alcohol and removed to expose the skull totally. To accurately locate the areas of interest, the head was adjusted between middle and lateral, and anterior and posterior. In order to completely inactivate the rhinal cortex, two injection sites per hemisphere were determined for virus injection using the following coordinates: site 1: anteroposterior (AP), -3.52 mm from Bregma, mediolateral (ML), 3.57 mm, dorsoventral (DV), -3.33 mm from the brain surface; site 2: AP, -4.24 mm from Bregma, ML, 3.55 mm, DV, -2.85 from the brain surface. Microinjections were carried out using a microinjector (world precision instruments, USA) and a glass pipette (Cat#504949, world precision instruments, USA). The volume is 200 nl for each site and the flow rate is 50 nl/min.

To track the projection of CCK neuron from the rhinal cortex to the motor cortex, retrograde AAV-EF1a-DIO-eYFP was injected into the motor cortex. The coordinates is: site 1: AP, 1.8 mm to the Bregma, ML, 1.2 mm, DV 200 um, and 600 um; site 2: AP, 1.0 mm to the Bregma, ML, 1.5 mm, DV, 200 um and 600 um. The volume of each site at each DV was 200 nl and the flow rate was 20 nl/ min to protect the fluid from flowing out. An anterograde AAV-hSyn-DIO-mCherry is also used for projection tracking by injecting the virus into the rhinal cortex of the hemisphere. The specific coordinates are as described above. After virus injection, skins were seamed with sterilized sewing thread, and the cut was spread with antibiotic paste to protect it from pathogens and accelerate healing.

The surface virus infusion process for the calcium imaging was performed as

described previously with mild modification (Li et al., 2017). A wide-tip glass pipette was prepared by a micropipette puller and then cut, polished, and flame-treated to make it even and smooth. Mice were intraperitoneally injected with dexamethasone (0.2 mg/kg, s.c.) and carprofen (5 mg/kg, s.c.) to protect the brain from swelling and inflammation. Three hours later, mice were anesthetized with pentobarbital. The periosteum covered on the skull was removed, cleaned, and dried with 100% alcohol to prevent the skull and tissues from growing. A 3 x 3 mm² window above the motor cortex contralateral to the dominant hand was opened with a hand drill, and the bone debris was carefully removed with fine forceps. After that, the dura around the injection area was removed (open a dura hole of about 1 mm²) to expose the pial tissue for virus infusion. The tip of the pipette tightly covered the brain surface by lowering 400-500 um, and 0.6 ul virus was infused at the speed of 0.06 ul/min. A 3 x 3 cover glass (thickness, around 150 um) was attached to the brain surface, and gentle pressure was applied to keep the cover glass at the level same as the skull. The edge of the cover glass was sealed with superglue. After the glue totally hastened, the skin was stretched back and sutured.

Baseplate implantation

2-3 weeks after cranial window implantation, the scalp over the skull was totally removed with surgical scissors. Success implantation shows a clear observation window without blood on the brain surface and a cover glass tightly fixed on the skull. The cover glass surface was gently cleaned with Ringer's solution and lens paper, and

the regrowth of periosteum on the skull was removed with fine forceps. Before baseplate implantation, the skull was dried with 100% alcohol, covered with Metbond glue, and a thick layer of dental acrylic except for the cover glass for observation.

A one-photon miniscope (UCLA miniscope V4, Lab maker, Germany) connected to the data acquisition software was attached to the baseplate, secured on the stereotaxic micromanipulator, and gradually lowered to the cover glass until there was only a 1 mm gap between the skull and the baseplate. We turned on the LED and adjusted the focal distance of the electrowetting lens to 0 on the software. The position of the miniscope was adjusted until the brain tissue was observed in the data acquisition system. Dental acrylic was used to fix the baseplate to the acrylic cap covering the skull around the window. Once the dental acrylic had hardened, the miniscope was removed, and a metal cap was attached to the baseplate to protect the cover glass window.

Calcium imaging and fluorescent signal analysis

After the implantation of the baseplate, a miniscope model was attached to the baseplate, and the mouse was placed in the chamber to acclimate to the weight of the miniscope for 20 minutes for 3 days. The LED laser and focal plate were slightly adjusted until the cells with fluorescent protruded from the background. A web camera was also connected to the data acquisition software and recorded the behavior movement of the animal simultaneously.

An imaging field of about 1.0 x 1.0 mm² (resolution: 608 x 608 pixels) video at

approximately 10 min long was recorded. To clearly figure out the role of CCK played in the neuronal plasticity of the motor cortex from CCK^{-/-} mice, C57BL/6 mice as well as C57BL/6 mice that intraperitoneal injection of CCKBR antagonist, L365,260 (0.4 mg/kg, Cat. No. 2767, biotechne). Raw AVI videos were firstly spatially down-sample by two folds to reduce the size of the videos by Fiji (Image J, USA). Then a MATLAB algorithm, NoRMCorre, was applied for piecewise rigid motion correction before data analysis. The calcium signals were extracted with the MATLAB code of Constrained Nonnegative Matrix Factorization for microEndoscopic (CNMF-E) (code availability: https://github.com/zhoupc/CNMF_E) (Zhou et al., 2018). The scaled fluorescent calcium signal overtime was extracted as C_raw. The raw data was then deconvolved. The activity higher than 3 times the standard deviation of baseline fluctuation is deemed as a calcium event which has been revealed to be associated with neuronal spiking activity, and the rising phase of which was searched and used for further neuronal activity analysis (Peters et al., 2014; Wang et al., 2017). Timestamps from both the behavior videos and the calcium imaging videos were aligned to find out the time window when the mouse performed the reaching task. Neuronal activity in the time window from 100 ms before reaching to 100 ms after retrieval was considered the activity related to the movements. Wilcoxon ranksum test was conducted between activity inside the time window and activity outside (p<0.05) to exclude the neurons that activated indiscriminately or not correlated with the reaching task. Neurons with the average activity in the time window higher than the average outside the time window were considered

movement-related neurons. The neurons were aligned based on each neuron's sorted time of peak event to visualize each and all the neuronal activity patterns during the reaching task. The recurrence of neuronal activities related to the movements was also elevated by pairwise comparison of the population neuronal activity between trials using the Pearson correlation coefficient.

Immunohistochemistry

Four weeks after virus injection, mice were perfused with 50 mL cold PBS buffer (1x) to remove the blood and 50 mL 4% paraformaldehyde (PFA) in PBS to fix the brain tissue. The skull was carefully opened, and the brain was removed from the skull and fixed by immersing it in 4% PFA at 4 °C for 24 hours, then dehydrated in 30% sucrose PBS solution until it sank to the bottom. Brains were covered with OTC, freezing fixed, and sectioned to a thickness of 50 um using a freezing microtome (Leica, German). Brain slices were preserved in an anti-freezing solution (25% glycerol and 30% ethylene glycol, in PBS) and stored in the -80 °C refrigerator.

For immunostaining, the brain slices were washed 3 times using 1 x PBS in a shaker and incubated in blocking solution (10% normal goat serum and 0.2% Triton X-100 in PBS) for more than 1.5 hours in a shaker and incubated with the primary antibody (Mouse anti- GAD67, Millipore; Mouse anti-CaMK2a, Abcam; Mouse anti-mCherry, Invitrogen) in 0.2% Triton and 5% Goat serum in PBS at 4 °C for 24 -36 hours. Slices were washed with PBS four times before incubating with the second antibody (Alexa Fluor 594 conjugated goat anti-mouse, Alexa Fluor 594 conjugated

goat anti-rabbit, Jackson immunity) diluted in 0.1% Triton PBS solution for 3 hours. Finally, slices were washed in 1 x PBS 4 times, then incubated with DAPI (1mg/ml) for 10 min, mounted on slides and sealed with mounting medium (70% glycerol in PBS). Slices were observed and imaged with a confocal laser-scanning microscope (Zeiss, German) using 10 x and 20 x air objectives or 40 x and 60 x oil immersion objectives.

Brain Slice Electrophysiology

The slice electrophysiology experiment was carried out following the methods reported previously (Chen et al., 2019). In the experiments, 6-8 weeks old C57BL/6 or CCK^{-/-} mice were anesthetized with isoflurane in a small chamber. The mouse head was cut, and the brain was rapidly removed and put into an oxygenated (95% O₂-5% CO₂) artificial cerebral spinal fluid (ACSF) cold bath containing 26 mM of NaHCO₃, 2 mM of CaCl₂, 1.25 mM of KH₂PO₄, 1.25 mM of MgSO₄, 124 mM of NaCl, 3 mM of KCl and 10 mM of glucose, pH 7.35–7.45. The brain was sectioned from the middle line into two hemispheres. The portions with the brain areas of the motor cortex were trimmed and glued on the ice-cold stage of a vibrating tissue slicer (Leica VT1000S). Coronal sections of slices containing the motor cortex (300 µm thick) were trimmed and gently transferred into an ACSF containing chamber, which was put in a water bath at 28 °C and oxygen blowing continuously. After 2 hours of recovery in the ACSF bath, the slice was applied for the following electrophysiological recording.

A commercial 4-slice 8 x 8 channels recording system (MED, Panasonic Alpha-Med Sciences) was applied to record the fEPSPs. The MED probe is composed of 64 microelectrodes; the distance between the two channels is 50 x 50 μm , (MED-P515A, 64-channel, 8 x 8 pattern, 50 x 50 μm , inter-electrode distance 150 μm or MED-PG515A).

After recovery, the motor cortex slice was covered by the recording electrodes. A fine-mesh anchor (Warner Instruments, Harvard) was covered on the brain slice to stabilize it, and the probe chamber was perfused with fresh ACSF oxygenated with oxygen with a peristaltic pump (Minipuls 3, Gilson), and the water bath was kept at 32 °C. After 20 min of recovery, one of the microelectrodes in the area of interest was selected as the stimulating electrode through an inverted camera (DP70, Olympus). The surface layer of the motor cortex was stimulated with constant current pulses at 0.1 ms in duration at 0.017 Hz by the connected controlling software, data acquisition software (Mobius, Panasonic Alpha-Med Sciences). After the baseline recording, which was stimulated at the current of that triggering around 50% of the saturating potential. For drug application, CCK4 (final concentration: 500 nM) or vehicle was injected into the electrode dishes. High-frequency stimulation (HFS) (25 bursts at 120 Hz for each burst, at the highest intensity) was applied to the stimulation probe. The electrophysiological data were extracted and analyzed with offline software, Mobius software. For quantification of the LTP data, the initial amplitudes of fEPSPs were normalized and expressed as percentage changes over the averaged baseline activity. The fEPSP was normalized based on the percentage of the baseline potential.

760

761 ***Rescue of the motor learning ability of the CCK^{-/-} mice with CCK4***

762 CCK4, a tetrapeptide derived from the peptide of CCK was selected as a potential
763 drug to rescue the motor learning defect caused by the lack of CCK, because CCK4
764 remains the function to activate the CCK receptor but has a much smaller molecule
765 than CCK8s or CCK58, making it transmit through the brain-blood barrier easily and
766 smoothly (Javanmard et al., 1999; Eser et al., 2009). Therefore, intraperitoneal
767 injection of the CCK4 is a simple and easily available way to rescue CCK lack caused
768 motor learning defects.

769 After shaping, CCK^{-/-} mice were injected intraperitoneally with CCK4 (0.45 mg/kg,
770 Cat# ab141328, Abcam, UK) or vehicle before training every day.

771

772 ***Statistical analysis***

773 Group data were shown as mean ± SEM (standard error of the mean) unless
774 otherwise stated. Statistical analyses, including paired t-tests, one-way RM ANOVA,
775 and two-way mixed ANOVA, were conducted in SPSS 26 (IBM, Armonk, NY).
776 Statistical significance was defined as $p < 0.05$ by default.

777

778 ***Data availability***

779 Data for this submission has been uploaded to the Dryad Digital Repository,
780 <https://doi.org/10.5061/dryad.9ghx3ffms>.

781

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Competing Interest Statement

No competing interest exists in the submission of this manuscript.

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Figures

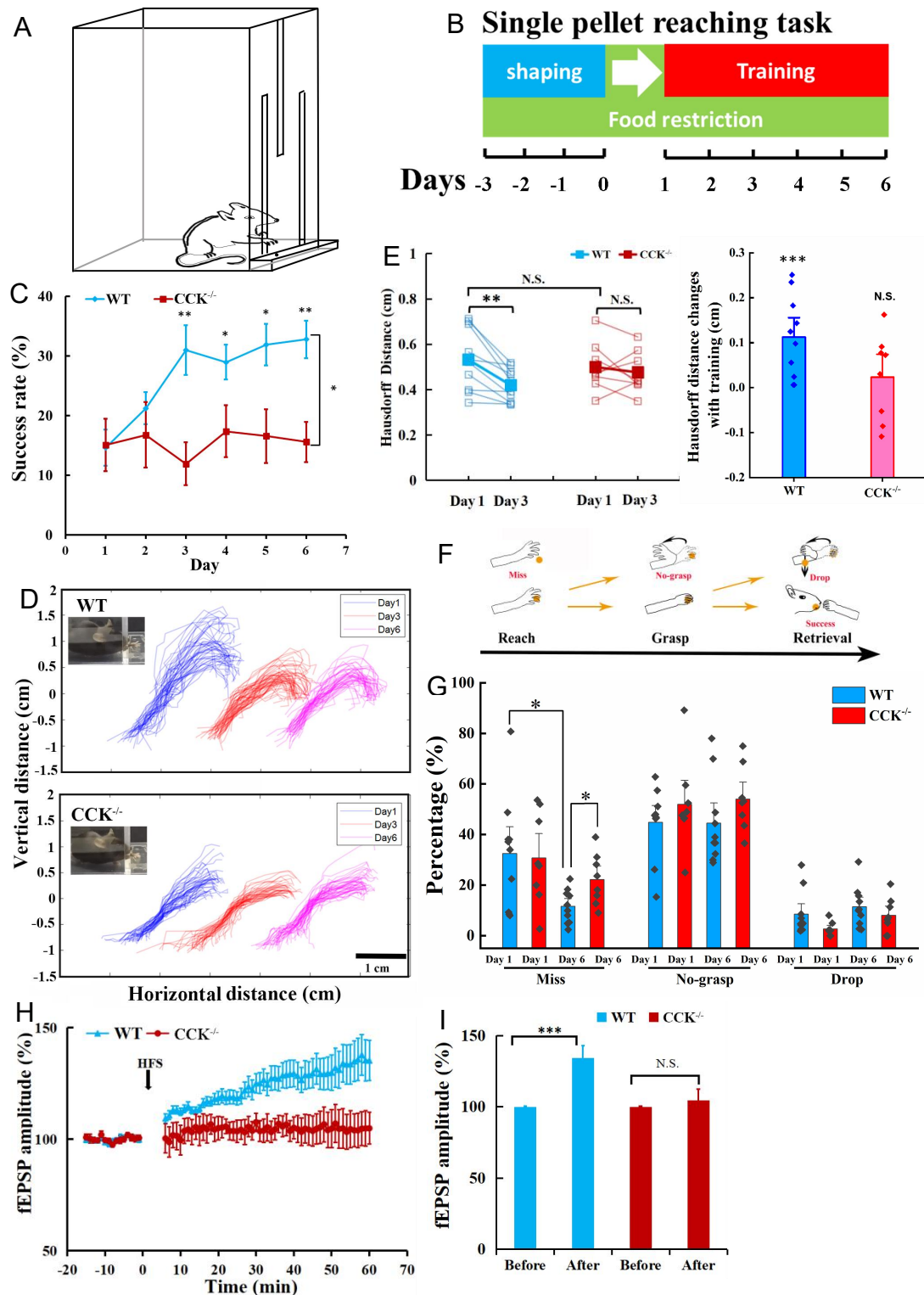


Figure 1. Single pellet reaching task for CCK^{-/-} and WT mice. (A) Task schematic.

A mouse reaches for the food pellet through the slit. (B) Procedure. Three days before

training, the mouse was placed in the chamber and allowed to acclimate to the

environment and determine the dominant hand. Throughout the procedure, the mouse

was food restricted, keeping the body weight at approximately 90% of the original

weight. (C) Success rate of wildtype (WT, C57BL/6) (N = 10) and CCK^{-/-} (N = 8)

mice performing the single pellet reaching task. *p<0.05, **p<0.01. Two-way mixed

ANOVA, post hoc. comparison between two groups. (D) Representative trajectories

of WT and CCK^{-/-} mice at Day 1, Day 3, Day 6. (E) The pairwise Hausdorff distances

of the trajectories were calculated to compare the variation in the trajectories of WT

(N=10) and CCK^{-/-} mice (N = 8). Left, blue and red solid square represent for average

of the Hausdorff distance of WT and CCK^{-/-} mice, respectively. **p<0.01, N.S. means

not significant. Paired t-test. Right, Hausdorff distance changes with 3-day training of

WT and CCK^{-/-} mice. ***p<0.001, N.S. means not significant. t-test. (F) Diagram

shows the task phases (reach, grasp, and retrieval) and different reaching results (miss,

no-grasp, drop, and success). (G) Detailed reaching results for WT and CCK^{-/-} mice

on experimental Day 1 and Day 6. *p<0.05; paired t-test and t-test. (H) Normalized

field EPSP amplitude before and after high frequency stimulation (HFS) for both WT

(N = 6, n = 21) and CCK^{-/-} mice (N = 3, n = 7). (I) The average normalized fEPSP

amplitude 10 min before HFS (-10 - 0 min, before) and 10 min after HFS (50 - 60

min, after) in the two groups of mice. ***p<0.001, N.S. means not significant.

Two-way mixed ANOVA, pairwise comparison.

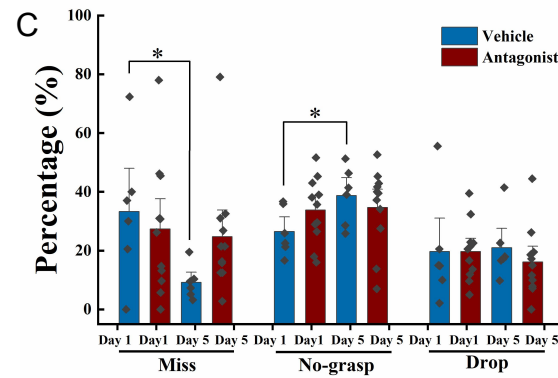
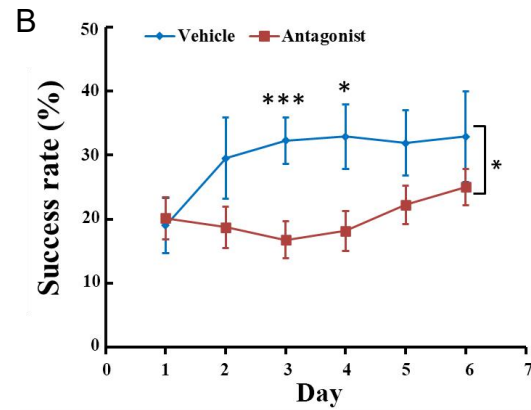
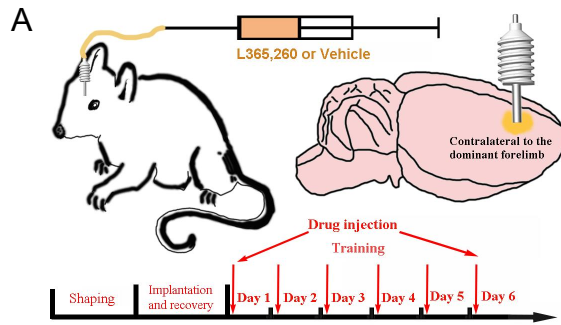


Figure 2. Effect of local injection of CCKBR antagonist on motor learning. (A) A cannula was implanted into the motor cortex contralateral to the dominant hand. One microliter of L365,260 or vehicle was injected into the motor cortex through the cannula every day before training. (B) Success rate of the mice injected with CCKBR antagonist (N = 11) and vehicle (N = 6). * $p < 0.05$, *** $p < 0.001$. Two-way mixed ANOVA, post hoc. comparison between two groups. (C) Detailed reaching results, in terms of miss, no-grasp, drop, on Day 1 and Day 5 for mice injected with CCKBR antagonist and vehicle. * $p < 0.05$, paired t-test.

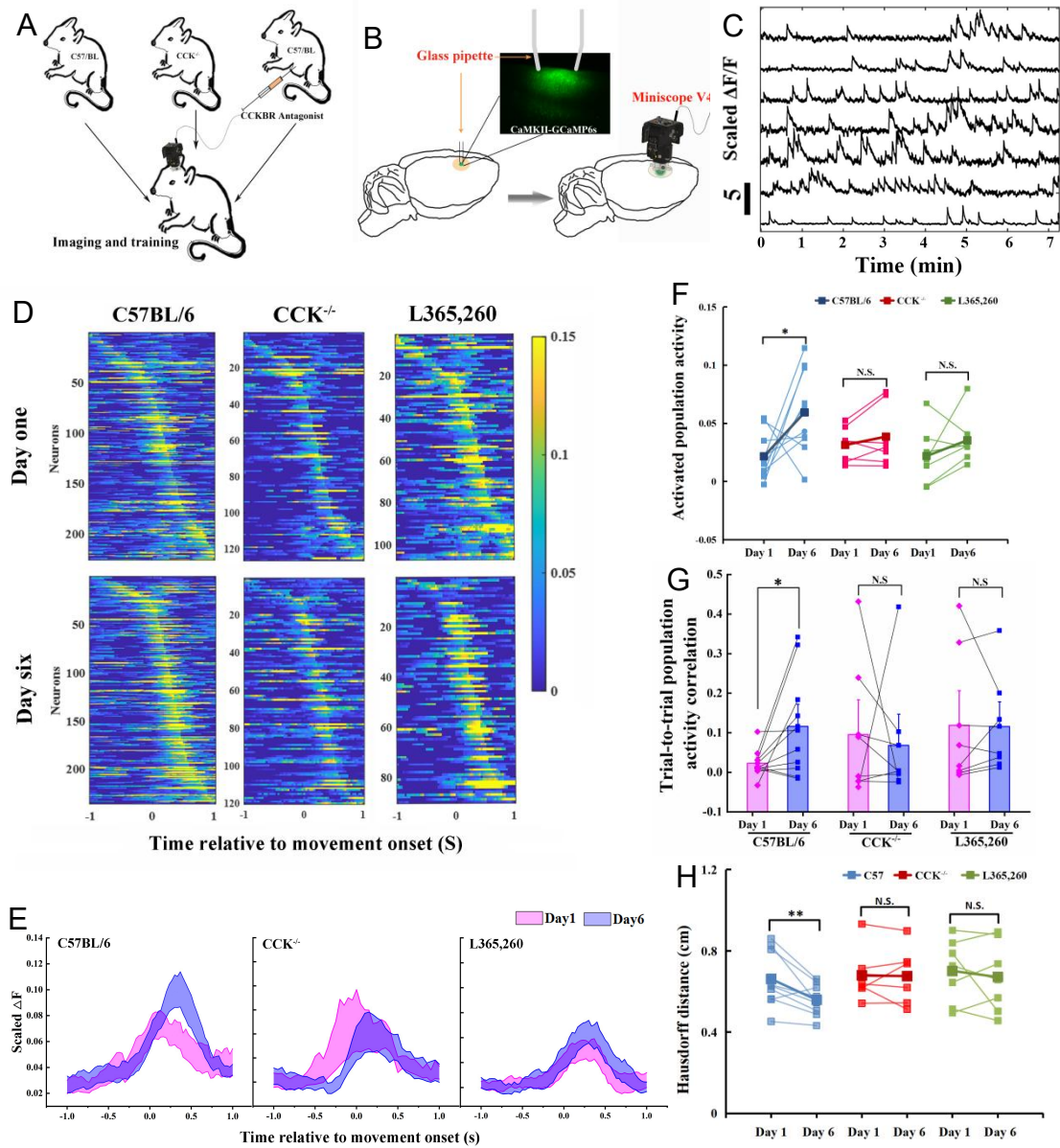


Figure 3. Calcium imaging of the MC during motor skill learning. (A) Experiment set-up. C57BL/6, CCK^{-/-} and C57BL/6 mice injected with CCKBR antagonist were applied for single pellet reaching task training and calcium imaging. (B) Schematic diagram of calcium imaging. A wide-tip glass pipette tightly touched the brain by being lowered to a depth of 400-500 μm , and strong GCaMP6s virus expression was observed in the superficial layer of the motor cortex with a high contrast compared with the deep layers after >14 days of expression. A baseplate was implanted on the skull, which was connected to the miniscope for calcium imaging during motor skills training (right panel). (C) Representative traces of extracted neurons from miniscope using the CNMF-E algorithm. The scale bar represents 5 units of the scaled $\Delta F/F$ (D) Neuronal activity pattern of C57BL/6 (N = 10), CCK^{-/-} (N = 7) and C57BL/6 mice injected with L365,260 (N = 7). Upper line is from training Day 1 and the bottom is from training Day 6. (E) Neuronal population activities from C57BL/6, CCK^{-/-} and C57BL/6 mice injected with L365,260. (F) Activated population activity (peak activity minus baseline activity) was calculated for C57BL/6, CCK^{-/-} and C57BL/6 mice injected with L365,260 at Day 1 and Day 6. * $p < 0.05$, N.S. not significant. Paired t-test. (G) Trial-to-trial population activity correlation at Day 1 and Day 6 for C57BL/6, CCK^{-/-} and C57BL/6 injected with L365,260. (H) The pairwise Hausdorff distances of the trajectories for C57BL/6, CCK^{-/-} and C57BL/6 injected with L365,260 at Day 1 and Day 6. * $p < 0.05$, N.S. not significant. One-way RM ANOVA.

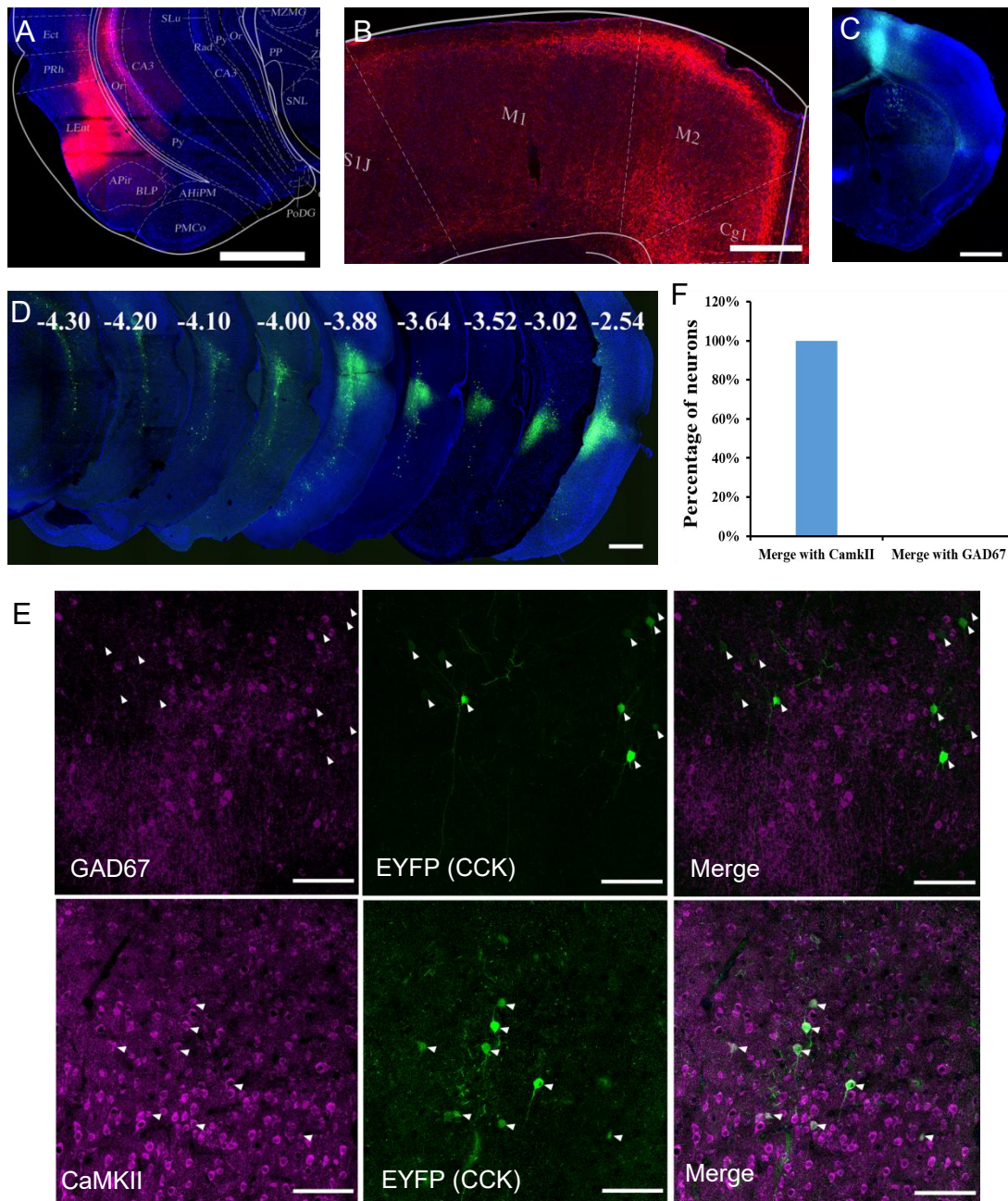


Figure 4. Labeling of CCK neuron projections from the RC to the MC. (A)

Coronal section showing the virus injection site. The Cre-dependent AAV-hsyn-DIO-mCherry virus was injected into CCK-Cre mice. (B) Effective labeling of CCK neuron fibers in the MC. (C) Cre-dependent retrograde AAV virus injection site in the MC of the CCK-Cre mouse. (D) Continuous coronal brain sections showing EYFP in the lateral EC. The numbers (mm) indicate the position of the sections relative to the bregma. (E) GAD67 staining did not merge with the retrograde tracking CCK positive neurons in the EC and CaMKII staining merged with the signal of retrograde tracking CCK neurons EC projecting. Arrowhead indicate the positions of CCK neurons. (F) Percentage of retrogradely labeled neurons merged with CaMKII and GAD67 (n = 3). Scale bars represent 1000 μ m in (A), (B), (C), and (D) and 100 μ m in (E)

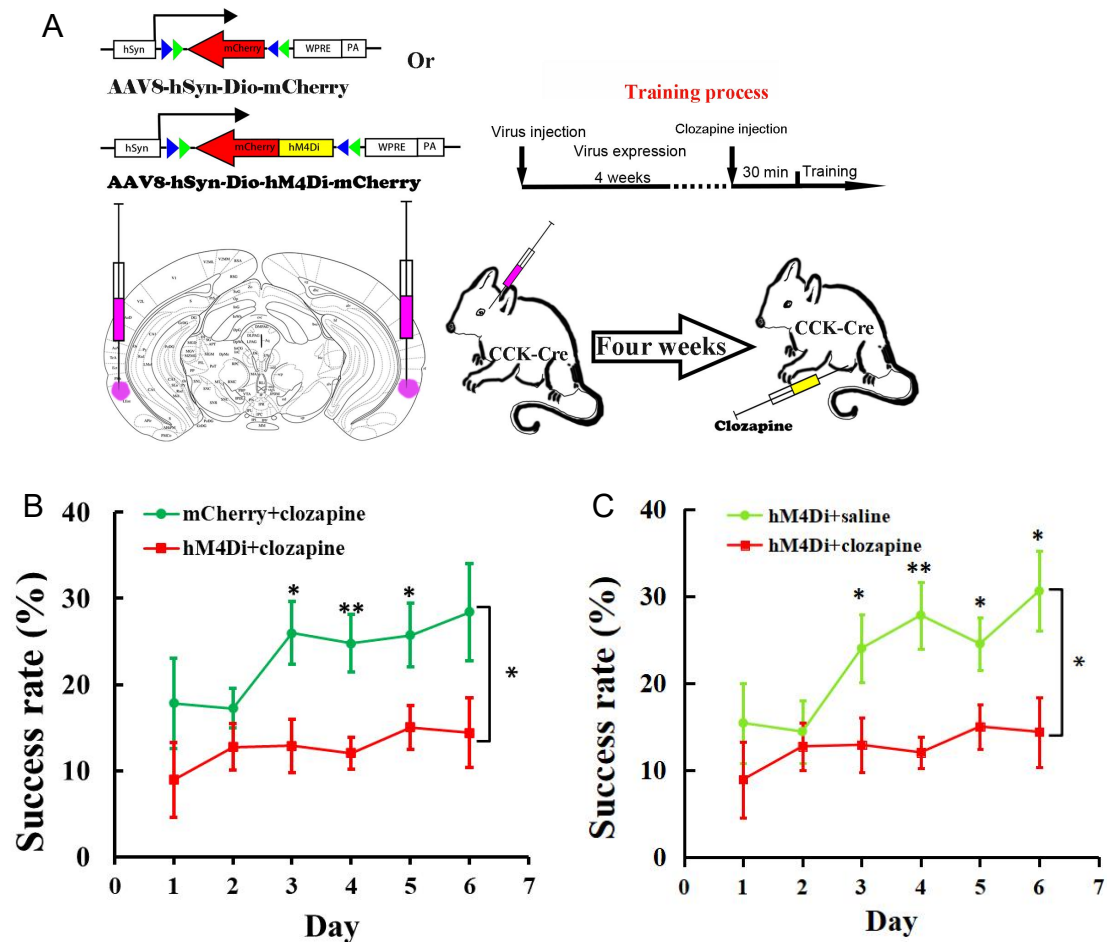


Figure 5. Effect of inhibition of the RC CCK neurons on motor learning. (A)

Experimental paradigm for the chemogenetic experiment. Cre-dependent AAV-DIO-hM4Di-mCherry or AAV-DIO-mCherry was infused into the rhinal cortex of CCK-Cre mice. After four weeks, clozapine or saline was intraperitoneally injected 30 min before training. (B) Success rate of CCK-Cre mice injected with hM4Di containing virus plus clozapine (hM4Di+clozapine) (N = 10) and control virus plus clozapine (mCherry+clozapine) (N = 8). (C) Success rate of CCK-Cre mice injected with hM4Di containing virus plus clozapine (hM4di+clozapine, shared with B) and hM4Di plus saline (hM4Di+saline) (N = 11). The hM4Di+clozapine curve in Figure 5C shared that in B). *p<0.05, **p<0.01. Two-way mixed ANOVA, post hoc. comparison between two groups on different days.

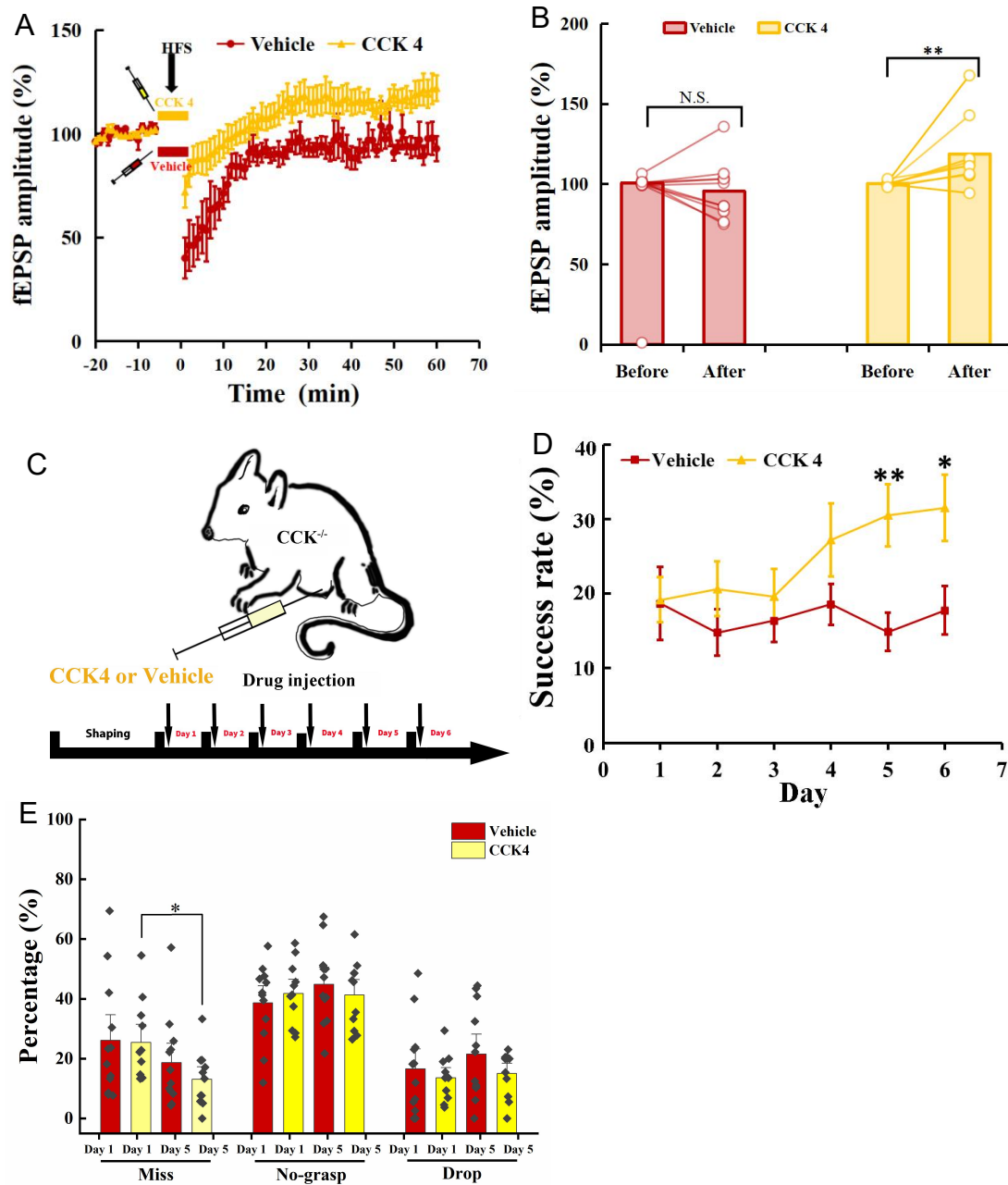


Figure 6. Rescuing the motor learning ability of CCK^{-/-} mice by CCK 4. (A)

Normalized fEPSP amplitude before and after HFS of the MC of CCK^{-/-} mice applied with CCK4 (N = 6, n = 14) or vehicle (N = 6, n = 11). (B) The average normalized fEPSP amplitude 10 min before HFS (-10-0 min, before) and 10 min after HFS (50-60 min, after) in the MC of CCK^{-/-} mice injected with CCK 4 or vehicle. *p<0.05, **p<0.01. Two-way mixed ANOVA with Bonferroni pairwise comparison. (C) Experimental paradigm for CCK rescuing experiment. CCK4 or vehicle was injected (i.p.) every day before training. (D) Success rate of CCK^{-/-} mice injected with CCK4 (N = 11) or vehicle (N = 10). *p<0.05, **p<0.01. Two-way mixed ANOVA, post hoc. comparison between two groups on Day 5 and Day 6. (E) Detailed reaching results of CCK^{-/-} mice injected (i.p.) with vehicle and CCK4 on Day 1 and Day 5. *p<0.05, N.S. not significant. Paired t-test.

Cholecystokinin from the Rhinal Cortex Facilitates Motor Skill Learning

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Author Contributions: Jufang He, Kuan Hong Wang, Hao Li and Jingyu Feng designed the research; Hao Li, Jingyu Feng, and Xi Chen set up behavior model and analysis methods; Hao Li, Mengying Chen and Min Xin carried out the experiments; Hao Li, Xi Chen, Jufang He and Kuan Hong Wang analyzed the data; Hao Li and Jufang He wrote the draft of the manuscript; Hao Li, Jufang He and Kuan Hong Wang edited the manuscript.

Figure S1. Learning curve of single mouse of CCK^{-/-} (A) and Wildtype (B) group

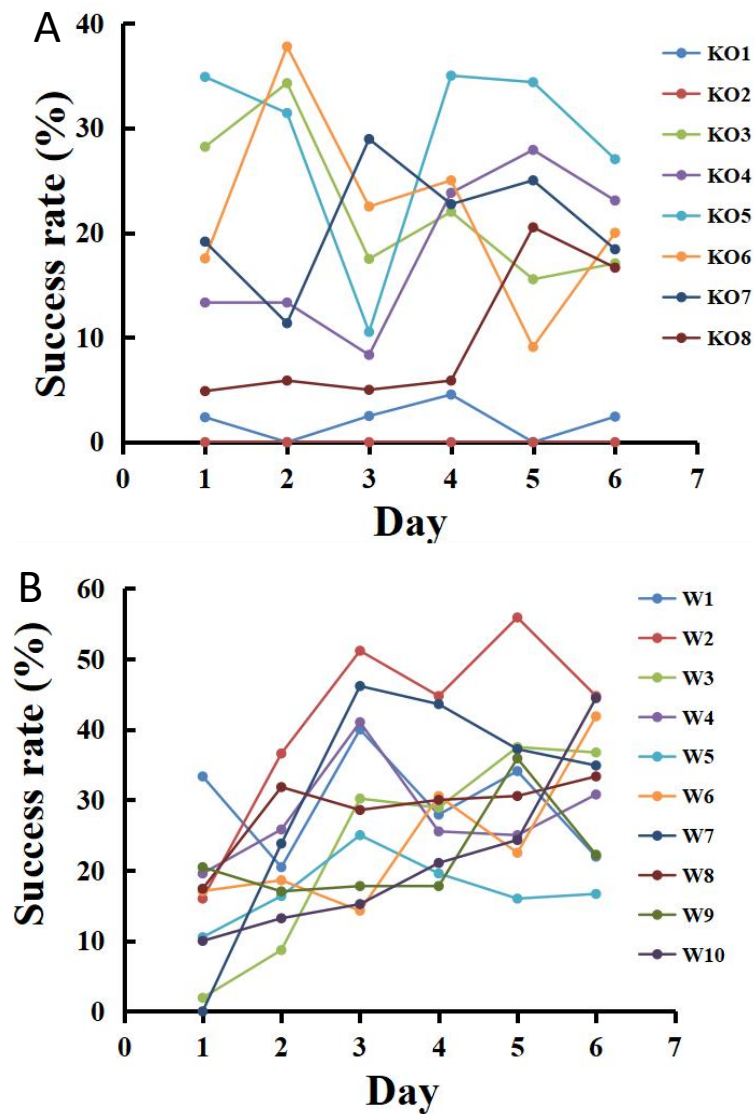
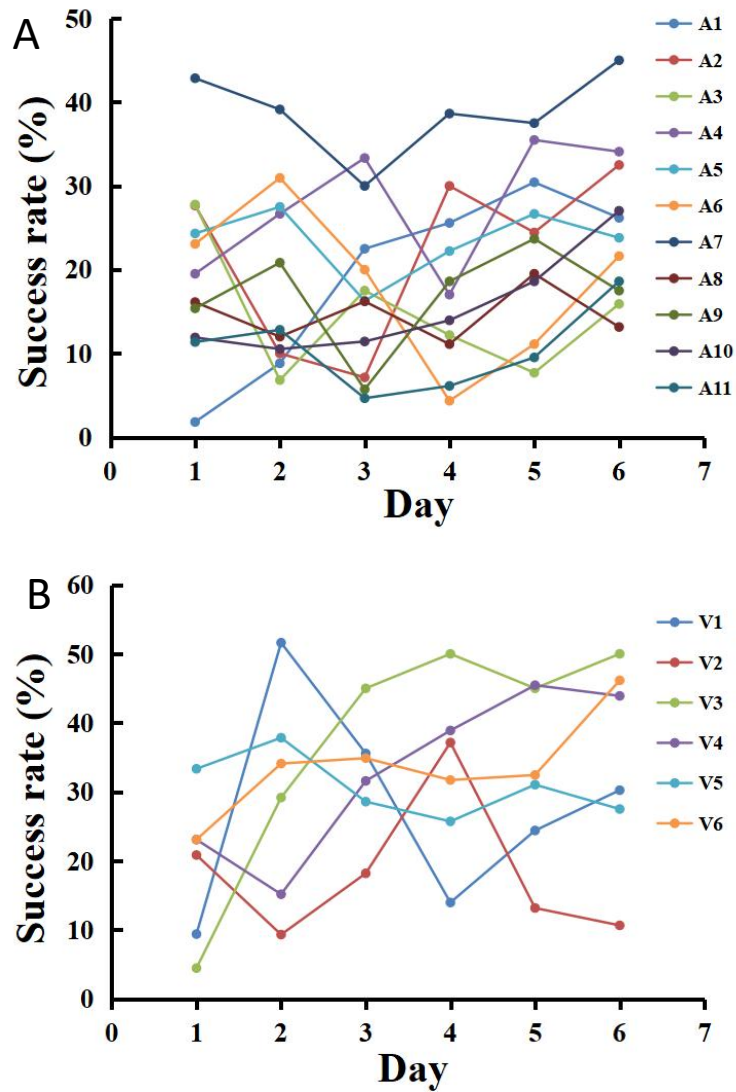
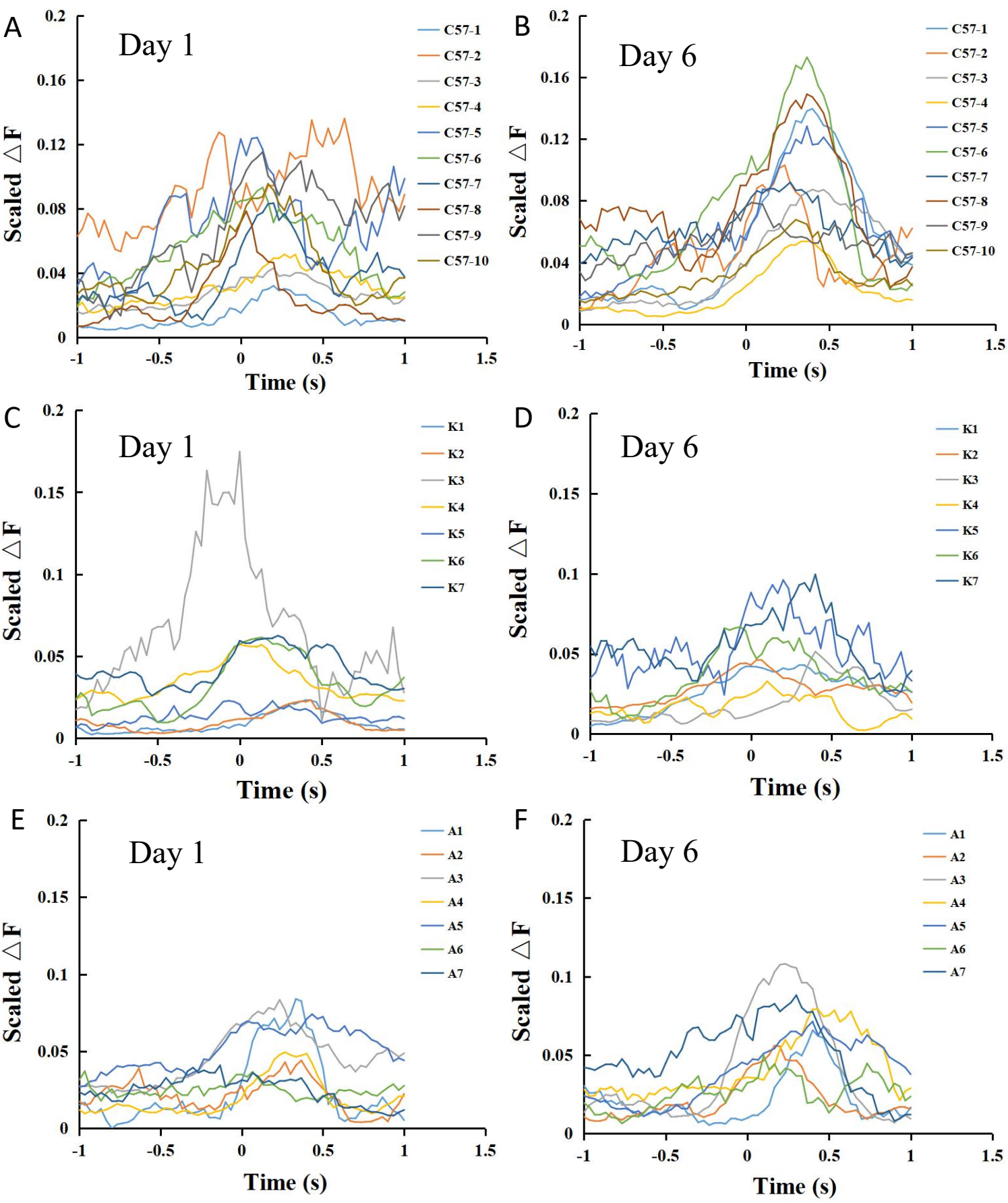


Figure S2. Learning curve of single mouse administrated with CCKBR Antagonist (A) and Vehicle (B).



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Figure S3: Neuronal activity relative to the movement of different groups, including C57BL/6 (A, B), CCK^{-/-} (C, D) and L365,260 injection (E, F) mice at Day 1 and Day 6.



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Figure S4. Learning curve of single CCK-cre mouse injected with hM4Di-clozapine (A), Control-clozapine (B) and hM4Di-saline (C).

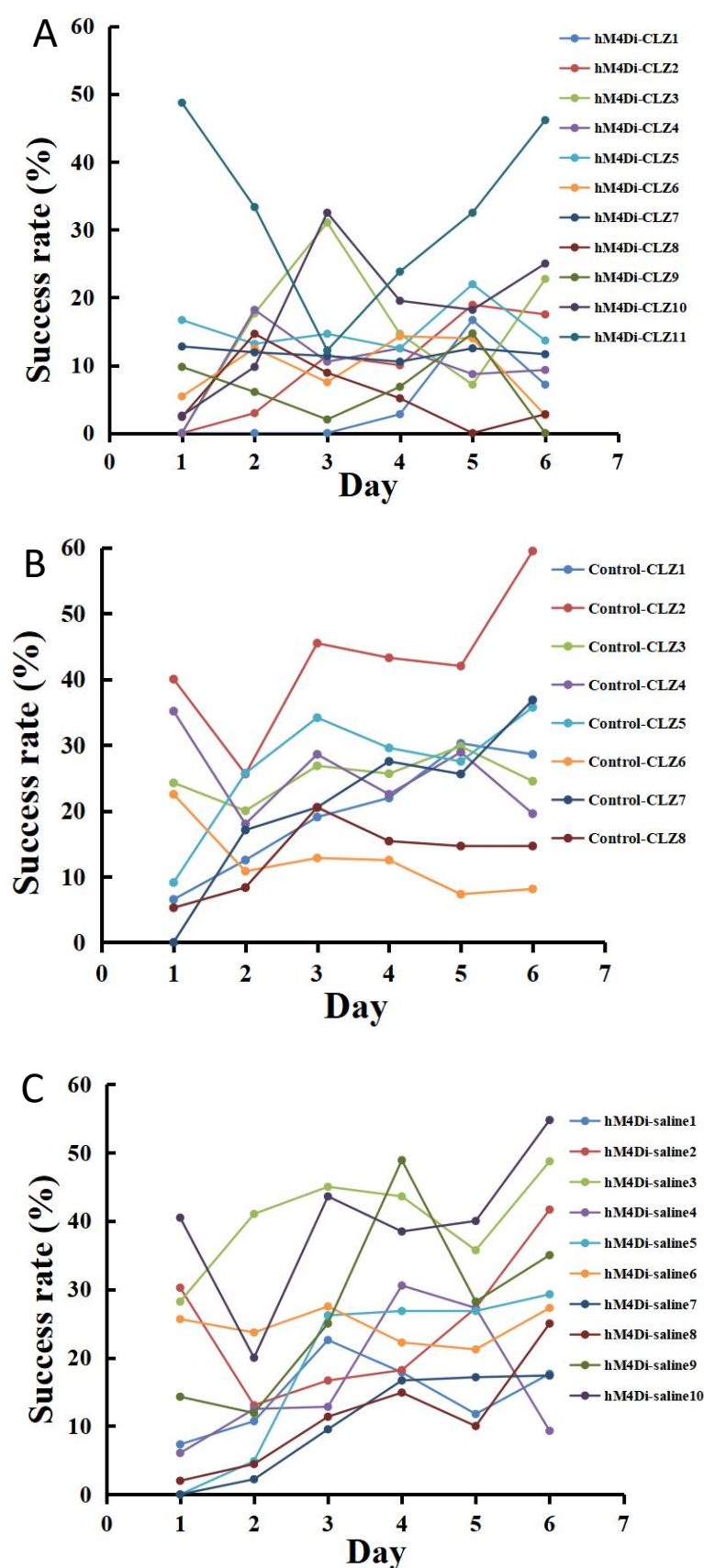


Figure S5. Learning curve of single CCK mouse administrated with Vehicle (A) and CCK4 (B).

