

1 Computation of transcranial magnetic stimulation electric fields using self- 2 supervised deep learning 3

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13 Abstract

14 Electric fields (E-fields) induced by transcranial magnetic stimulation (TMS) can be modeled using partial
15 differential equations (PDEs). Using state-of-the-art finite-element methods (FEM), it often takes tens of
16 seconds to solve the PDEs for computing a high-resolution E-field, hampering the wide application of the
17 E-field modeling in practice and research. To improve the E-field modeling's computational efficiency, we
18 developed a self-supervised deep learning (DL) method to compute precise TMS E-fields. Given a head
19 model and the primary E-field generated by TMS coils, a DL model was built to generate a E-field by
20 minimizing a loss function that measures how well the generated E-field fits the governing PDE. The DL
21 model was trained in a self-supervised manner, which does not require any external supervision. We
22 evaluated the DL model using both a simulated sphere head model and realistic head models of 125
23 individuals and compared the accuracy and computational speed of the DL model with a state-of-the-art
24 FEM. In realistic head models, the DL model obtained accurate E-fields that were significantly correlated
25 with the FEM solutions. The DL model could obtain precise E-fields within seconds for whole head models
26 at a high spatial resolution, faster than the FEM. The DL model built for the simulated sphere head model
27 also obtained an accurate E-field whose average difference from the analytical E-fields was 0.0054,
28 comparable to the FEM solution. These results demonstrated that the self-supervised DL method could
29 obtain precise E-fields comparable to the FEM solutions with improved computational speed.

30 **Keywords:** Self-supervised learning, deep neural networks, electric field modeling, TMS

31 Introduction

32 Transcranial magnetic stimulation (TMS) is a noninvasive brain stimulation method used in treating major
33 depression and other neuropsychiatric disorders (O'Reardon et al., 2007). However, TMS treatment
34 outcomes vary greatly across patients (Cash et al., 2021; Cash et al., 2020; Diekhoff-Krebs et al., 2017;

1 Fox et al., 2012; Fox et al., 2013; Kim et al., 2014; Luber et al., 2017; Opitz et al., 2016; Sack et al., 2009;
2 Weigand et al., 2018; Williams et al., 2021). One primary source of such variability is that TMS suffers
3 from targeting inaccuracies (Julkunen et al., 2009; Weiss et al., 2013). Recent studies have demonstrated
4 that optimizing TMS stimulation parameters, such as location and orientation of the TMS coil, might
5 improve TMS targeting and focality for individual subjects (Gomez et al., 2021; Makarov et al., 2020b;
6 Weise et al., 2020), and optimizing TMS coil placement based on individual functional neuroanatomy
7 could potentially increase effect sizes for both basic and clinical studies (Diekhoff-Krebs et al., 2017; Fox
8 et al., 2012; Fox et al., 2013; Kim et al., 2014; Luber et al., 2017; Opitz et al., 2016; Weigand et al., 2018).

9 Modeling of electric-fields (E-fields) is now the most widely used method to characterize the
10 localization and spread of electrical current in the brain induced by TMS (Bungert et al., 2017; Deng et
11 al., 2013; Goetz and Deng, 2017; Gomez-Tames et al., 2020; Saturnino et al., 2019; Wang and Eisenberg,
12 1994). A variety of numerical computational methods have been developed to compute E-fields in
13 conjunction with realistic head models by iteratively solving PDEs governing the E-field induced by TMS
14 coils, including finite element methods (FEMs), boundary element methods (BEMs), and finite-difference
15 methods (FDMs) (Htet et al., 2019; Makarov et al., 2020a; Nielsen et al., 2018; Paffi et al., 2015; Saturnino
16 et al., 2019). The convergence of these numerical methods to the actual solution is sensitive to density
17 of the head mesh, the polynomial approximation order, and error tolerance, and their computational cost
18 is proportional to the modeling accuracy (Babuska et al., 1981). Although compromise is often necessary
19 in real applications, it often takes tens of seconds for state-of-the-art E-field modeling methods to compute
20 a high-resolution E-field (Htet et al., 2019; Makarov et al., 2020a; Nielsen et al., 2018; Paffi et al., 2015;
21 Saturnino et al., 2019).

22 The high computational cost of E-field modeling also makes it time-consuming and costly to
23 optimize TMS stimulation parameters since a large number of E-fields have to be explored to identify an
24 optimal solution (Gomez et al., 2021; Makarov et al., 2020b; Weise et al., 2020). To benefit clinical
25 practice using these sophisticated tools, the computational cost of E-field modeling has to be reduced
26 substantially without compromising accuracy. Faster E-field modeling is achievable by using a dipole-
27 based magnetic stimulation profile approach that has to compute a magnetic stimulation profile for each
28 individual subject with several hours of CPU time (Daneshzand et al., 2021) or to compute the E-field
29 only on sparse points or the mean of the E-field in a region of interest (ROI) by leveraging the reciprocity
30 principle (Gomez et al., 2021; Koponen et al., 2019). Recent studies have demonstrated that superfast
31 high-resolution E-field modeling can be achieved using deep neural networks (DNNs) (Xu et al., 2021;
32 Yokota et al., 2019). Particularly, the magnitude of E-fields was estimated based on individualized MRI
33 head scans and TMS coil positions by DNNs (Yokota et al., 2019), and 3D vector E-fields were predicted
34 using deep DNNs by integrating both individualized neuroanatomy (scalar-valued tissue conductivity or

1 anisotropic conductivity tensors) and primary E-fields generated by TMS coils as the input (Xu et al.,
2 2021). Though promising results have been obtained, the existing deep learning (DL) based models were
3 driven and optimized in a supervised learning setting. To train the DNNs, E-fields estimated by
4 conventional numerical methods, such as FEM, are used to generate training data. Therefore, their
5 accuracy would be bounded by the conventional numerical methods used to generate the training data.

6 Inspired by self-supervised deep learning methods (Geneva and Zabaras, 2020; Guo et al., 2020;
7 Li et al., 2021; Li and Fan, 2018, 2020; Qin et al., 2019; Raissi et al., 2019; Rao et al., 2021; Tian et al.,
8 2020; Winovich et al., 2019; Yang and Perdikaris, 2019; Zhu et al., 2019) and the pioneer deep learning
9 based E-field computation methods (Xu et al., 2021; Yokota et al., 2019), we develop a novel self-
10 supervised deep learning based TMS E-field modeling method to obtain precise high-resolution E-fields.
11 Specially, given a head model and the primary E-field generated by TMS coil, a DL model is built to
12 generate the electric scalar potential by minimizing a loss function that measures how well the generated
13 electric scalar potential fits the governing PDE, from which the E-field can be derived directly. In contrast
14 to the conventional numerical methods that solve the PDEs iteratively, the DL model is built to learn the
15 solution to the PDE directly. In contrast to the existing supervised DL methods, our DL model is trained
16 in a self-supervised manner by minimizing an energy function that solves the governing PDE as a loss
17 function, which does not require any external supervision. The trained DL model could be applied to new
18 subjects and predict their E-fields by one forward-pass computation. We have validated the proposed DL
19 model using both simulated sphere head model and realistic head models, and experimental results have
20 demonstrated that our method can obtain precise E-fields comparable to solutions obtained by a state-
21 of-the-art FEM implemented in SimNIBS v3.1 with improved computational speed.

22 **Methods**

23 We develop a self-supervised DL model to compute TMS E-fields by directly learning a mapping from
24 the magnetic vector potential of a TMS coil and a realistic head model to the TMS induced E-field so that
25 high-resolution TMS E-fields will be a good estimate of the solution to the governing PDE of TMS E-fields
26 and be computed by one feedforward computation rapidly.

27 *TMS E-fields modeling*

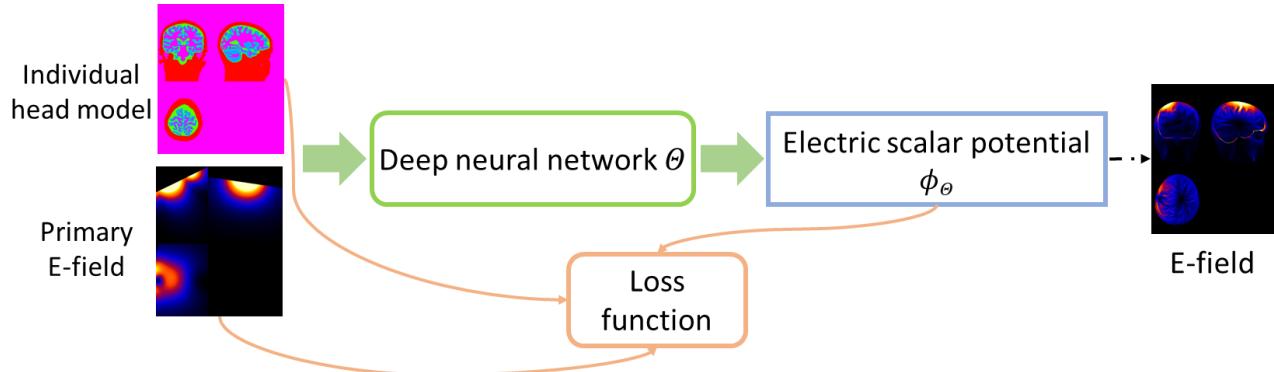
28 Given a head model consisting of head tissue compartments with different conductivities, the E-field E in
29 the head induced by a TMS coil can be computed by solving a PDE (Goetz and Deng, 2017; Gomez-
30 Tames et al., 2020; Wang and Eisenberg, 1994). Based on quasi-static approximation, the E-field, $E =$
31 $-\nabla\phi - \frac{\partial A}{\partial t}$, can be computed by solving

$$\nabla \cdot (\sigma \nabla \phi) + \nabla \cdot (\sigma \frac{\partial A}{\partial t}) = 0, \quad (1)$$

1 with the Neumann boundary condition

$$\vec{n} \cdot (\sigma \nabla \phi + \sigma \frac{\partial A}{\partial t}) = 0, \quad (2)$$

2 where σ is the tissue conductivity, A is the magnetic vector potential of the TMS coil, ϕ is the electric
 3 scalar potential, and \vec{n} is the normal vector to the tissue surface. Particularly, the primary E-Field $-\frac{\partial A}{\partial t}$
 4 depends only on the TMS coil characteristics (Deng et al., 2013; Koponen et al., 2017) and the secondary
 5 field $-\nabla \phi$ is caused by surface charges in the conducting medium characterized by the head model.



6
 7 **Fig.1.** A self-supervised deep learning model for computing TMS E-field. A deep neural network is applied to learn
 8 a mapping from individual head model and TMS induced primary E-field to the TMS electric scalar potential, and
 9 the network is optimized by a loss function determined by an energy function (Wang and Eisenberg, 1994).

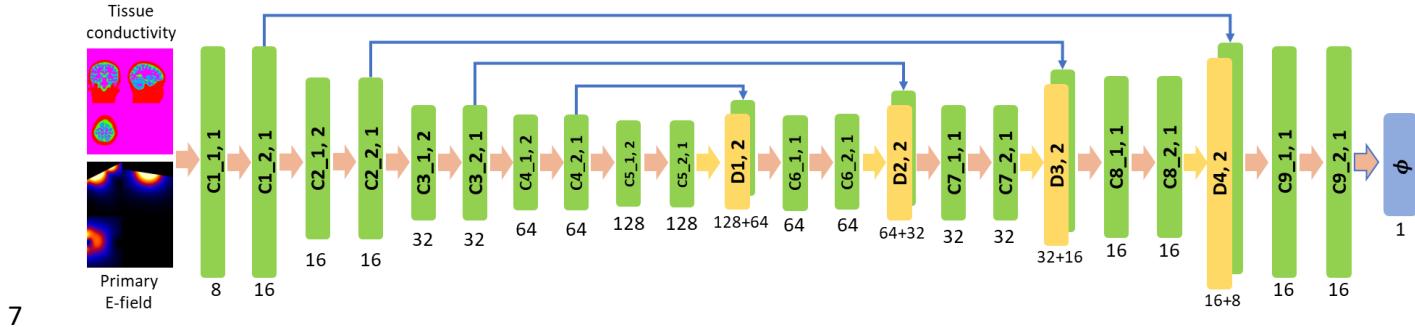
10 *Computing TMS E-fields using deep neural networks*

11 In contrast to the prevailing FEM/BEM methods adopted in E-field modeling studies (Gomez et al., 2021;
 12 Koponen et al., 2019; Makarov et al., 2020a; Makarov et al., 2020b; Nielsen et al., 2018; Paffi et al., 2015;
 13 Saturnino et al., 2019; Weise et al., 2020) and the existing DL methods that learn a mapping from
 14 individual MRI head scans/anatomy to E-fields in a supervised learning framework (Xu et al., 2021;
 15 Yokota et al., 2019), our DL model is built to minimize an energy function that solves the governing
 16 equation of Eq. (1) with the boundary condition of Eq. (2) in a self-supervised fashion as illustrated in Fig.
 17 1. Given a head model and TMS induced primary E-field as input, a deep neural network with parameters
 18 θ is built to estimate ϕ by minimizing a loss function L that measures the dissipated power in the
 19 conducting medium (Wang and Eisenberg, 1994), specified as:

$$L(\theta; \phi_\theta) = \int_{\Omega} \sigma (\nabla \phi_\theta + \frac{\partial A}{\partial t}) \cdot (\nabla \phi_\theta + \frac{\partial A}{\partial t}) d\Omega, \quad (3)$$

1 where ϕ_Θ is the electric scalar potential computed by the deep neural network and v refers to a spatial
 2 location (voxel) within the head model Ω .

3 Given the input training data, the deep neural network is trained to optimize the loss function of
 4 Eq. (3) in a self-supervised manner. Once the deep neural network is optimized, it could be applied to
 5 new subjects and predict the electric scalar potential ϕ by one forward-pass computation, from which the
 6 E-fields could be computed directly.



8 **Fig.2.** Deep convolutional neural network with an Encoder-Decoder architecture applied to learn TMS E-field. The
 9 numbers underneath convolutional (C1_1, C1_2, ..., C9_2) and deconvolutional (D1, D2, D3, and D4) layers
 10 indicate their corresponding numbers of kernels, with a stride of 1 or 2 for downsampling or upsampling. The kernel
 11 size in all layers is set to 3x3x3.

12 *Network architecture for computing TMS E-fields*

13 The overall architecture of our deep neural network for computing TMS E-fields is illustrated in Fig. 2.
 14 The deep neural network's backbone is a U-Net with an Encoder-Decoder architecture (Ronneberger et
 15 al., 2015). The network's input consists of an individual head model (scalar tissue conductivity map, a 4D
 16 volume with a channel size of 1) and a subject-specific primary E-field ($-\frac{\partial A}{\partial t}$, a 4D volume with a channel
 17 size of 3), and its output includes the estimated electric scalar potential ϕ_Θ (a 4D volume with a channel
 18 size of 1 and the same spatial dimension as the head model) and its gradient. The total E-field will be
 19 estimated as $E = -\nabla\phi_\Theta - \frac{\partial A}{\partial t}$. Particularly, the encoder path consists of ten convolutional layers with 8 to
 20 128 filters and a stride of 1 or 2 for downsampling, the decoder path consists of four deconvolutional
 21 layers with 128, 64, 32, and 16 filters and a stride of 2 for upsampling, each of which is followed by two
 22 additional convolutional layers with 64, 32, 16, and 16 filters and a stride of 1. One output convolutional
 23 layer with 1 filter is used to predict the electric scalar potential ϕ_Θ , and its gradient is computed with a
 24 central difference operator on the image grid. Leaky ReLU (Maas et al., 2013) activation function is used
 25 for all the convolutional and deconvolutional layers, except those two output layers. The kernel size in all
 26 layers is set to 3x3x3.

1 **Experimental results**

2 *Data preparation*

3 We have evaluated the proposed deep learning method using both simulated sphere head model and
4 realistic head models from real MRI scans.

5 For the simulated data, a 3D sphere head model with a radius of 95 mm and isotropic resolution
6 of 1 mm was generated. Its origin coordinate was set to [0, 0, 0] and its conductivity set to 1 s/m
7 homogeneously. The excitation was given by a point magnetic dipole located outside of the sphere. The
8 dipole's location was set to [0, 0, 100] and its moment set to [0, 0, 1]. The TMS induced E-field of this
9 sphere head model can be calculated analytically (Heller and van Hulsteyn, 1992), facilitating the direct
10 evaluation of numerical accuracy of methods under comparison.

11 For the realistic head models, we adopted a local cohort of 125 healthy adult subjects with high-
12 resolution multi-echo T1-weighted MPR images (TR=2400 ms, TI=1060 ms, TE= 2.24 ms, FA=8°,
13 0.8×0.8×0.8 mm³ voxels, image size=208×300×320, FOV= 256 mm). Based on these MRI scans, we
14 used SimNIBS v3.1 to generate anatomically accurate head models ('headreco' option with
15 SPM/Computational Anatomy Toolbox for tissue segmentation) and compute primary E-fields induced
16 by a Magstim 70mm Figure-of-Eight coil placed at varied locations with different orientations (Gomez-
17 Tames et al., 2018). For meshes of head models used in FEM computation, the average number of
18 tetrahedrons was 3.915×10^6 (with std of 3.633×10^5), and the average edge length was 2.103 mm (with
19 std of 0.801 mm), as the default setting used in the SIMNIBS pipeline. The tissue conductivity map was
20 generated by substituting the head tissue label values with their corresponding conductivity values. We
21 adopted the SimNIBS conductivity values, i.e., 0.126, 0.275, 1.654, 0.01, 0.465, and 0.5 S/m for whiter
22 matter, gray matter, CSF, bone, scalp, and eyes respectively.

23 *Experiment settings and implementation*

24 To obtain the E-field of the simulated sphere head model using our proposed deep learning model, the
25 conductivity map of the sphere and the primary E-field induced by the dipole was fed into the network as
26 illustrated in Fig. 2, and the network was trained and optimized with respect to the loss function of Eq. (3)
27 until convergence.

28 For the evaluation on the realistic head models, we randomly selected 100 subjects as training
29 subjects and the remaining 25 as testing subjects. To evaluate the accuracy and robustness of our deep
30 learning model with respect to different TMS coil positions and directions, three different experiment
31 settings were adopted.

1 *Setting 1.* The TMS coil was placed at a location within the motor cortex (center='C1' and
2 pos_ydir='CP1' as defined in the EEG10-10 system) for each subject to generate a primary E-field using
3 SimNIBS. There were 100 pairs of subject specific tissue conductivity maps and primary E-fields in total
4 used for training the deep learning model and 25 pairs for testing its accuracy under this setting, which
5 served as a proof-of-concept validation of our deep learning model on realistic head models.

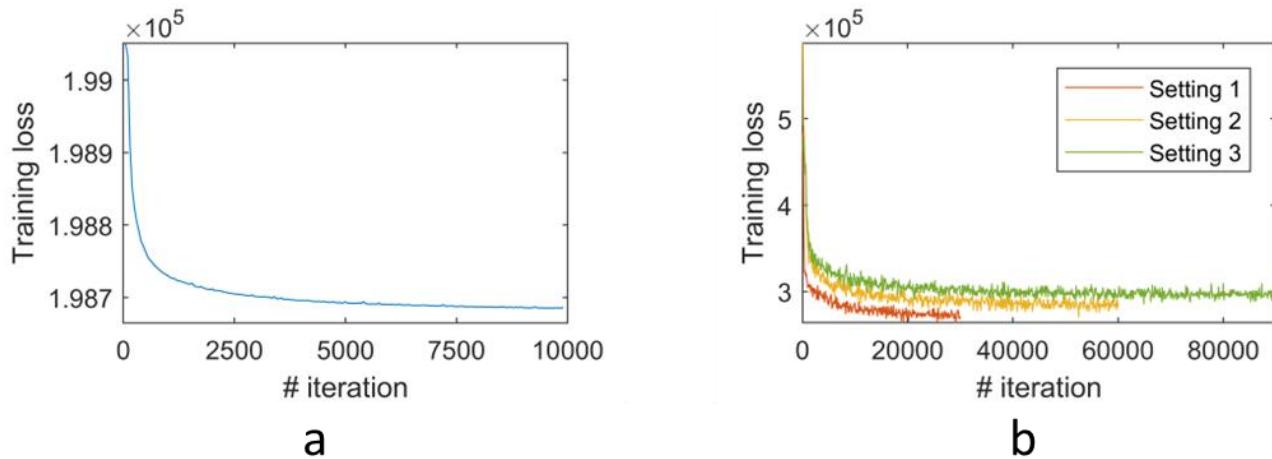
6 *Setting 2.* The TMS coil was placed at the same location within the motor cortex (center='C1') but
7 in different directions for training and testing the deep learning model. Particularly, primary E-fields of
8 each training subject were generated with different coil directions (seen directions), including 'CP1', 'Cz',
9 'FC1', and 'C3', as training data. There were 400 pairs of subject specific tissue conductivity maps and
10 primary E-fields in total for training the deep learning model. The optimized deep learning model was
11 then evaluated on the testing subjects with the coil placed in directions different from those for generating
12 the training data (unseen directions), including 'CPz', 'FCz', 'FC3', and 'CP3'. In total, there were 100
13 pairs of subject specific tissue conductivity maps and primary E-fields for testing. This setting was
14 adopted to evaluate the generalization performance of the deep learning model with respect to varying
15 coil directions.

16 *Setting 3.* The TMS coil was placed at different spatial locations within the left dorsolateral
17 prefrontal cortex (DLPFC) to evaluate the robustness of the deep learning model with respect to changes
18 of coil locations. Particularly, a target position was defined using the average mean Montreal Neurological
19 Institute (MNI) coordinates (x=-42, y=16, z=28) (Friehs et al., 2020), which was transformed to subject
20 space using SIMNIBS to obtain a subject-specific target position. Then, multiple coil positions and
21 directions were generated within a grid centered at the target position using the SIMNIBS function
22 'optimize_tms.get_opt_grid' with parameters of radius=20, resolution_pos=10, resolution_angle=90,
23 angle_limits=[-180,180], yielding 36 (9 positions by 4 directions) pairs of tissue conductivity map and
24 primary E-field for each subject. In total, there were 3600 pairs of subject specific tissue conductivity
25 maps and primary E-fields for training the deep learning model and 900 pairs of subject specific tissue
26 conductivity maps and primary E-fields for testing its accuracy.

27 For both the simulated and realistic head models, our deep neural network's input was a
28 concatenated 4D volume data of the scalar tissue conductivity map (a 4D volume with a channel size of
29 1) and the primary E-field (a 4D volume with a channel size of 3), and its output included a predicted
30 scalar electric potential (a 4D volume with a channel size of 1) and its gradient. The deep neural network
31 was optimized under each setting respectively on the training data regarding the loss function of Eq. (3).
32 The subject-specific head model and primary E-field was generated using SimNIBS for each subject. For
33 the realistic head models, the input image was cropped (only regions outside the head was cropped) to
34 have a spatial dimension of 208x288x304 to fit the fully convolutional network architecture of our DL

1 model. The channel size was 1 and 3 for scalar image (tissue conductivity map and electric potential)
2 and vector image (primary E-field), respectively.

3 Our deep learning model was implemented using Tensorflow (Abadi et al., 2016). Adam optimizer
4 (Kingma and Ba, 2014) is adopted to optimize the network, the learning rate was set to 1×10^{-4} , the
5 batch size was set to 1, and the number of iterations is set to 10000 for the simulated sphere head model,
6 30000 for realistic head model setting 1, 60000 and 90000 for realistic head model setting 2 and 3 during
7 training. One NVIDIA TITAN RTX GPU with 24G memory was used for training and testing. Training
8 losses of our deep learning models on the simulated sphere head model and realistic head models are
9 shown in Fig. 3, demonstrating the optimized deep learning models reached convergence with the
10 specified parameters.



11
12 **Fig.3.** Training loss of the proposed deep learning model on simulated sphere head model (a) and realistic head
13 models under different experiment settings (b).

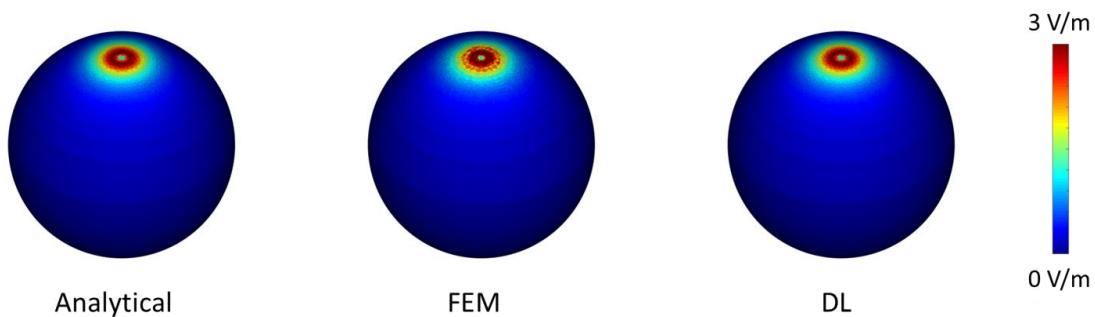
14 *Evaluation and comparisons*

15 We compared our method in terms of both accuracy and computational speed with a state-of-the-art FEM,
16 with superconvergent patch recovery, implemented in SimNIBS v3.1. We also compared our method
17 with a FDM under *Setting 1* using an implementation available at
18 https://github.com/luisgo/TMS_Efield_Solvers (Gomez et al., 2020). As no ground truth was available for
19 the realistic head models, we used the solutions of FEM as reference to estimate the accuracy, following
20 the existing deep learning studies of E-field modeling (Xu et al., 2021; Yokota et al., 2019). The FEM
21 solutions were projected onto voxels using “msh2nii” as implemented in SimNIBS for the comparison.
22 Two evaluation metrics, including pointwise magnitude error and correlation coefficient between the
23 predicted and reference solutions were adopted (Gomez et al., 2020). Specifically, the correlation
24 coefficient was computed as Pearson correlation between the magnitude of E-fields obtained by our DL
25 method and the FEM within a specified ROI, and the pointwise magnitude error was computed as

1 $err(r) = \frac{abs(E_{DL}(r) - E_{ref}(r))}{\max_{r \in \{GM, WM\}} E_{ref}(r)}$, where r refers to voxel r in GM and WM region. Both measures were
2 evaluated within different ROIs, including the combined gray matter and whiter matter (GM&WM) region,
3 the gray matter (GM) region, the white matter (WM) region, region thresholded at the 95th percentile of
4 E-field magnitude (Xu et al., 2021), and region thresholded at the 50% of the E-field maximum (Deng et
5 al., 2013; Yokota et al., 2019), to get better understanding about the characteristics of the DL based
6 solution. For the simulated sphere head model, the E-field can be calculated analytically (Heller and van
7 Hulsteyn, 1992) to directly evaluate the numerical accuracy of methods under comparison. Particularly,
8 the difference between a numerical solution E_{num} and an analytically solution E_{ana} was measured with a
9 normalized root-mean-square error (NRMSE): $\frac{1}{N} \sum_{v=1}^N \frac{\|E_{num}(v) - E_{ana}(v)\|}{\|E_{ana}(v)\|}$, where N is the number of voxels
10 in the sphere head model. The evaluation metrics were computed on voxels with values greater than 0
11 in the reference/ground-truth solution.

12 **Results**

13 *Results on simulated sphere head model.* Fig. 4 shows the magnitude of E-fields computed analytically,
14 by the FEM, and by the proposed DL model, respectively, demonstrating that the numerical E-fields
15 obtained by our DL model and the FEM were visually similar to the analytical solution. The NRMSE
16 between the DL based and analytical E-field was 0.0054, close to the NRMSE between FEM based and
17 analytical E-field (NRMSE=0.0055), indicating that the E-field solution obtained by the DL model was
18 comparable to the FEM solution. This result demonstrated that the proposed DL model can indeed be
19 optimized to learn the E-field that follows the physics law underlying the TMS stimulation.



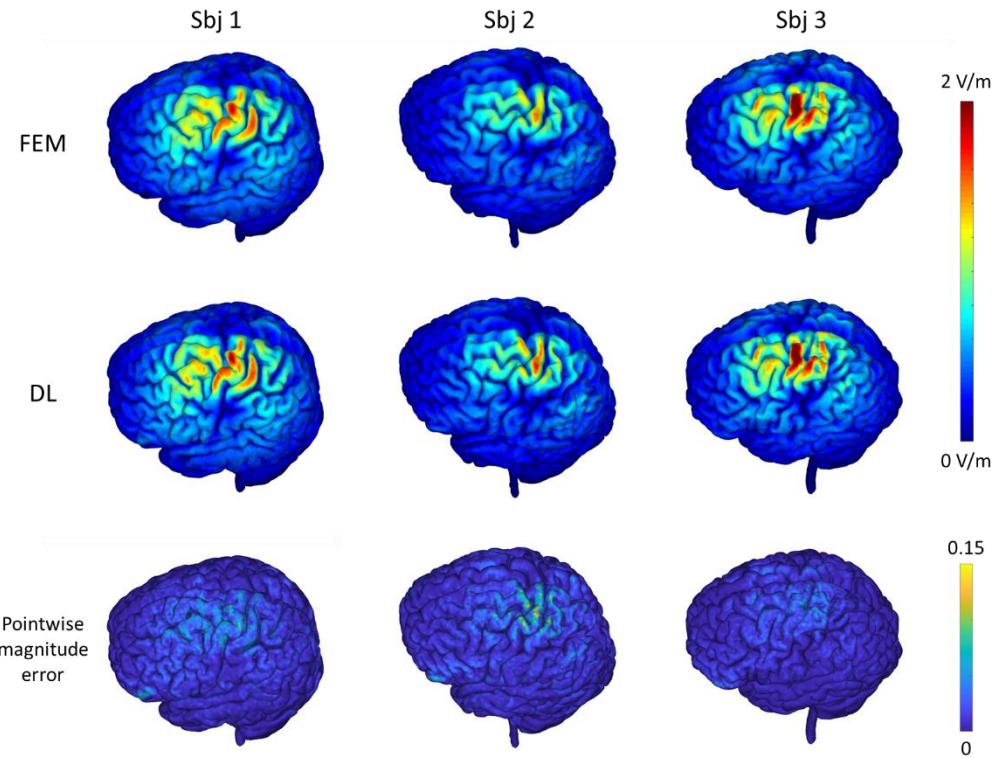
20
21 **Fig.4.** The magnitude of E-fields of the sphere model computed analytically, by FEM (with a NRMSE of 0.0055),
22 and by our DL method (with a NRMSE of 0.0054), respectively.

23 **Table 1.** Quantitative evaluation of the proposed DL method under different experimental settings, with the FEM
24 solutions as reference. Mean and standard deviation of the correlation coefficient (CC) and pointwise magnitude
25 error (PME) measures within different regions of interest (ROIs) are demonstrated. ROI definition: gray and whiter

1 matter (GM&WM), gray matter (GM), white matter (WM), region thresholded at the 95th percentile of E-field
2 magnitude (95th percentile), region thresholded at the 50% of maximum E-field magnitude (50% of max).

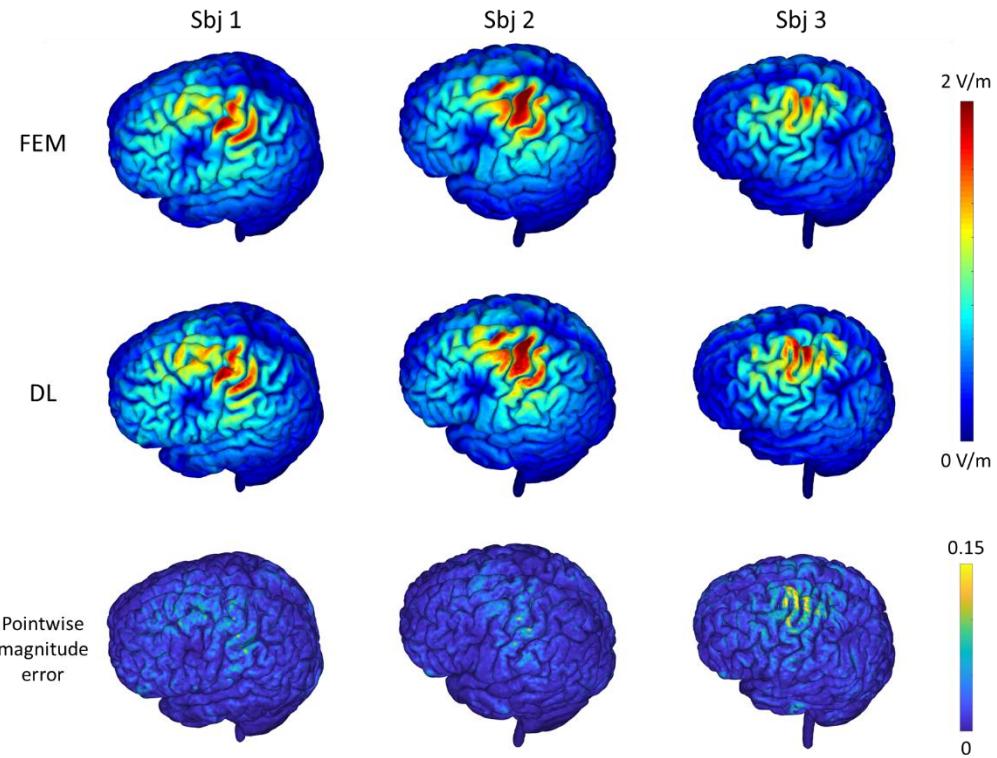
	CC GM&WM	CC GM	CC WM	CC 95 th percentile	CC 50% of Max	PME GM&WM	PME GM	PME WM	PME 95 th percentile	PME 50% of Max
Setting 1 train	0.984 ±0.005	0.984 ±0.004	0.985 ±0.006	0.958 ±0.007	0.856 ±0.035	0.010 ±0.002	0.010 ±0.002	0.010 ±0.002	0.025 ±0.003	0.044 ±0.003
Setting 1 test	0.978 ±0.006	0.979 ±0.005	0.977 ±0.008	0.948 ±0.014	0.837 ±0.034	0.012 ±0.003	0.012 ±0.003	0.013 ±0.003	0.030 ±0.005	0.049 ±0.008
Setting 2 test (seen dir)	0.979 ±0.005	0.978 ±0.005	0.980 ±0.006	0.933 ±0.017	0.801 ±0.127	0.013 ±0.003	0.013 ±0.003	0.013 ±0.003	0.034 ±0.007	0.055 ±0.011
Setting 2 test (unseen dir)	0.957 ±0.012	0.961 ±0.010	0.953 ±0.015	0.918 ±0.022	0.782 ±0.113	0.019 ±0.005	0.019 ±0.005	0.022 ±0.005	0.042 ±0.011	0.064 ±0.014
Setting 3 test	0.984 ±0.004	0.983 ±0.004	0.985 ±0.004	0.943 ±0.010	0.819 ±0.052	0.012 ±0.002	0.012 ±0.002	0.012 ±0.003	0.036 ±0.005	0.055 ±0.006

3
4 *Results on realistic head model setting 1.* The E-fields of three randomly selected testing subjects
5 computed by the FEM and our proposed DL method are shown in Fig. 5. The results obtained by our DL
6 model had patterns similar to those obtained by FEM. Quantitatively, the results obtained by our DL
7 method were significantly correlated with the FEM solutions, with an average correlation of 0.978 and an
8 average pointwise magnitude error of 0.012 within the gray and white matter region, and these measures
9 were similar when evaluated within gray matter and white matter respectively, as summarized in Table
10 1, indicating that the results by our DL model are comparable to the reference solutions of FEM. The
11 average correlation and pointwise magnitude error were 0.948 and 0.03 respectively for regions with E-
12 field magnitude exceeding the 95th percentile, which are similar to those obtained by state-of-the-art
13 supervised DL models (Xu et al., 2021). For regions with a E-field magnitude exceeding 50% of the E-
14 field maximum, the average correlation and pointwise magnitude error were 0.837 and 0.049 respectively.
15 These quantitative measures were largely consistent with results shown in Fig. 5 that the magnitude error
16 was relatively larger for regions with a high E-field magnitude. Moreover, our DL model obtained similar
17 correlation coefficients and pointwise magnitude error on both training and testing subjects as shown in
18 Table 1, demonstrating the model's robustness to the anatomical differences across different subjects.
19 Our E-field solutions were also significantly correlated with the FDM solutions, with an average correlation
20 coefficient of 0.981 (standard deviation: 0.006) and an average pointwise magnitude error of 0.010
21 (standard deviation: 0.002) within the gray and white matter.



1
2 **Fig.5.** E-fields of three randomly selected testing subjects computed by the FEM and the proposed DL model with
3 the motor cortex as a stimulation target (1st and 2nd rows), and the corresponding pointwise magnitude error map
4 with the FEM solution as reference (3rd row). The top colorbar shows the magnitude values (in V/m) of the E-fields
5 and the bottom colorbar shows the normalized pointwise magnitude error.

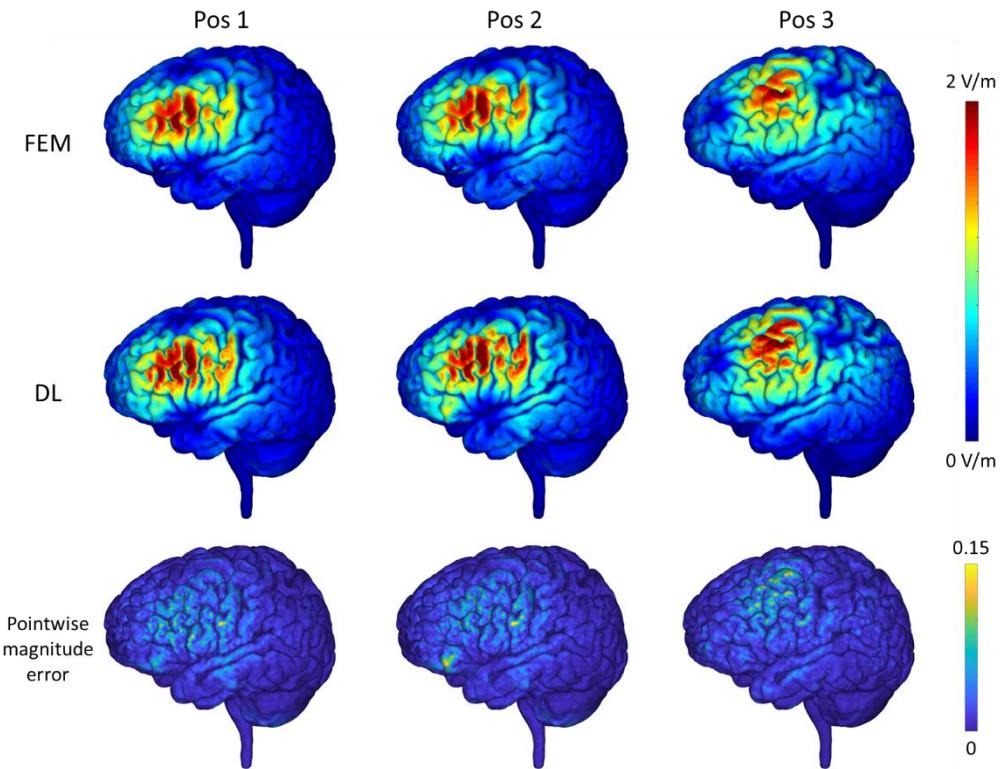
6 *Results on realistic head model setting 2.* The E-fields of three randomly selected testing subjects with
7 unseen coil directions computed by the FEM and our proposed DL method are shown in Fig. 6. Though
8 the coil directions were different from those used for training the DL model, the DL model still successfully
9 predicted the E-fields for the testing subjects, demonstrating good consistency with those obtained by
10 the FEM. Quantitatively, the results on both seen and unseen coil directions obtained by our DL method
11 were significantly correlated with the FEM solutions, with an average correlation of 0.979 and 0.957
12 respectively, while the average pointwise magnitude error was 0.013 and 0.019 respectively for the gray
13 and white matter region, as summarized in Table 1. As shown in Fig. 6, the prediction error was relatively
14 larger for regions with a high E-field magnitude. It is worth noting that all these results were obtained for
15 testing subjects which were not used for the model training. These results demonstrated that the DL
16 model was robust under different coil direction settings and could generalize to unseen coil directions.
17 We also observed that the pointwise magnitude error of the 3rd subject was larger compared with others
18 in Fig. 6, which might indicate the model's robustness to inter-subject anatomical difference compromises
19 moderately when the coil directions were not seen during the model training procedure.



1

2 **Fig.6.** E-fields of three randomly selected testing subjects computed by the FEM and the proposed DL model with
3 the motor cortex as a stimulation target and the coil set in varying directions (1st and 2nd rows), the corresponding
4 pointwise magnitude error map with the FEM solution as reference (3rd row). The top colorbar shows the magnitude
5 values of the E-fields and the bottom colorbar shows the normalized pointwise magnitude error.

6 *Results on realistic head model setting 3.* The E-fields of one randomly selected testing subject computed
7 by the FEM and our proposed DL method for three different coil positions located within the DLPFC area
8 are shown in Fig. 7. The E-fields obtained by our DL model are visually similar to those obtained by FEM.
9 The average correlation coefficient of the solutions obtained by our DL model and FEM was 0.984 within
10 the gray and white matter for the testing subjects, with an average pointwise magnitude error of 0.012 as
11 summarized in Table 1, indicating that our DL model was capable of predicting E-fields with varying coil
12 positions and directions. It could be observed that the prediction error was relatively larger for regions
13 with a high E-field magnitude. The average correlation and pointwise magnitude error were 0.943 and
14 0.036 respectively for regions with a E-field magnitude exceeding the 95th percentile, and the average
15 correlation and pointwise magnitude error was 0.819 and 0.055 respectively for regions with E-field
16 magnitude exceeding 50% of the E-field maximum.



1

2 **Fig.7.** E-fields of one randomly selected testing subjects computed by the FEM and the proposed DL model with
3 the dorsolateral prefrontal cortex (DLPFC) as a stimulation target and the coil set at varying positions and in different
4 directions (1st and 2nd rows), and the corresponding pointwise magnitude error map with the FEM solution as
5 reference (3rd row). The top colorbar shows the magnitude values of the E-fields and the bottom colorbar shows
6 the normalized pointwise magnitude error.

7 *Computation time.* It took 35.17 and 33.65 seconds on average by the FEM as implemented in SIMNIBS
8 to obtain the E-field for one subject (whole head model with $208 \times 288 \times 304$ voxels at a spatial resolution
9 of $0.8 \times 0.8 \times 0.8 \text{ mm}^3$) with the TMS coil located at the motor cortex and DLPFC respectively when using
10 one Intel Xeon Gold 5218 CPU. It took 14.27 and 14.26 seconds by our trained DL model using the same
11 CPU. On one NVIDIA TITAN RTX GPU, it took 1.47 and 1.49 seconds respectively by our trained DL
12 model to compute E-fields with the TMS coil located at the motor cortex and DLPFC, respectively. For
13 the FEM, the timing measurement included the time for assembling and solving the FEM system; For DL
14 method, the timing measurement includes the time for one forward pass to obtain the E-field and the
15 electric potential using a head model and a primary E-field as input. We did not include the time for
16 computing head model/mesh and primary E-field for both the FEM and our DL method. This comparison
17 demonstrated the improved computational speed obtained by the proposed deep learning model. For the
18 model training, it took 2.88 seconds on average for each training iteration. It is worth noting that the model
19 only needs to be trained once for a target ROI, which can be applied to new testing subjects without

1 further optimization once trained.

2 **Discussion**

3 We have developed a self-supervised deep learning model to directly learn a mapping from the magnetic
4 vector potential of a TMS coil and a realistic head model to the TMS induced E-fields, instead of iteratively
5 solving equations governing the E-field induced by a TMS coil. Experimental results on both simulated
6 and realistic head models have demonstrated that our method could obtain similar accuracy compared
7 with the most commonly used numerical method. Our method is capable of computing the TMS induced
8 E-fields by one forward-pass computation, taking less than 1.5 seconds for a realistic head model with
9 high spatial resolution.

10 Several numerical computational methods have been developed for accurate E-fields modeling
11 in conjunction with realistic head models, such as FEMs, BEMs, and FDMs. Though the computational
12 speed of state-of-the-art numerical methods has been improved a lot, their computational cost for high-
13 resolution E-fields is still high due to the nature of iterative optimization in their PDE solvers, which
14 compromises their use in the optimization of TMS stimulation parameters in both basic and clinical studies.
15 Instead of solving the governing PDEs from scratch, recently studies have demonstrated promising
16 performance of deep neural networks for rapid estimation of E-fields (Xu et al., 2021; Yokota et al., 2019),
17 in which deep neural networks are trained to directly predict the E-fields with high fidelity to those
18 estimated using conventional E-field modeling methods, such as FEMs. Therefore, the deep neural
19 networks are actually trained to predict the solutions obtained by the conventional E-field modeling
20 methods and their performance is bounded by the conventional E-field modeling methods used for
21 generating training data. Moreover, it will also be time-consuming to generate surrogate training data with
22 different TMS stimulation parameters on a large cohort.

23 In contrast to the existing deep learning based E-field modeling methods (Xu et al., 2021; Yokota
24 et al., 2019) that learn a mapping from head scans/models to surrogate E-fields estimated using
25 conventional E-field modeling methods in the supervised learning way, our method directly learns a
26 solution to the governing equations in a self-supervised learning way, which does not require any external
27 supervision. Our proposed deep neural network is designed to predict the TMS induced electric scalar
28 potential and is optimized so that the network's output fit the governing PDE as much as possible, which
29 is formulated to minimize an energy function that solves the governing PDE. Therefore, our method
30 directly learns a solution to the same governing PDE as the convention numerical optimization methods
31 do, while benefiting from the fast inference of deep neural networks. As surrogate E-fields are not required
32 by our method, realistic head models from diverse imaging datasets can be used as the training data for
33 our method. To the best of our knowledge, our method is the first study to investigate self-supervised

1 deep learning for TMS E-field modeling, though physics-informed deep learning methods have been
2 successfully applied to solving PDEs on varied domains (Geneva and Zabaras, 2020; Guo et al., 2020;
3 Qin et al., 2019; Raissi et al., 2019; Rao et al., 2021; Tian et al., 2020; Winovich et al., 2019; Yang and
4 Perdikaris, 2019; Zhu et al., 2019).

5 Our method is designed as a general-purpose method for the computation of E-field, and it could
6 obtain the E-field for a new subject (whole head model with $208 \times 288 \times 304$ voxels at a spatial resolution
7 of $0.8 \times 0.8 \times 0.8$ mm³) in about 1.47 seconds. Several alternative fast E-field computation methods have
8 been developed (Daneshzand et al., 2021; Stenroos and Koponen, 2019). Particularly, a magnetic
9 stimulation profile for each subject needs to be computed in advance (Daneshzand et al., 2021), which
10 may require hours of CPU time. The surface integral equation used in (Stenroos and Koponen, 2019) is
11 valid only for isotropic medium, which cannot account for the anisotropic conductivity of white matter
12 properly. Our method does not require per-subject training or pre-computation, it could be applied to new
13 subjects directly without further optimization once a DL model training is finished. Moreover, we can
14 further reduce its computation time by applying the trained model to a region of interest (ROI) instead of
15 the whole head model, facilitated by the fully convolutional network architecture of our method. It should
16 be noted that an isotropic tissue conductivity model was adopted in our current method development and
17 evaluation, and the trained model should not be applied to head models with anisotropic tissue
18 conductivity. It should be also noted that extension to anisotropic tissue conductivity is feasible by
19 incorporating anisotropic conductivity tensor into the loss function defined in Eq. (3) and replacing the
20 scalar conductivity with anisotropic conductivity tensor properly as the network input.

21 In addition to promising accuracy and computational speed, our method is robust to varying TMS
22 coil locations and directions. As demonstrated in Fig. 6, the deep neural network generalized well for
23 computing E-fields of the testing subjects that were generated by the coil placed in directions different
24 from those for generating the training data. The validation experiment with the coil placed at left DLPFC
25 has further demonstrated that the accuracy of the predicted E-fields was still comparable to that obtained
26 by the FEM on the testing subjects, even though the coil was placed at varying locations and in different
27 directions, as illustrated in Fig. 7. The good generalization performance of the proposed method may be
28 attributed to its self-supervised learning nature, which optimizes the deep learning model to learn the
29 underlying mapping between head anatomy and electric potential without external guidance or prior
30 assumptions. The robust generalization emphasizes that this method is likely to be applicable to the
31 optimization of TMS stimulation where varying positions and directions around the target position are to
32 be explored. Nevertheless, it was observed in Figs. 5 to 7 that the pointwise magnitude errors were
33 relatively large at the regions with a high E-field magnitude, indicating there is still room for improving the
34 model's performance with respect to both methodological development and model training, such as

1 optimizing the neural network architecture and increasing the size of training dataset. It was also
2 observed in Fig. 6 that the prediction error for the 3rd subject was relatively larger than that for other
3 subjects, which might be due to large inter-subject anatomical differences between training and testing
4 subjects, and it is expected that a model trained on a larger training dataset with more subjects will
5 improve the model's robustness to anatomical differences across subjects. On the other hand, the DL-
6 based results can also be served as a good initialization for conventional PDE solvers to achieve an
7 improved convergence rate given that the DL-based results were close to the FEM-based solutions.

8 Though the self-supervised deep learning method has demonstrated enormous potential for fast
9 and accurate E-field modeling, there are still several limitations should be noted. First, current evaluation
10 was focused on E-field induced by a Figure-of-Eight coil and head models at a single resolution, the
11 influence of different coils and spatial resolutions of head models merits further investigation. Second,
12 scalar tissue conductivity maps were used in the present study. Future work will be devoted to modeling
13 of anisotropic tissue conductivity with deep learning and exploring its effects on the derived E-field. Third,
14 our current model adopts a traditional U-Net architecture, which can be optimized in terms of both
15 accuracy and computational speed of the E-field modeling using neural architecture search (NAS)
16 techniques (Elsken et al., 2019). In addition, tuning the hyper-parameters for network training such as
17 batch size along with the architecture optimization may further improve the performance. Moreover, the
18 gradient operator currently used to compute the loss function in Eq. (3) was implemented as a central
19 difference operator on the image grid, which may generate blurring or artificially elevated peak values
20 around the tissue boundaries. More attention should also be paid to exploring other numerical solutions
21 such as cubic spline based method and spectral differentiation for computing gradient or other processing
22 strategies to improve the prediction at tissue boundary regions. Fourth, dedicated deep neural networks
23 were trained separately for different target regions in the present study, future work will be devoted to
24 investigating the feasibility of one unified neural network for multiple target regions across the cerebral
25 cortex and its generalization with respect to the size of training data and the neural network capacity.

26 In conclusion, a self-supervised deep learning model was developed to estimate TMS induced E-
27 fields directly from realistic head models and the TMS coil's magnetic vector potential. The DL model can
28 obtain high-resolution E-fields from realistic head models with high accuracy, facilitating fast and precise
29 TMS E-field modeling, and therefore the optimization of TMS stimulation parameters in both basic and
30 clinical studies.

31 **Declarations of interest**

32 None.

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