

Mapping mechanical stress in curved epithelia of designed size and shape

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Abstract

The function of organs such as lungs, kidneys and mammary glands relies on the three-dimensional geometry of their epithelium. To adopt shapes such as spheres, tubes and ellipsoids, epithelia generate mechanical stresses that are generally unknown. Here we engineered curved epithelial monolayers of controlled size and shape and mapped their state of stress. We designed pressurized epithelia with circular, rectangular and ellipsoidal footprints. We developed a computational method to map the stress tensor in these epithelia. This method establishes a direct correspondence between epithelial shape and mechanical stress without assumptions of material properties. In epithelia with spherical geometry spanning more than one order of magnitude in radius, we show that stress weakly increases with areal strain in a size-independent manner. In epithelia with rectangular and ellipsoidal cross-section we found pronounced stress anisotropies consistent with the asymmetric distribution of tractions measured at the cell-substrate contact line. In these anisotropic profiles, cell shape tended to align with the direction of maximum principal stress but this alignment was non-universal and depended on epithelial geometry. Besides interrogating the fundamental mechanics of epithelia over a broad range of sizes and shapes, our approach will enable a systematic study of how geometry and stress influence epithelial fate and function in three-dimensions.

MAIN TEXT

Introduction

The internal and external surfaces of the animal body are lined by thin cellular layers called epithelia. Epithelia are active materials that sculpt the early embryo, separate body compartments, protect against pathogenic and physicochemical attacks, and control fluid and biomolecular transport¹. To perform these functions, most epithelia fold into three-dimensional structures that enclose a pressurized fluid-filled cavity called lumen. Some folded epithelia such as the trophectoderm or alveoli are nearly spherical². Others, such as those lining nephrons or blood vessels are tubular^{3,4}. Yet others, like the developing otic vesicle or the early *Drosophila* embryo, are ellipsoidal^{5,6}. In general, epithelia display a combination of shapes and a broad diversity of sizes, with lumens ranging from a few microns to several millimeters⁷⁻⁹. These diverse geometries enable optimal physiological processes and influence cellular fate and function¹⁰⁻¹³.

To adopt their three-dimensional geometry, epithelia generate active mechanical stresses. With the exception of purely spherical epithelia^{8,14,15}, no current technology enables mapping these stresses in 3D in absolute quantitative terms. To fill this gap, here we present an experimental and computational approach to design epithelia of controlled geometry and to map the stress tensor everywhere in the monolayer without assumptions of mechanical properties. Using this approach, we show that the relationship between epithelial tension and strain is largely independent of lumen size. By engineering elliptical and tubular epithelia, we examine the link between the anisotropic stress tensor, cell shape, and cellular tractions.

Results

To design curved epithelia with controlled geometry, we photopatterned soft PDMS (3 kPa Young's Modulus) substrates with low fibronectin density motifs surrounded by high fibronectin areas (Fig. 1a). MDCK cells attached on both high and low fibronectin density areas and formed a flat cohesive monolayer. After 24-48 hours, the monolayer delaminated spontaneously from the low-density motifs to form a fluid-filled lumen. The basal geometry of the lumens closely followed the micropatterned motif, which we hereafter refer to as footprint (Fig. 1b,c). Lumen formation and inflation is driven by the well-known ability of MDCK cells to pump osmolytes in the apico-basal direction^{16,17}, which builds up sufficient osmotic pressure to delaminate cells from the low fibronectin motifs but not from the surrounding high fibronectin areas. This method allowed us to engineer precise lumens with a broader range of sizes and shapes than previous approaches¹⁴.

Using this technique, we investigated the mechanics of epithelial monolayers with circular footprints of diameters 25 μ m, 50 μ m, 100 μ m and 200 μ m. In every case, the epithelial monolayer adopted a dome-like morphology that was well fitted by a spherical cap (Fig. 1b,c). Cell density on the domes did not vary with footprint size (Extended Data Fig. 1). We used traction microscopy to map the three-dimensional traction vectors at the substrate surface. Traction under the suspended dome, which pointed uniformly towards the substrate, are a direct readout of luminal pressure, ΔP . Pressure was balanced by an upwards traction at the contact point between the first ring of cells adhered to the substrate. This out-of-plane traction was not purely tangential to the suspended dome (Fig. 1c), indicating a contribution of the adherent monolayer to the mechanical equilibrium at the contact point.

Thanks to the spontaneous fluctuations in dome volume (Extended Data Fig. 2), we were able to measure luminal pressure for epithelial curvatures spanning more than one order of magnitude (Fig. 1d). Pressure increased linearly with curvature and then tended to plateau, indicating a limit in the pressure that MDCK

monolayers spontaneously build up. We next sought to infer the epithelial stress on the dome monolayer from tissue shape and luminal pressure. To do so, we assumed a membrane state of stress in the monolayer characterized by a symmetric 2×2 tensor, $\bar{\sigma}$ ¹⁴. In spherically symmetric monolayers as domes, cysts, and blastocysts, mechanical equilibrium tangential to the tissue requires that stress is uniform and isotropic¹⁸ and, therefore, $\bar{\sigma}$ is diagonal and has equal diagonal elements σ , which correspond to the surface tension. Mechanical equilibrium normal to the tissue results in Young-Laplace's law, $\sigma = \frac{\Delta P \cdot R}{2}$, where R is taken as the radius at half thickness of the monolayer, from which σ can be computed.

We noticed that the contact angle between adjacent cells is smaller on the apical cellular surface than on the basal one, which indicates higher basal than apical surface tension (Extended Data Fig. 3). This observation prompted us to re-examine our membrane assumption. Indeed, apicobasal differences in tension could give rise to a self-generated bending moment or spontaneous curvature with a potentially relevant contribution to the mechanical balance of lumen pressure beyond Young-Laplace's law¹⁹⁻²². This effect should be size-dependent since spontaneous curvature introduces a length-scale. To answer this question, we quantified with computational 3D vertex models of domes the role of apicobasal asymmetry on inferred stresses using Young-Laplace's law, finding a negligible effect irrespective of dome size and for 9-fold differences in surface tension asymmetry (Supplementary Note 1 and Supplementary Fig. 2). These results support the membrane assumption in the context of stress inference for tense epithelial domes.

We then studied how σ varies with areal strain ε_a , defined as the change in tissue area normalized by the area of the footprint, for each footprint size, focusing on the range $\varepsilon_a < 100\%$ (Fig. 1e). Data were highly scattered, with comparable values for mean and standard deviation. Upon averaging over several domes and time points, we observed that σ weakly increases with ε_a , consistent with the low-strain behavior we had previously defined as active superelasticity¹⁴. Remarkably, the stress-strain relationship did not depend on the footprint size. This result indicates that for a broad range of sizes, curvature does not trigger mechanosensing feedback loops that impact the magnitude of epithelial tension significantly.

Whereas Young-Laplace's law provides an exact expression of stress in spherical monolayer membranes, epithelia generally deviate from perfectly spherical geometries. We thus sought to develop a general formalism to map the full stress tensor in monolayers of arbitrary size and shape. This approach, which we call curved Monolayer Stress Microscopy (cMSM), accounts for the two tangential equilibrium equations used in standard (planar) stress inference methods²³⁻²⁸ and further exploits the equation of out-of-plane force balance available in the presence of curvature (Extended Data Fig. 4). Thus, unlike planar stress inference, with an equal number of equations and unknowns it is possible in principle to determine the three independent components of the stress tensor without any assumptions about material behavior other than a membrane state of stress. The formulation of cMSM, its finite element implementation, the criteria to select regularization parameters, and a thorough verification of the method is available in Supplementary Note 2.

We applied this force inference method to domes that deviate from a spherical cap. First, we photopatterned substrates with rectangular footprints of same cross-sectional area but different ratios between long and short axis lengths, ranging from 1 (square) to 4 (Fig. 2). Like spherical domes, epithelia delaminated from the footprints and formed caps and tubes with slowly fluctuating levels of inflation (Fig. 2a). We then inferred the stress tensor from the measured luminal pressure and monolayer geometry. To visualize it, we computed the mutually orthogonal principal directions of stress and the principal stresses $\sigma_{1,II}$ along these directions. We plotted the hydrostatic or mean surface tension, $\sigma_1 + \sigma_{II}$, as a colormap and the principal stresses as converging (negative) or diverging (positive) pairs of arrows along their corresponding directions. The tension maps inferred by cMSM exhibited spatial variability associated with specific geometric features of

dome surfaces, but also systematic patterns such as markedly uniaxial stresses parallel to the short axis of the dome (Fig. 2b).

To validate cMSM, we reasoned that the traction component normal to the substrate at the contact line between the suspended monolayer and the substrate, T_z , should match closely the normal traction computed from the inferred stress on the suspended monolayer at that point (Fig. 2c). We tested these predictions as a function of epithelial inflation and footprint aspect ratio (Fig. 2d,e). Note that $\bar{\sigma}$ has units of tension and thus needs to be divided by a length l_T to compare it with T_z . This length should be understood as the thickness of the band lining the footprint over which tension in the suspended epithelium is transmitted to the substrate. We found $l_T = 15.7\mu m$ (methods), of the order of one cell diameter. As expected, the experimental values of T_z were equal on all sides of squares and increased with inflation (Fig. 2d), closely matching the inferred tractions (Fig. 2e). For rectangles, T_z was higher along the long axis (Fig. 2d), again in close agreement with the inferred tension map (Fig. 2e), and inflation tended to increase T_z . Together, these data establish a close agreement between the inferred and measured stress at the contact point between the dome and the substrate, supporting the validity of our stress inference method.

To study systematically the effect of curvature on inferred stress we designed epithelia with an elliptical footprint and two different eccentricities (aspect ratios 1:3 and 2:3). In agreement with domes with rectangular footprints, stress was anisotropic, with the maximum principal stress direction predominantly parallel to the short axis of the ellipse (Fig. 3b, see Extended Data Fig. 5 for additional domes). We then measured T_z as a function of the polar angle along the elliptical footprint, θ . For shallow domes, T_z slightly depended on θ (Fig. 3c). As inflation levels grew, T_z increased and became progressively anisotropic, with higher values of traction along the less curved regions of the ellipse. This behavior was more pronounced in domes of higher eccentricity. We next compared these experimental values with those predicted by our force inference method, using the experimentally measured geometry and luminal pressure as the sole input variables. cMSM predictions matched closely the experimental T_z , capturing the magnitude as well as its dependence on dome inflation, footprint eccentricity and polar angle (Fig. 3d). The agreement was more pronounced at higher levels of inflation, where the assumption of membrane stress was more robust and the estimation of dome shape was more precise.

We finally asked whether the inferred stress was predictive of cell orientation, as previously observed in 2D^{23,29,30}. We segmented cells in the domes and fitted the shape of each cell to a 2D ellipse on the dome plane (Fig. 4a). We then computed the angle α between the longest axis of the ellipse and the maximum principal stress direction (Fig. 4b) and plotted the distribution of α for domes of high and low eccentricity. Data were binned according to the position of the cell center in the dome (top vs side and major vs minor axis regions, Fig. 4c,d). Both for high and low eccentricity, the angular distributions in the minor axis region (top and side) and in the major axis top region were skewed towards small angles, indicating a predominant alignment between maximum principal stress and cell elongation. Interestingly, the angular distributions of cells located in the major axis side region were skewed towards high angles. In these regions, maximum stress tended to be normal to the long axis, whereas cells tended to be parallel to it (Fig. 4a). Thus, dome shape imposes seemingly contradicting mechanical constraints, as force balance requires maximum stress to be in one direction but kinematics requires cell elongation in the perpendicular direction, suggesting that alignment between cell elongation and maximum stress is not a fundamental biomechanical principle.

Discussion

The past decade has seen the development of numerous techniques to measure mechanical stresses in epithelial tissues including laser ablation³¹, FRET tension sensors³², droplet inserts³³, monolayer stress

microscopy²³, cantilevers³⁴, and stress inference methods³⁵. Whereas each of these techniques has advantages and limitations (discussed in refs 36,37), none of them enables mapping the stress tensor in curved epithelia in absolute quantitative terms. Here we filled this gap by combining experimental and computational tools to design epithelia of arbitrary geometry and to map their luminal pressure and stress tensor. As a proof of concept, we used MDCK cell domes of spherical footprint to show that the relationship between stress and strain is largely independent of epithelial curvature, indicating that within the range of lumen size considered in this study, curvature is not mechanotransduced into changes in tension^{38,39}. Using epithelia with elliptical footprint, we showed that cells tend to align with the direction of maximum principal stress, as previously observed in 2D monolayers^{23,29,30}, but this alignment was not universal and depended on geometry.

To map stresses on surfaces of arbitrary geometry, we developed a force inference method based solely on the measured geometry of the epithelium and luminal pressure. The method, which we call cMSM, uses the two tangential equilibrium equations (as in conventional 2D force inference²³⁻²⁸) and the normal equilibrium equation (à la Young-Laplace) to infer the three independent components of the epithelial stress tensor. Hence, unlike in planar stress inference, it does not require knowledge of the material properties of the monolayer. The only assumption of our approach is that the epithelium behaves as a 2D membrane, i.e. that it supports a two-dimensional state of stress. We tested the validity of this core assumption of the method using a 3D vertex model, which showed that a large apico-basal asymmetry has negligible effect on the inferred monolayer stress. In principle, in highly columnar and polarized monolayers, bending moments could play a stronger effect, but this situation is rare in epithelia surrounding pressurized lumens. In cMSM, epithelial shape allows us to infer the stress pattern whereas pressure provides the stress scale. Hence, in experimental conditions where both epithelial shape and pressure can be measured, as in the present study, cMSM enables an absolute quantification of the stress tensor. In situations where geometry but not pressure can be measured, as is often the case *in vitro* and *in vivo*, cMSM can still provide quantification of epithelial stress up to a scaling factor. Therefore, our technique is of general applicability beyond the highly controlled conditions reported in this study.

To validate our technique, we designed tubular caps of different aspect ratio and elliptical caps of different eccentricity. In these geometries, the stress field inferred by cMSM was anisotropic, with higher values in the direction parallel to the short axis of the tubes and ellipsoids. These inferred anisotropic stresses were in close agreement with normal tractions at the contact line between the free-standing epithelium and the substrate. For rectangular footprints, we found that normal tractions were higher along the long axis of the rectangle. For elliptical footprints, we found a close match between inferred stress and normal traction all along the contact line and as a function of local footprint curvature. Moreover, normal tractions increased with inflation, in agreement with inferred stresses. Together, these data provide a validation of our method showing that a direct measurement of monolayer shape and luminal pressure, together with the equations of mechanical equilibrium, suffice to infer the 2D stress tensor on a curved monolayer.

The shape of epithelia *in vivo* is often influenced by the presence of a basement membrane, by adjacent mesenchymal cells and smooth muscle, and by local bending moments and buckling instabilities⁴⁰⁻⁴³. Here we designed an approach that purposely ignores each of these confounding factors in order to study the behavior of the isolated free-standing monolayer under tight mechanical control. Additional mechanical elements such as localized bending moments can be readily added to the system through optogenetic approaches⁴⁴⁻⁴⁶ or controlled deposition of extracellular matrix⁴⁷. Through the approach presented here, fundamental questions of how epithelial shape and stress anisotropies influence epithelial functions such as division^{48,49}, extrusion^{50,51}, intercalation⁵² and stemness¹³ can now be addressed quantitatively. The relations

between shape, pressure and stress identified here can be used for the rational design of organoids and organ-on-a-chip systems based on epithelial layers^{53,54}.

Materials and Methods

Fabrication of soft silicone gels

Soft silicone gels were prepared using a protocol based on previous publications⁵⁵⁻⁵⁸. Briefly, the silicone elastomer was synthesized by mixing a 1:1 weight ratio of CY52-276A and CY52-276B polydimethylsiloxane (Dow Corning Toray). After degassing for 30 min in ice, the gel was spin-coated on glass-bottom dishes (35-mm, no. 0 coverslip thickness, Mattek) for 90 s at 400 r.p.m. The samples were then cured at 65°C overnight. The substrates were kept in a clean and dry environment and they were used within 8 weeks of fabrication.

Coating the soft PDMS substrate with fluorescent beads

After curing, a thin PDMS stencil with an inner diameter of 7 mm was placed on top of the soft PDMS gels. The region in the stencil was treated with (3-aminopropyl)triethoxysilane (APTES, Sigma-Aldrich, cat. no. A3648) diluted at 5% in absolute ethanol for 3 min, rinsed 3 times with ethanol absolute and rinsed once with type 1 water. Samples were incubated for 1h with a filtered and sonicated solution of red fluorescent carboxylate-modified beads (FluoSpheres, Invitrogen) of 100nm (220nm filter) or 200nm diameter (450nm filter) in sodium tetraborate (3.8 mg/ml, Sigma-Aldrich) and boric acid (5 mg/ml, Sigma-Aldrich). Next, gels were rinsed 3 times with type 1 water.

Passivation of soft PDMS substrates

After coating, soft PDMS gels were incubated with a solution of 1% poly-L-lysine (P2636, Sigma-Aldrich) diluted in type 1 water for 1 h. Next, the gels were rinsed 4 times with a 10mM HEPES (1M, Sigma-Aldrich) solution with pH in the range 8.2-8.4 and incubated with a 50 mg/ml dilution of PEG-SVA (Laysan Bio) in this pH-adjusted 10mM HEPES for 1 h. Then, samples were rinsed 4 times with type I water and stored at 4°C with type I water until photopatterning. All samples were used within 48 hours of passivation.

Protein photopatterning on soft PDMS

Photopatterning of soft PDMS gels was performed using the PRIMO optical module⁵⁹ (Alvéole) controlled by the Leonardo plugin (Alvéole) mounted on a Nikon inverted microscope (Nikon Instruments) equipped with a Super Plan Fluor $\times 20$ ELWD lens (Nikon) and a DMD-based UV (375 nm). Before starting, the liquid on each sample was carefully aspirated (without letting the sample dry) and the sample was covered with PLPP photoactivator (Alvéole). The desired patterns for photoillumination were created using Inkscape (Inkscape Project) and loaded into Leonardo. The UV dose of all samples was set to 900 mJ/mm². After photopatterning, samples were rinsed 4 times with phosphate-buffered saline (PBS, Sigma-Aldrich), incubated for 5 min with a 0.02% fibronectin (F0895, Sigma-Aldrich) solution in PBS and rinsed thoroughly 5 times with PBS. For timelapse imaging experiments, filtered (220nm filter) Alexa Fluor 647 conjugated fibrinogen was added to the fibronectin solution to allow visualization of the micropattern. Samples were stored at 4°C until use (less than 48 h).

Soft PDMS stiffness measurements

Gel stiffness was measured as previously described¹⁴. Briefly, a large 1mm-diameter metal sphere of known mass was used to generate an indentation on the non-photopatterned gels. Then, the depth of the indentation was quantified using confocal microscopy. Using the indentation depth and the sphere mass, we computed Young's modulus by applying Hertz theory and correcting for the finite thickness of the gel⁶⁰. The resulting Young's modulus was 2.9 ± 0.7 kPa (mean \pm SD, n=16). Repeating the same measurements on photopatterned

gels shows that stiffness was not affected by photoillumination (3.1±0.8 kPa, mean±SD, n=15, Extended Data Fig. 6).

Cell seeding

Before cell seeding, soft PDMS gels were exposed to sterilizing UV light for 15 min inside of the culture hood and then incubated with cell medium for 10 min. The medium was removed and 50 μ l of new medium containing ~180,000 cells were placed inside of the stencil. Fifty minutes after seeding, the samples were washed using PBS to remove the non-attached cells and 1-2 ml of medium were added. Cells were seeded between 20 and 60h before experiments (depending on dome size).

Cell density calculation

To quantify cells in the dome, maximum projections of domes were obtained using Fiji⁶⁵. Then the number of cells in the dome (C_{in}) and of those partially in of the dome but in contact with the substrate (C_{bound}) were manually counted for each dome (n=8 for each dome size). To compute cell density, the following formula was used: Density = $(C_{in} + C_{bound}/2)/A$, where A is the 2D area of the dome footprint.

Three-dimensional traction microscopy

Three-dimensional traction forces were computed using traction microscopy with finite gel thickness^{61,62}. The fluorescent beads coating the gel surface were imaged using 12 μ m-thick confocal stacks with a z-step of 0.2 μ m. Images of every experimental timepoint were compared to a reference image obtained after cell trypsinization. From these images, 3D displacement fields of the top layer of the gel were computed using home-made particle imaging velocimetry software, based on an iterative algorithm with a dynamic interrogation window size and implementing convergence criteria based on image intensity as described in previous publications^{14,63}.

Cell culture

All experiments were performed using a MDCK strain II line expressing CIBN–GFP–CAAX to visualize the plasma membrane. Cells were cultured in minimum essential medium with Earle's Salts and l-glutamine (Gibco) supplemented with 10% v/v fetal bovine serum (FBS; Gibco), 100 μ g/ml penicillin and 100 μ g/ml streptomycin. Cells were maintained at 37 °C in a humidified atmosphere with 5% CO₂. The cell line was obtained by viral infection of CIBN–GFP–CAAX. The cell line tested negative for mycoplasma contamination.

Time-lapse microscopy

Multidimensional acquisition for traction force measurements was performed using an inverted Nikon microscope with a spinning disk confocal unit (CSU-W1, Yokogawa), Zyla sCMOS camera (Andor, image size 2,048 × 2,048 pixels) using a 40 x 0.75 NA air lens (Nikon). The microscope was equipped with temperature and CO₂ control and controlled using Micro-manager software⁶⁴.

Areal strain calculation

Areal strain of the dome was computed as $\varepsilon_a = (h/a)^2$, see ref. 14.

Estimation of vertical traction from stress inference

We calculated l_T as $l_T = \tilde{\sigma}_{rz}/\tilde{T}_{rz}$, where $\tilde{\sigma}_{rz}$ is the median tension at the boundary for rectangular domes and \tilde{T}_{rz} is the median experimental traction of rectangular domes. We obtained $l_T = 15.7 \mu\text{m}$.

Dome shape segmentation

The luminal surface of domes was extracted by fitting a smooth surface to the point cloud representing the basal cell faces (Supplementary Note 2). The three-dimensional point cloud was obtained by manually adding points to the x-y, y-z, and x-z slices from the image stack using a custom Matlab code. The basal

footprint was segmented first using *x*-*y* slices. Then, *y*-*z* and *x*-*z* slices spaced about 7.5 μ m apart were processed.

Cell segmentation

Cellular segmentation was carried out with Cellpose, a Python-based cell segmentation plugin⁶⁶. For each *z* plane, cells were automatically segmented using a diameter of 100 pixels and then manually corrected. 2D segmentations from all planes were stitched together and cellular shape was extracted using home-made Matlab software.

Statistical analysis

Comparisons between each group of unpaired samples were computed using the unpaired two-sided Wilcoxon rank sum test. Comparisons between groups of paired samples (long vs short sides in rectangular domes) were computed using the paired two-sided Wilcoxon rank sum test. For domes with elliptical footprint, 95% confidence intervals were computed by bootstrapping of the median with 10⁴ replicates, using the “boot” function in R. For cell orientation data, the median of α distributions was compared to that of 10⁴ uniform distributions generated by MATLAB. P-value was calculated as the number of times the median of a random uniform distribution was below that of our distribution.

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Author contributions

AM-L, MA and XT conceived the project. AM-L performed experiments and analyzed data. AO, AT-S developed software and performed simulations. SK and MA conceived and implemented the force inference method. RS developed tools for surface micropatterning and statistical methods. EL and MG-G developed software for traction calculation and image analysis. PR-C contributed technical expertise, materials, and discussion. AM-L, SK, AO, MA, XT wrote the manuscript. SK, MA and XT supervised the project.

Competing interests

Authors declare that they have no competing interests.

Data and materials availability

Data and materials included in this paper may be requested from the authors.

Code availability

The cMSM code along with experimental datasets are included in this submission.

Figures

Figure 1

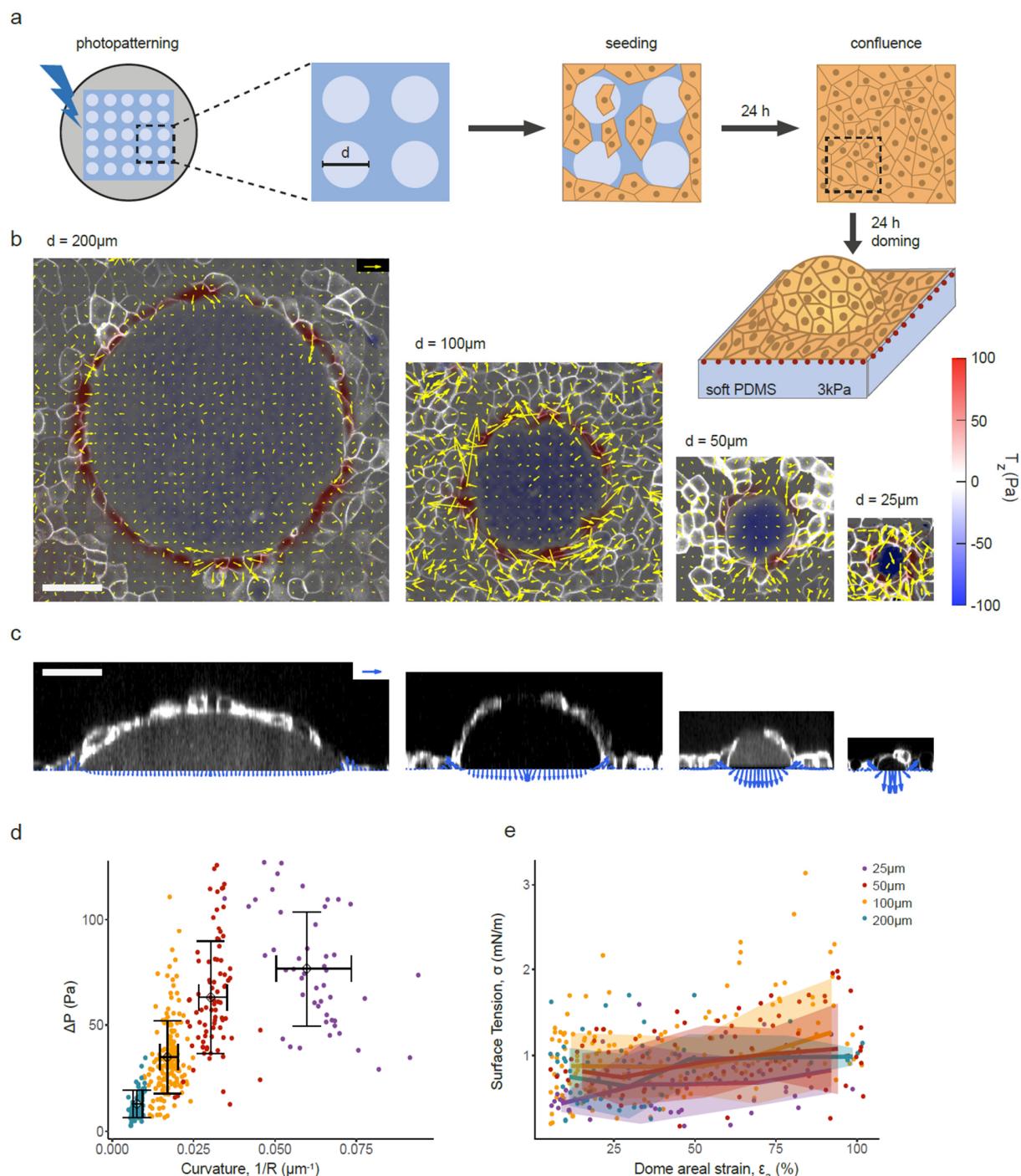


Figure 1. Scaling of tension and pressure in spherical domes.

a, Scheme of substrate photopatterning, cell seeding and dome formation. **b**, 3D traction maps overlaid on top views of representative MDCK domes of 200 μm , 100 μm , 50 μm and 25 μm pattern in diameter (from left to right). Yellow vectors represent in-plane horizontal components T_x and T_y and the color map

represents the vertical component T_z . **c**, Traction overlaid on lateral views of the domes shown in b. Traction were averaged circumferentially for plotting. Scale bars, 50 μ m. Scale vectors, 100 Pa. **d**, Dome pressure as a function of dome curvature. Data shown as mean \pm SD of n=12 domes (25 μ m), 11 domes (50 μ m), 17 domes (100 μ m) and 13 domes (200 μ m) at different levels of inflation. Color coding indicates the footprint diameter (see legend in panel e). **e**, Surface tension in the free-standing sheet as a function of nominal areal strain of the dome. The line and shaded area indicate mean \pm SD by binning the data (equally spaced bins with $n \geq 3$ points per bin). Number of domes is the same as in panel d.

Figure 2

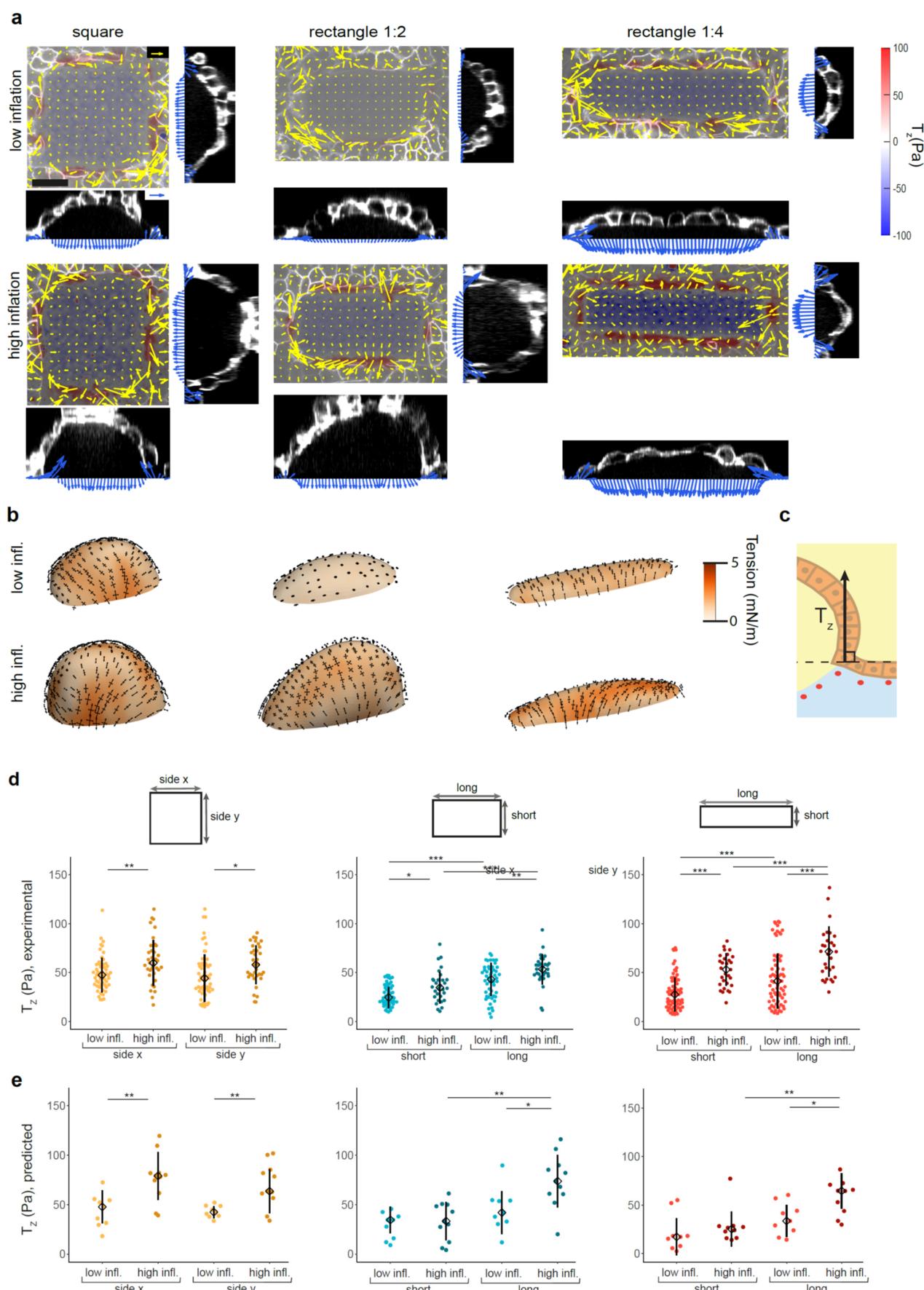


Figure 2. Stress in domes with squared and rectangular cross-section.

a, Traction maps of rectangular domes with different aspect ratios (from left to right, 1:1, 1:2 and 1:4 aspect ratios) and inflation levels (low inflation, top row; high inflation, bottom row). Each one of the six panels comprises a top view (center) and two lateral views (right and bottom). The top view shows a 3D traction map, where yellow vectors represent the in plane (T_x , T_y) components and the color map represents the vertical component T_z . The lateral views show the tractions averaged over the central region of the dome footprint. Scale bar, 25 μ m. Scale vector, 50 Pa. **b**, Inferred stress tensor on the free-standing cell layer of the domes shown in **a**. The black arrows represent the two principal components of the inferred stress. **c**, Schematic of the vertical traction component T_z at the cell-substrate interface. **d**, Experimental vertical tractions at the short and long sides of domes with low and high inflation levels. The tractions were averaged along the central 50% of the dome sides. Data are shown as median \pm SD of n=53 (square low), 35 (square high), 50 (rect. 1:2 low), 30 (rect. 1:2 high), 69 (rect. 1:4 low), 29 (rect. 1:4 high). **e**, Vertical tractions at the short and long sides of domes with low and high inflation levels obtained with cMSM. The tractions were averaged along the central 50% of the dome sides. Data are shown as median \pm SD of n=9 (square low), 11 (square high), 8 (rect. 1:2 low), 12 (rect. 1:2 high), 9 (rect. 1:4 low), 10 (rect. 1:4 high). Statistical significance was determined using the Wilcoxon rank sum test for paired and unpaired samples. Only statistically significant pairwise comparisons are indicated. * P < 0.05, ** P < 0.01 and *** P < 0.001.

Figure 3

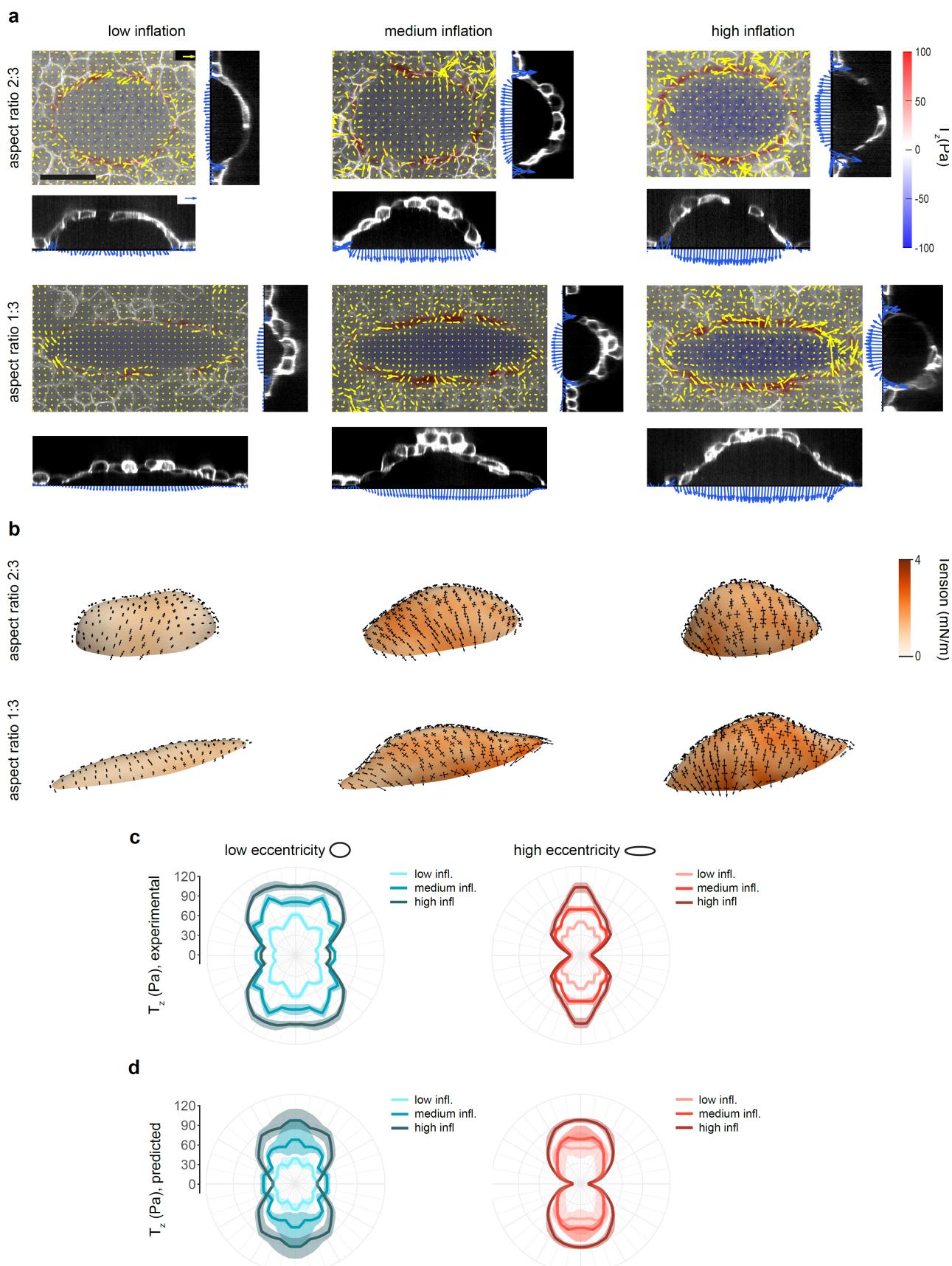


Figure 3. Stress in ellipsoidal domes.

a, Traction maps of ellipsoidal domes with different aspect ratios (2:3 top and 1:3 bottom) and inflation levels (from left to right). Each one of the six panels comprises a top view (center) and two lateral views (right and bottom). The top view shows a 3D traction map, where yellow vectors represent the in plane (T_x , T_y) components and the color map represents the vertical component T_z . The lateral views show the tractions averaged over the central region of the dome footprint. Scale bar, 50 μm . Scale vector, 50 Pa. **b**, Inferred stresses on the free-standing cell layer of domes shown in **a**. The black arrows represent the two principal components of the inferred stress. **c**, Experimental vertical tractions at the dome-substrate interface for low, medium and high inflation levels. Left: low eccentricity, $n=11$ (low), 16 (medium), 23 (high). Right: high eccentricity, $n=15$ (low), 30 (medium), 16 (high). The tractions are shown after averaging in the four quadrants of the ellipses, taking advantage of the symmetry of the system. **d**, Vertical tractions inferred at the dome-substrate interface using cMSM for low, medium and high inflation levels. Left: low eccentricity, $n=6$ (low), 9 (medium), 8 (high). Right: high eccentricity, $n=8$ (low), 8 (medium), 8 (high). The line and shaded area indicate median and 95% CI of the median by bootstrapping (methods).

Figure 4

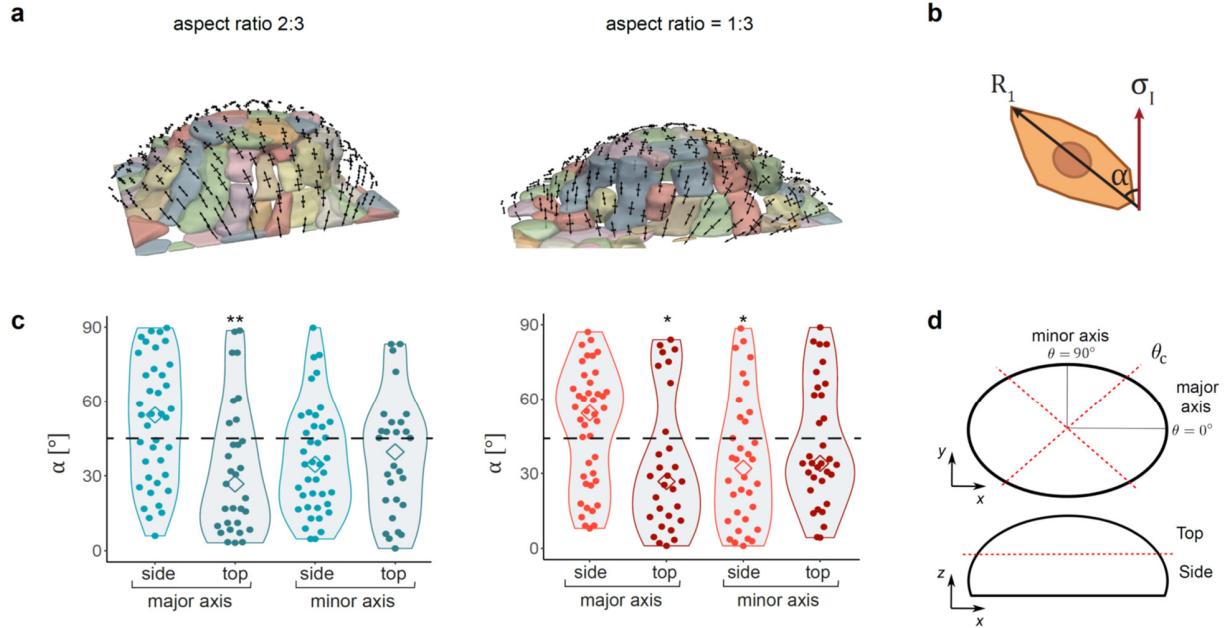


Figure 4. Relationship between stress and cell orientation in elliptical domes.

a, Segmentation images of high inflation ellipsoidal domes with 2:3 (left) and 1:3 (right) aspect ratio. The black arrows represent the two principal components of the inferred stress. **b**, Schematic showing the calculation of angle α between the longest cell axis (R_l) and the direction of the maximum principal stress (σ_l). **c**, Distribution of angles α for the different regions of highly inflated domes. Statistical significance was determined by comparing the experimental distributions and 10^4 randomly generated uniform distributions with the same n . $n=39$ (major side, left), 31 (major top, left), 40 (minor side, left), 28 (minor top, left), 42 (major side, right), 29 (major top, right), 34 (minor side, right), 33 (minor top, right). $*P < 0.05$ and $**P < 0.01$. **d**, Schematic indicating the different dome regions in which cells were binned. $\theta_c = 45^\circ$ (2:3 aspect ratio) and 30° (1:3 aspect ratio). Top-Side threshold = 50% (2:3 aspect ratio) and 40% (1:3 aspect ratio) of dome height.