

A quantitative biophysical principle to explain the 3D cellular connectivity in curved epithelia

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1 SUMMARY

2 Epithelial cell organization and the mechanical stability of tissues are closely related.
3 In this context, it has been recently shown that packing optimization in
4 bended/folded epithelia is achieved by a surface tension energy minimization
5 mechanism that leads to a novel cellular shape: the *scutoid*. However, further cellular
6 and tissue level implications of this new developmental paradigm remain unknown.
7 Here we focus on the relationship between this complex cellular shape and the
8 connectivity between cells. We address this problem using a combination of
9 computational, experimental, and biophysical approaches in tubular epithelia. In
10 particular, we examine how energy drivers affect the three-dimensional packing of
11 these tissues. We challenge our biophysical model by reducing the cell adhesion in
12 epithelial cells. As a result, we observed an increment on the cell apico-basal
13 intercalation propensity that correlated with a decrease of the energy barrier
14 necessary to connect with new cells. We conclude that tubular epithelia satisfy a
15 quantitative biophysical principle, that links tissue geometry and energetics with the
16 average cellular connectivity.

19 KEYWORDS

20 Tissue/Cellular Biophysics, Computational geometry, Developmental Systems
21 Biology, Mathematical/Biophysical modeling, Bioimage Analysis

22

1 INTRODUCTION

2 During the last decades much progress has been achieved in the understanding of
3 the emergence of self-organization in tissues. This problem has been addressed from
4 the viewpoint of energetics considerations (Alt et al., 2017; Canela-Xandri et al.,
5 2011; Fletcher et al., 2014; Misra et al., 2017; Nelson et al., 2005; Siedlik et al., 2017;
6 Sugimura et al., 2016; Trepatt et al., 2009), material-like properties (Bi et al., 2015;
7 Campàs et al., 2014; Latorre et al., 2018; Mongera et al., 2018; Pérez-González et al.,
8 2019; Yang et al., 2017), and the analysis of the cellular packing (Curran et al., 2017;
9 Farhadifar et al., 2007; Gibson et al., 2006; Gibson et al., 2011; Gómez et al., 2021;
10 Honda, 1978; Lewis, 1928; Mao et al., 2013; Sanchez-Gutierrez et al., 2016;
11 Thompson, 1945). As for the latter, the analysis of epithelial surfaces as tessellations
12 of convex polygons has revealed mathematical and physical principles with biological
13 consequences. One well-known example are the implications of the celebrated
14 Euler's formula, $V - E + F = \chi$ (**STAR Methods**) (Euler, 1767). This formula implies
15 that cells in packed tissues have, on average, six neighbors (i.e., the average cellular
16 connectivity on a surface reads $\langle n_{2D} \rangle = 6$) (Reinhardt, 1918; Wetzel, 1926). This
17 principle has biological consequences, for example, the degree of cellular
18 connectivity regulates the strength of the cell-cell juxtracrine signaling (Guignard et
19 al., 2020; Sharma et al., 2019; Tung et al., 2012).

20 For a long time, the validity of this mathematical concept (i.e., each cell, on average,
21 connects with six neighboring cells) has been assumed in three dimensions (3D):
22 $\langle n_{2D} \rangle = 6 \Rightarrow \langle n_{3D} \rangle = 6$. Such an assumption is rooted in the common idealization
23 of epithelial cells as regular prismatic solids in either planar or bended epithelia.
24 However, the recent discovery of more complex cellular shapes in epithelia, i.e.,
25 scutoids, that achieve an efficient 3D tissue packing has set a new paradigm that has
26 not been yet fully explored (**Box A**) (Gómez-Gálvez et al., 2018; Mughal et al., 2018;
27 Rupprecht et al., 2017). Scutoidal cellular shapes are the result of intercalations
28 among cells along the apico-basal axis (**Box A-C** and **Fig. 1A**). This phenomenon is
29 then a spatial version of the so-called T1 transitions that produce rearrangements of
30 neighboring cells in the plane as a function of time in numerous developmental
31 processes (**Box B**) (Bertet et al., 2004; Irvine and Wieschaus, 1994; Spencer et al.,

2017). Importantly, scutoids imply necessarily changes in the neighboring relationship between cells in a 3D spatial context and, consequently, modify the connectivity properties of cells (**Box C**). Still, the analysis of tissue organization in 3D and the corresponding biophysical insight have been hindered by the technical difficulties to accurately segment and 3D-reconstruct cells, especially in curved tissues. In addition, very few computational models account for the presence of apico-basal transitions to investigate 3D self-organization in tissues (Gómez-Gálvez et al., 2018; Ioannou et al., 2020; Mughal et al., 2018; Okuda et al., 2019; Rupprecht et al., 2017). Moreover, from an energetics viewpoint, while the appearance of scutoids can be explained by a minimal model based on a surface/line tension minimization mechanism (Gómez-Gálvez et al., 2018; Mughal et al., 2018; Okuda et al., 2019; Rupprecht et al., 2017), the role played by additional energetic contributions to modulate the frequency of apico-basal intercalations is unknown.

The analysis of 3D packing is in turn utterly relevant in cubic and columnar monolayer tubular epithelia, where scutoids appear more frequently (Gómez-Gálvez et al., 2018; Gómez et al., 2021; Iruela-Arispe and Beitel, 2013; Sanchez-Corrales et al., 2018). Epithelial tubes are in fact the primary developmental structures in all organisms with bilateral symmetry (Gilbert and Barresi, 2013), and tubulogenesis is fundamental in a broad variety of key developmental processes, including gastrulation and neurulation (Colas and Schoenwolf, 2001; Iruela-Arispe and Beitel, 2013; Leptin and Grunewald, 1990; Nelson, 2009; Pilot and Lecuit, 2005; Röper, 2018; Swanson and Beitel, 2006). Furthermore, epithelial tubes are the essential functional unit of many mammalian organs, including glands, components of the digestive apparatus, lungs, and kidney (Huebner and Ewald, 2014).

Here, we study the packing and the 3D cellular connectivity properties of epithelial tubes. We analyze the effect of different energetic contributions to modulate the frequency of apico-basal intercalations; demonstrate that the presence of scutoids implies a breakdown of the principle $\langle n_{3D} \rangle = 6$; and reveal a quantitative biophysical principle that links the 3D cellular connectivity, energetics, and geometrical descriptors (e.g., tissue curvature/thickness). Our findings are supported by i) a computational model that realistically renders the 3D cellular organization of tubular

1 epithelia (including the appearance of scutoids); ii) experimental data of wildtype
2 (wt) and mutant epithelial tubes (*Drosophila's* salivary gland) whose 3D cellular
3 structure has been accurately characterized by means of a computer-aided image
4 analysis pipeline. And iii), a biophysical model, supported by mathematical
5 calculations, that connects the tissue energetics with the 3D organization of epithelial
6 tubes.

8 RESULTS

9 The Voronoi computational tubular model supports a relationship between energy 10 profiles and the intercalation propensity

11 To understand how the geometry of tubular epithelia and different energy
12 contributions affect the 3D cellular packing and connectivity of these tissues, we
13 designed and implemented a computational epithelial model that follows the
14 principles of Voronoi tessellations (**Box D, E**) (Gómez-Gálvez et al., 2018). In brief, we
15 generated 3D models of epithelial tubes by populating with seeds the apical surface,
16 Σ_a (light blue points in **Fig. 1B**) and implementing normal projections of those seeds
17 up to the basal surface, Σ_b (dark blue points in **Fig. 1B**). Each seed and its projection
18 corresponded to an individual cell of a tube. At each surface section Σ (from apical to
19 basal) a 2D Voronoi diagram was performed, and the collection of those tessellations
20 rendered the 3D cellular geometry of cells (see details in **STAR Methods**). We point
21 out that we do not implement any temporal dynamics to the seeds. Thus, our
22 computational model is suited to static epithelial configurations as the ones
23 experimentally reported herein (see below).

24 Epithelial tubes appear in nature with very different thicknesses and cellular
25 arrangements. In order to explore how these features influence the 3D packing
26 properties of tubular epithelia we built diverse *in silico* Voronoi tubes. First, to
27 investigate the effect of tissue thickness we computed Voronoi tubes with different
28 surface ratios $s = R/R_a$ (R and R_a being the radial coordinate of the tube and the
29 apical radius respectively, **Fig. 1C, D**). We used s -steps of 0.5 up to $s = 10$, so we
30 were able to explore 19 different values of the basal radius, R_b (**Fig. 1D**). Second, we
31 generated 10 different configurations in terms of the disorder level of the spatial

positions of the cellular seeds on the apical surface and the corresponding Voronoi tessellations (V1 to V10, **Fig. 1D**). To that end, we used a fully random Voronoi tessellation, i.e., randomized positions of cellular seeds, as the most disordered pattern (V1). That configuration was made progressively more uniform (i.e., spatially ordered) after nine successive iterations of the homogenizing Lloyd's algorithm (**Box E** and **STAR Methods**) (**Fig. 1D**). The resulting set of 10 different cellular arrangements (V1 to V10) with increasing order properties conforms a Centroidal Voronoi Tessellation (CVT) scale that has been proved useful to analyze the effect of the topological organization of tissues and to simulate different tissues and/or pathological conditions (Sanchez-Gutierrez et al., 2016; Vicente-Munuera et al., 2020). We used the CVT scale to investigate how the average number of apico-basal intercalations per cell, $\langle i \rangle$, changes as a function of the apico-basal coordinate, s , and the disorder level (**Fig. 1D**). As previously reported, we found that the number of apico-basal transitions (**Fig. 1D**) and scutoids (**Fig. S1**) increased with s (Gómez-Gálvez et al., 2018). As for the effect of the disorder level, we found that only in the case of fully disordered tubes (i.e., V1: random case), and for low values of s , there are more intercalations, whereas for the rest of cases we observed that $\langle i \rangle$ is fairly independent of the CVT scale (**Fig. 1D**).

Energy contributions can be linked to geometric features of the shapes of epithelial cells (Alt et al., 2017), see **Box F-H**. We used the set of Voronoi tubes (V1 to V10) to explore surface tension, elasticity, and apical contractility energies, since these energy contributions have been shown to play key roles in the organization of epithelia (Alt et al., 2017; Farhadifar et al., 2007). As a first step, we estimated the average cellular energy profiles as a function of s in the computational tubular model (**Fig. 1E-G**). The average surface tension energy (**Box F**) is related to the average lateral area of the cells, $\langle A \rangle$, and therefore increase with the surface ratio, s . Our results revealed that $\langle A \rangle$ is seemingly independent of the CVT scale (**Fig. 1E**). Consequently, the average cell surface tension energy profile does not depend on the level of the topological disorder. The contractile energy (**Box G**) is related to the average and the variance of the apical perimeter, L , (Gilbert and Barresi, 2013; Farhadifar et al., 2007) therefore it does not depend on the surface ratio, s . The

1 Voronoi model revealed that $\langle L \rangle$ is CVT independent, but the apical perimeter
2 fluctuations decrease as the CVT scale increases (**Fig. 1F**). Finally, the average cell
3 elastic energy (Gelbart et al., 2012; Odell et al., 1981) depends on the average and
4 the variance of the cellular volume (**Box H**). Since the average cell volume $\langle V \rangle$ is, by
5 construction, independent of the CVT scale (**STAR Methods**), the average cellular
6 elastic energy increases with the cellular volume fluctuations, that in turn decrease
7 with the CVT scale (**Fig. 1G**).

8 In order to evaluate how the appearance of scutoids is modulated by these energy
9 contributions for different values of the tissue thickness, we computed the cross-
10 correlation functions, $C(s)$, between the average cellular energy profiles, $\langle E_Z \rangle$ (Z
11 being A or V , i.e., surface tension or elastic terms), and the average number of apico-
12 basal intercalations, $\langle i \rangle$ (**Fig. 1H** and **STAR Methods**). The cross-correlation measures
13 the similarity between two signals as a function of the displacement (or lag) of one
14 signal relative to the other. In our case the displacement/lag refers to the apico-basal
15 coordinate, s , and consequently we inquire into the possibility that energetic
16 contributions either precede or follow the appearance of apico-basal intercalations.
17 Our results indicate that maximum correlations are obtained at zero lag
18 independently of the disorder level and that the appearance of scutoids correlates
19 more significantly with the surface tension energy profile than with the elastic
20 energy: 95% vs. 80% respectively. The latter is in agreement with previous studies
21 that have shown that surface tension energy minimization is the main cause
22 underlying the appearance of scutoids (Gómez-Gálvez et al., 2018; Gómez et al.,
23 2021; Mughal et al., 2018). Also, when assessing the extra effect of the energy input
24 due to the apical contractility term to the surface tension energy, $\langle E_A \rangle + \langle E_L \rangle$, we
25 found that it increases the correlation between energy profile and the number of
26 intercalations up to 98%, but it does not lead to any change in the correlation due to
27 elastic terms, $\langle E_V \rangle + \langle E_L \rangle$ (**Fig. 1H**).

28 We further examined the cross-correlation between the gradient of cellular
29 intercalations along the apico-basal axis, $\partial_s \langle i \rangle = \partial \langle i \rangle / \partial s$, and the gradient of the
30 energy, $\partial_s \langle E_Z \rangle$. In this way, we evaluated the level of correspondence between the
31 variation of the number of intercalations and the changes of the energy as a function

1 of the radial coordinate, s . We found that, independently of the CVT scale, $\partial_s \langle i \rangle$
2 correlates slightly stronger with changes in the surface tension energy, $\partial_s \langle E_A \rangle$, than
3 with changes of the elastic contribution, $\partial_s \langle E_V \rangle$: $\sim 80\%$ versus $\sim 75\%$ respectively at
4 optimal lag (**Fig. 1I**). Interestingly, $\partial_s \langle i \rangle$ lags behind $\partial_s \langle E_Z \rangle$, i.e., the optimal lag for
5 which $C(s)$ is the largest is located at $s > 0$. Therefore, energy variations along the
6 apico-basal axis seem to precede changes in the number of intercalations that, in
7 turn, suggests an instructive role of the former over the latter.

8 Summing up, the Voronoi tubular model supports the idea that surface tension
9 energy is the more relevant contribution regulating the appearance of apico-basal
10 intercalations, and suggests that elastic terms play a role, yet less important than
11 surface tension, for modulating the intercalation propensity (see **Discussion**).

12

13 **The Voronoi tubular model suggests a link between 3D tissue packing and energy** 14 **cues**

15 To link quantitatively energy traits and 3D packing, we implemented a benchmark
16 able to simultaneously reveal the existence of apico-basal intercalations (scutoids)
17 and the polygonal distribution of cells at the apical and the basal surfaces. To that
18 end, we computed the probability that cells change their polygonal class between the
19 apical and basal surfaces. Thus, the components (i.e., bins) of this distribution along
20 the diagonal account for cells that have the same polygonal class at apical and basal
21 surfaces, whereas the spreading away from the diagonal ensures the existence of
22 scutoids and, consequently, changes in the cellular 3D connectivity (**Fig. 2A** and **STAR**
23 **Methods**). Our data revealed that, regardless of the value of the tissue thickness (and
24 the CVT scale), the dominant apical-basal polygonal class corresponds to cells with six
25 neighbors (**Fig. 2A**). As the tissue thickness, $s_b = R_b/R_a$, increases, more scutoidal
26 shapes with a distinct number of neighbors in apical and basal surfaces appeared.
27 This feature was revealed by the increasing value of the spreading away from the
28 diagonal, η^2 (**STAR Methods** and **Table S1**). In that regard, in agreement with the
29 results shown in **Fig. 1D-G**, our data indicates that η^2 increases with the tissue
30 thickness and decreases with the CVT scale (**Fig. 2B**). Also, the cross-correlation
31 analysis between the spreading coefficient and energy profiles agrees with **Fig. 1H**

1 and reveals that independently of the CVT scale the neighbor exchanges correlate
2 more strongly with the surface tension energy profile than with the elastic
3 contribution: 90% vs. 70% at zero (optimal) lag (**Fig. 2C**). Furthermore, we computed
4 the average number of total contacts between cells (i.e., the average 3D cellular
5 connectivity), $\langle n_{3D} \rangle$, as a function of the surface ratio (i.e., the radial coordinate) and
6 the Voronoi class (i.e., the level of cellular disorder in the tissue) (**Fig. S1**). Our data
7 indicated, that cells, on average, are connected to more than six cells, i.e., $\langle n_{3D} \rangle > 6$,
8 and the results are quantitatively consistent with a mathematical derivation that
9 shows that $\langle n_{3D} \rangle$ is linearly proportional to the number of apico-basal intercalations
10 $\langle i \rangle$: $\langle n_{3D} \rangle = 6 + \langle i \rangle / 2$ (**STAR Methods** and **Fig. S1**).

11

12 The Voronoi tubular model recapitulates the properties of *in vivo* epithelial tubes

13 In order to compare the results obtained in our Voronoi computational tubular
14 models against the properties found in real tissues, we implemented a
15 methodological pipeline that combines several image analysis techniques to
16 accurately reconstruct the 3D shapes of cells of *in vivo* epithelial tubes (Arganda-
17 Carreras et al., 2017; Franco-Barranco et al., 2021; Machado et al., 2019) (**STAR**
18 **Methods**). We used the *Drosophila* larval salivary gland, a cubic monolayer
19 epithelium, as a model due to its ideal characteristics to study complex tubular
20 developmental structures (Girdler and Roper, 2014) (**Fig. 3A**). Also, cellular growth
21 and division, as well as possible global tissue deformation processes, do not occur in
22 the *Drosophila*'s salivary gland at the developmental stage of our observations (i.e.
23 the tissue is static); a fact that enables the comparison with the Voronoi
24 computational model.

25 We determined the average basal surface ratio (thickness) of the salivary glands,
26 $\langle s_b \rangle = 8.5 \pm 1.1$, the average percentage of scutoids, $72 \pm 12\%$, the average 3D
27 connectivity, $\langle n_{3D}(s_b) \rangle = 6.6 \pm 0.2$, and the average number of apico-basal
28 intercalations per cell, $\langle i(s_b) \rangle = 1.2 \pm 0.3$, thus confirming *in vivo* the validity of the
29 formula $\langle n_{3D} \rangle = 6 + \langle i \rangle / 2$ (**STAR Methods** and **Fig. S1**). We also calculated the
30 spreading coefficient of the 3D connectivity, $\eta^2 = 1.2 \cdot 10^{-2}$, (**Fig. 3B**), and the 2D
31 polygonal distributions in the apical and basal surfaces (**Fig. S2**). Interestingly, we

1 observed a small, but significant, increase of the number of hexagons on the basal
2 surface of the wt glands (see **Fig. S2, Table S1**).

3 Further, in order to derive how energy contributions change as a function of the
4 apico-basal coordinate, s , we implemented an algorithm that obtains the concentric
5 radial sections of *in vivo* tubes from apical to basal (Yang et al., 2019) (**STAR**
6 **Methods**). These sections were used to quantify as a function of the surface ratio, s ,
7 the number of apico-basal intercalations, $\langle i(s) \rangle$, the average lateral area, $\langle A(s) \rangle$, and
8 the cellular volume fluctuations, $\sigma_V^2(s)$ (**Fig. 3C**). Similarly to the procedure that we
9 implemented in the Voronoi tubular model (**Fig. 1H, I**), we used these *in vivo* data to
10 perform a cross-correlation analysis between $\langle i \rangle$ and the energy contributions $\langle E_Z \rangle$
11 (Z being A or V , i.e., surface tension or elastic terms). The results indicated that *in*
12 *vivo* intercalations also correlate stronger with surface tension energy contributions
13 than with elastic terms: ~98% vs. ~90% at zero (optimal) lag (**Fig. 3D**). We also found
14 that in this case, by including the extra contribution from the apical contractile
15 energy to the surface tension energy, i.e. $\langle E_A \rangle + \langle E_L \rangle$, slightly decreases the
16 correlation down to ~95% (optimal lag) but does not modify that of the elastic term,
17 i.e. $\langle E_V \rangle + \langle E_L \rangle$ (**Fig. 3D**). As for the cross-correlation between $\partial_s \langle i \rangle$ and $\partial_s \langle E_Z \rangle$, we
18 also found that in *in vivo* tubes it is more significant for the case of the surface
19 tension energy, ~80%, than for the elastic contribution, ~70%. In addition, we also
20 observed a positive lag for $\partial_s \langle E_V \rangle$ that suggests an instructive role of elastic energy
21 variations towards changes in the number of apico-basal intercalations (**Fig. 3E**).

22 Subsequently, we sampled the Voronoi tubular model in terms of the disorder
23 configuration (CVT scale) and the value of the thickness, s_b , that leads to a tube that
24 represents the aforementioned properties observed *in vivo*. We found that the V8 *in*
25 *silico* model with $s_b = 1.75$ displayed a scutoid prevalence, $79 \pm 5\%$, average
26 number of 3D neighbors, 6.72 ± 0.08 , average number of apico-basal intercalations
27 per cell, 1.4 ± 0.1 , and value of the 3D histogram spreading, $\eta^2 = 1.4 \cdot 10^{-2}$,
28 comparable to those found in *in vivo* tubes (**Fig. S3**). Further, the 2D polygonal
29 distributions in the apical and basal surfaces of the V8 model ($s_b = 1.75$) were found
30 to be similar and in agreement with those found in wt salivary glands (**Fig. S2** and
31 **Table S1**). We also observed that the increment apico-basal transitions by means of a

larger surface ratio ($s_b = 10$) leads to an increase of topological disorder (larger variance of cell sidedness, see **Fig. S2** and **Table S1**); a phenomenon that is similar to that observed in T1-transitions (Blankenship et al., 2006; Zallen and Zallen, 2004). Finally, we implemented the cross-correlation analyses between intercalations and energy contributions in the V8 model ($s_b = 1.75$). We obtained similar features as those obtained *in vivo*, including the suggested instructive role of elastic energy variations towards changes in the number of apico-basal intercalations (**Fig. S3**). Altogether, we concluded that the V8 model ($s_b = 1.75$) reproduces the 2D and 3D packing properties of the *Drosophila*'s larval salivary glands.

10

11 **A biophysical model explains the cellular connectivity observed in *in silico* and in** 12 ***vivo* tubular epithelia**

13 In order to explain how the number of 3D neighbors of a cell (i.e., the cellular
14 connectivity) changes as a function of the apico-basal coordinate, we developed a
15 biophysical model. The model is based on a Kolmogorov rate equation and accounts
16 for the probability of cells to increase their 3D connectivity as the radial coordinate
17 along the apico-basal axis changes from s to $s + ds$ (**Fig. 4A, B** and **STAR Methods**):

$$18 \quad \frac{dP_m(s)}{ds} = P_{m-1}(s)r_{m-1,m} - P_m(s)r_{m,m+1} \quad (1)$$

19 This equation determines, as a function of s , the set of probabilities $\{P_m(s)\} =$
20 $P_3(s), P_4(s), \dots, P_{N_{max}}(s)$, i.e., the fractions of cells with a given number, m , of 3D
21 neighbors such that $\sum_m P_m(s) = 1$. Thus, the average 3D cellular connectivity (i.e.,
22 the average number of 3D neighbors per cell) as a function of s reads $\langle n_{3D}(s) \rangle =$
23 $\langle m \rangle = \sum_m m P_m(s)$.

24 In Eq. (1), $r_{m,m+1}$ accounts for the transition “rate” at which 3D are gained, i.e., the
25 probability per unit of s to increase the cellular connectivity by one cell. By drawing
26 parallels between apico-basal intercalations and planar T1 transitions (Bi et al., 2014;
27 Gómez-Gálvez et al., 2018; Sanchez-Corrales et al., 2018) we assumed, following the
28 Eyring model (Eyring, 1935), that cells need to overcome an energy barrier, $\Delta E_m(s)$,
29 to gain a new 3D neighbor, that is, $r_{m,m+1} \sim e^{-\Delta E_m(s)}$ (**Fig. 4A, B**). Our experimental,
30 computational, and analytical results (see **STAR Methods** and **Figs. S4, S5**) support

1 the idea that $r_{m,m+1} = \alpha(N_{max} - m)e^{-m\beta(s)}$, where α is a ‘bare’ transition “rate”,
 2 $\beta(s)$ accounts for the energy cost required to gain one 3D neighbor at a given
 3 position of the apico-basal coordinate, s , and N_{max} is the maximum possible 3D
 4 cellular connectivity for a cell (i.e., if $m = N_{max}$ then $r_{m,m+1} = 0$) (**STAR Methods**).
 5 This model predicts a logistic-like growth of the cellular connectivity (**STAR Methods**).
 6 In order to assess the validity of our model we implemented a fitting/optimization
 7 procedure that provides the value of the model parameters that minimize the error
 8 in the fitting of the curve $\langle n_{3D}(s) \rangle$ (**STAR Methods**). Our results show an excellent
 9 agreement for all values of the CVT scale (**Fig. S6, Table S1**), the computational
 10 tubular model that represents the best in vivo data, i.e. V8 ($s_b = 1.75$) (**Fig. 4C**), and
 11 the wt salivary glands (**Fig. 4D**). We further assessed the goodness of the biophysical
 12 model by predicting accurately the 3D neighbor’s distribution as a function of the
 13 apico-basal coordinate, $\{P_m(s)\}$ (**Fig. 4C, D, Fig. S6**).

14

15 **Genetic perturbations modify the 3D cellular connectivity properties of epithelial** 16 **tubes**

17 Our analyses suggest that surface tension is the energy contribution that affects the
 18 propensity of apico-basal intercalations the most. Surface tension energy originates
 19 in adhesion-mediated interactions between cells that ultimately modulate the
 20 magnitude of cell-cell contacts. Following these ideas, we explored the role of cell-
 21 cell adhesion by experimentally reducing the amount of the E-cadherin (E-cadh). For
 22 this aim, we overexpressed a *UAS-RNAi* line specific for the *shotgun* (*shg*) gene on the
 23 developing *Drosophila* salivary gland (Brand and Perrimon, 1993; Hammond et al.,
 24 2000; Tepass et al., 1996) (**STAR Methods**). We compared the E-cadh antibody
 25 fluorescence profiles in wt and the mutant glands ($\Delta Ecad$) and confirmed the
 26 reduction of E-cadh levels in the latter (**Fig. S7**). The cells in the $\Delta Ecad$ glands bulged
 27 at the basal surface and were smaller than the wt cells (**Fig. 5A, Table S1, Fig. S7**). We
 28 processed these glands to extract their 3D cellular connectivity features and average
 29 energy profiles (**STAR Methods and Table S1**). We determined the effective average
 30 basal surface ratio (**STAR Methods**) of the mutant salivary glands $\langle s_b \rangle = 7.4 \pm 0.8$,
 31 the average percentage of scutoids, $65 \pm 14\%$, the average 3D connectivity,

6.5 \pm 0.2, and the average number of apico-basal intercalations per cell, 1.1 \pm 0.4, (Table S1 , Fig. S7). These values confirm the validity of the formula $\langle n_{3D} \rangle = 6 + \langle i \rangle / 2$ in this genetic background too. Also, the cross-correlation analysis revealed that the surface tension energy remained as the main energy contribution (Fig. S8). Thus, ΔE_{cad} and wt glands reached the same 3D connectivity although the effective surface ratio of the former was smaller (Table S1). These results suggest that a decrease in the cellular adhesion facilitates the emergence of apico-basal intercalations.

The reduction of cellular adhesion decreases the activation energy required to produce apico-basal intercalations

The fitting/optimization procedure of the mutant data showed, as in the case of the wt phenotype and the *in silico* tubes, an excellent agreement (Fig. 5B) that allowed us to estimate the energy-related parameters as summarized by α and $\beta(s)$ (Fig. 5C and Table S1). The estimation of α and $\beta(s)$ in wt and mutant tubes indicated that the energy required to gain an additional neighbor, $\beta(s)$, is larger in *in vivo* tubes than in the computational model independently of the CVT scale (Fig. 5C, Fig. S9, Table S1), see Discussion. Finally, the results obtained from the analysis of the mutant glands confirmed that a decrease in the cellular adhesion facilitates the emergence of apico-basal intercalations since the activation energy gets reduced in the ΔE_{cad} phenotype when compared to the wt case (Fig. 5B and 5C, and Table S1). In particular, in the mutant case, the curve that describes the energetic cost to gain new neighbors as a function of the apico-basal coordinate, $\beta(s)$, lies below the curve of the wt background (Fig. 5C) and we found that the average energy cost, $\bar{\beta}$ (STAR Methods), is $\sim 43\%$ larger in the wt case: $\bar{\beta}_{\Delta E_{cad}} = 0.46$ and $\bar{\beta}_{wt} = 0.65$. Altogether, when we challenged the biophysical model with the perturbation experiment, we obtained the expected results: smaller cellular adhesion leads to a smaller energetic cost to gain new neighbors.

DISCUSSION

1 Here we have shown how a biophysical principle underlies the emergence of
2 functionally complex 3D developmental structures. Namely, cells increase their 3D
3 connectivity in a logistic-like fashion by means of apico-basal intercalations that
4 require overcoming an energy barrier that grows with the number of 3D neighbors.
5 Thus, our analyses explain how the presence of the novel paradigm of epithelial cells'
6 shape and packing, the *scutoid*, affects the cellular connectivity in the third
7 dimension. In that regard, we have shown how the 3D cellular connectivity and
8 tissue energetics are coupled, and we have proposed a quantitative biophysical
9 model to explain that relationship.

10 Our biophysical model relies on a phenomenon observed in the Voronoi
11 computational simulations, supported by mathematical arguments, and confirmed in
12 experiments: the “poor get richer” principle (see **STAR Methods**). Roughly speaking,
13 we have shown that the fewer neighbors a cell has on a surface, the larger is the
14 probability of a 3D cellular connectivity increase. Interestingly, a similar idea has been
15 reported in T1 dynamical processes during the remodeling of planar epithelia where
16 it has been shown that the energy barrier associated with cellular remodeling, rather
17 than being constant, depends on the cellular environment (Bi et al., 2014). Since the
18 scutoidal geometry can be related to planar T1 transitions by exchanging the
19 concepts of space and time, this result reinforces the idea of the existence of
20 universal principles driving the organization of tissues.

21 From the viewpoint of the tissue energetics, both the Voronoi model and *in vivo*
22 tubes, identify the surface tension energy as the main cause of scutoids appearance
23 and hints at the elastic energy as an additional driver for modulating the propensity
24 of cells to undergo apico-basal intercalations. In that context, our results suggest that
25 the so-called ‘bare’ transition rate, α , or even the energy cost required to gain
26 additional neighbors, $\beta(s)$, would depend on both contributions. Related to this,
27 previous studies about the role of fluctuations in the remodeling of cellular
28 aggregates have shown that elastic behaviors (opposed to plastic ones) contribute to
29 reduce the cell stress by lowering the energy barrier that cells need to jump over
30 during cellular rearrangements (Marmottant et al., 2009).

1 In our study we have found that in real tissues (both wt and mutant) the value of
2 $\beta(s)$ is larger than in Voronoi models. We hypothesize that it is due to the purely
3 geometrical description used in the latter. In the *in silico* model the apico-basal
4 intercalations develop as a result of a topological constraint (a Voronoi tessellation)
5 that we have shown describes appropriately the geometrical and packing properties
6 of tubular epithelia. However, in the salivary glands, on top of that constraint, the
7 cells must actively remodel their membranes and cytoskeleton to make the
8 transitions possible. In that context, the cytoskeleton, adhesion molecules, and
9 cellular membranes are responsible for the biophysical properties of epithelia
10 including their energetics (Gómez-Gálvez et al., 2021b). Thus, to challenge the
11 proposed biophysical model we measured the value of $\beta(s)$ in salivary glands where
12 the amount of the adhesion molecule E-cadherin was reduced. Since the 3D connectivity
13 necessarily increases with the surface ratio, the lower effective surface ratio of the
14 mutant gland should correspond with a reduction of the 3D connectivity. However,
15 our results show that wt and mutant glands present the same value of $\langle n_{3D}(s_b) \rangle$
16 (Table S1, Fig. S7), thus indicating that the decrease of adhesion facilitates the
17 appearance of apico-basal intercalations. In terms of the tissue energetics, these
18 results suggest a reduction of the energy barrier required to undergo apico-basal
19 intercalations in the mutant glands. This prediction was confirmed by the biophysical
20 model that provided a lower $\beta(s)$ in the mutant case compared with the wt.

21 As for the technical advances associated to our work, we point out that a high level
22 of detail is necessary to quantify the apico-basal intercalation phenomenon and to
23 compare the *in vivo* data with computational models (Gómez-Gálvez et al., 2021a).
24 Along these lines, the importance of a realistic analysis of 3D cell-cell contacts has
25 been highlighted by recent studies focused on understanding the growth of mouse
26 embryonic lung explants (Gómez et al., 2021) and the early development of *C.*
27 *elegans* (Cao et al., 2020) and Ascidians (Guignard et al., 2020). Our novel
28 methodological pipeline (STAR Methods) allows to implement the accurate 3D
29 reconstruction of cells in epithelia subjected to curvature. This analysis makes
30 possible to quantify how different packing properties, e.g., intercalations, depend on
31 the apico-basal coordinate. These technical improvements are necessary to extract

1 biological consequences about the cellular and mechanical basis of self-organization
2 in curved tissues (Ambrosini et al., 2017; Hirashima and Adachi, 2019; Inoue et al.,
3 2019) or even whole embryos (Shahbazi et al., 2019).

4 As for the broader implications of our findings, our results provide new biological
5 insight into the regulation of cell-cell connectivity in curved tissues. This property
6 ultimately regulates juxtracrine signaling, and is pivotal for early development,
7 primordia patterning, and cell fate determination (Guignard et al., 2020; Sharma et
8 al., 2019; Tung et al., 2012). Moreover, recent research has shown that cellular
9 connectivity regulates the viscosity of tissues (Petridou et al., 2021).

10 Therefore, our findings open new ways to draw implications about primary
11 developmental processes in which epithelial bending is essential such as
12 tubulogenesis, gastrulation, neurulation, and early embryo development. In addition,
13 we argue that, while our analyses focus on static tissues, our results could also be
14 relevant to understand active 3D tissue remodeling. Dynamic changes of $\beta(s)$ would
15 modify the apico-basal intercalation propensity and therefore the material-like
16 properties: the larger $\beta(s)$ the more solid-like the tissue would behave.

17 Recent studies have confirmed that adhesion-dependent active remodeling can be
18 connected to an increased activity of neighbor exchanges. In particular, loss of
19 function mutants of N-cadherin in the presomitic mesoderm of the zebrafish embryo
20 cause an increase in extracellular spaces and a solid-fluid jamming transition
21 (Mongera et al., 2018). In addition, it has been recently shown that the stabilization
22 of E-cad at the cellular junctions in the *Drosophila* eye drives an increase of tension
23 that can be transmitted across the tissue (Founounou et al., 2021). This tension
24 results in a reinforcement of the solid-like tissue behavior. The salivary glands
25 experiments confirm that a reduction of E-cadherin increases the apico-basal
26 intercalation propensity. Our biophysical model predicted that such an increase of
27 the apico-basal intercalation propensity must be correlated with a decrease of the
28 energy barrier $\beta(s)$. Notably, this prediction was confirmed through the biophysical
29 analyses of the ΔE_{cad} samples.

30 Finally, with respect to the applicability of our results to other areas, we expect that
31 the emerging field of organoids will benefit from our discoveries. A precise

quantification of the 3D connectivity could then help to understand the lack of reproducibility in organoid production, one of the biggest challenges of the field (Clevers, 2016; Huch et al., 2017; Schutgens et al., 2019). Also, from a medical point of view, it has been recently shown that tissue curvature affects tumor progression due to the imbalance of tensions in apical and basal surfaces of epithelial tubes (Messal et al., 2019). Our study explains how cell energetics affect the 3D packing of these cells and therefore may shed light on the mechanism of tumorigenic morphogenesis in tubular organs.

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DECLARATION OF INTERESTS

The authors declare no competing interests.

1 **FIGURE TITLE AND LEGENDS**

2 **Box**

3 **A: Scutoids** are prismatic-like geometric solids bounded between two surfaces (top
4 and bottom). Scutoids are characterized by three main properties: i) The shape of
5 their top and bottom bases, and of every parallel section between them, are
6 polygons. ii) The lateral surfaces of scutoids can be concave and/or convex surfaces
7 such that a set of scutoids can be packed together (laterally) without leaving any
8 empty space. iii) Scutoids have at least one vertex along the top-bottom axis such
9 that when packed together there are changes in the nearest-neighbors relationship.
10 The example shows a scheme of a stereotypical scutoid (left) and four scutoids
11 packed together (right).

12 **B: A T1-transition** is a tissue rearrangement observed in epithelial surfaces where a
13 4-cells' motif swaps nearest neighbors along time. T1-transitions enable tissue
14 plasticity through cellular reorganizations that lead, for example, to elongation in
15 developing tissues.

16 **C: An apico-basal transition**, aka an **apico-basal intercalation**, is a tissue
17 rearrangement along the apico-basal (top-bottom) axis of cells that lead to new
18 cellular contacts (nearest-neighbors exchange). An apico-basal transition is similar to
19 the T1-transition but instead of developing along the time it does along space.

20 **D: A 2D tessellation** (aka a 2D mosaic) is a partition of a surface with tiles that do not
21 overlap or leave any gaps. In this example, the tiles are octagons and squares.

22 **E: A 2D Voronoi diagram** is a particular type of tessellation built by convex polygons
23 (Voronoi cells). These polygons emerge from a set of generator seeds (black points),
24 such that each cell contains the region that is closer to its generating seed. The so-
25 called **Lloyd's algorithm** makes the seeds of a Voronoi diagram to converge
26 progressively to the centroids (blue points): once a Voronoi diagram is obtained for a
27 set of seeds (black Voronoi diagram, V_N), an iteration of the Lloyd's algorithm
28 consists in repeating the Voronoi tessellation by replacing the seeds by the centroids
29 of the Voronoi tiles (blue Voronoi diagram, V_{N+1}). The Lloyd's algorithm makes the

1 Voronoi diagram progressively more ordered in terms of the polygonal distribution of
2 the Voronoi cells.

3 **F:** The **surface tension energy** is related to the cell-cell adherence through their
4 lateral area contacts. For each cell, the surface tension energy reads, $E_A = \Lambda A$, where
5 Λ and A are the effective surface tension parameter and the cellular lateral area
6 respectively. Thus, the average surface tension energy of cells reads $\langle E_A \rangle = \Lambda \langle A \rangle =$
7 $E_{\langle A \rangle}$ and is independent of the fluctuations of A .

8 **G:** The **contractile energy** is related to the polarized cortex activity of epithelia cells
9 at the apical surface. The contractile energy reads $E_L = \Gamma L^2$, where L stands for the
10 cellular perimeter at the apical surface and Γ is the cortical tension energy per unit of
11 cell apical area. As a result, the average cell apical contractile energy increases with
12 the fluctuations of the apical perimeter: $\langle E_L \rangle = \Gamma \langle L^2 \rangle = E_{\langle L \rangle} + \Gamma \sigma_L^2$ where
13 $\sigma_L^2 = \langle L^2 \rangle - \langle L \rangle^2$ is the cellular apical perimeter variance.

14 **H:** The cell **elastic energy** is related to the volume conservation of cells. The cell
15 elastic energy reads, $E_V = \frac{Y}{2} (V - V_0)^2$, where Y is proportional to the Young
16 modulus (a quantification of the relationship between the cellular stress and strain)
17 and, V and V_0 represent the *actual* and target cellular volumes respectively. The
18 average elastic energy per cell increases with the fluctuations of the volume:
19 $\langle E_V \rangle = \frac{Y}{2} \langle (V - V_0)^2 \rangle = E_{\langle V \rangle} + \frac{Y}{2} \sigma_V^2$ where $\sigma_V^2 = \langle V^2 \rangle - \langle V \rangle^2$ is the cellular volume
20 variance.

21

22

1 **Figure 1. *In silico* Voronoi epithelial model: energetics and analysis of apico-basal** 2 **cell intercalations in tubes**

3 **A:** (left) Scutoids entail apico-basal intercalations among packing cells that can be
4 envisioned as *spatial* T1 transitions to exchange neighbors (right): the green and the
5 red cells are neighbors in the basal surface (but not in the apical surface) while the
6 opposite is true for the blue and the yellow cells. **B:** *In silico* Voronoi 3D epithelial
7 models are generated by populating with cell seeds (circles) the apical surface, Σ_a .
8 The location of cell seeds at any other surface/plane, Σ , is obtained by implementing
9 apical normal projections, \mathbf{n} , up to the basal surface, Σ_b . At each surface, Σ , a 2D
10 Voronoi tessellation is performed and the 3D cellular shape of the cell is built upon
11 the collection of these tessellations. **C:** (top) In the particular case of tubular
12 epithelia, normal projections of apical cell seeds correspond to radial projections, and
13 the thickness/curvature of tubes are characterized by the surface ratio, $s = R/R_a$
14 (apical/basal surfaces: light/dark blue. R : dashed yellow). (bottom) Illustrative
15 rendering of a Voronoi tube cell. **D:** The so-called CVT scale (iterations of Lloyd's
16 algorithm, **STAR Methods**) measures the topological disorder in *in silico* tubular
17 epithelia and leads to different cellular morphologies. In a V1 (Voronoi 1) model cell
18 seeds are randomly distributed on the apical surface to generate a planar Voronoi
19 tessellation (**STAR Methods**). By applying the Lloyd algorithm iteratively, the apical
20 topological disorder diminishes (top to bottom: V1, V5, and V10 examples). The
21 random location of seeds in V1 implies the emergence of a wide range of different
22 polygonal cell types. As Lloyd's algorithm iterates, the larger the tessellation order is
23 (**Box E**). We observe this progressive ordering from a V1 to V10 as polygonal
24 distributions converge to results with a larger proportion of hexagons and a
25 reduction of the other polygonal shapes (inset: polygon distribution insets for V1, V5,
26 and V10). The average number of apico-basal intercalations per cell in *in silico* tubes
27 ($n = 20$ realizations per CVT scale, each tube composed by 200 cells) increases with
28 the tissue thickness (surface ratio) but does not change significantly with the CVT
29 scale. The black/red/green arrows correspond to the illustrative examples of the
30 planar apical tessellations shown on the left. **E:** The average lateral cell area as a
31 function of the CVT and the surface ratio (values normalized to the V1 case at
32 $s_b = 10$, $n = 20$ per CVT scale) indicates that the average surface tension energy

1 does not depend on the level of topological disorder. **F:** Average (green bar) and
2 standard deviation (red lines) of the apical cellular perimeter as a function of the CVT
3 scale. Values normalized with respect to the V1 case ($n = 20$ per CVT scale). **G:** The
4 cellular volume variance is a proxy for the average elastic cell energy (**STAR**
5 **Methods**). The latter decreases with the CVT scale and increases with the surface
6 ratio (tissue thickness) ($n = 20$ per CVT scale). Volume values were normalized with
7 respect to the V1 case with $\langle V(s_b = 10) \rangle = 1$. **H:** Cross-correlation between average
8 energy profiles along the apico-basal axis, $\langle E_A \rangle$ (dark grey), $\langle E_V \rangle$ (red), and $\langle E_A \rangle +$
9 $\langle E_L \rangle$ (light grey), and the number of apico-basal intercalations, $\langle i \rangle$. Solid lines stand
10 for the averages among disorder configurations (i.e., CVT scale) and the dotted lines
11 delimit the standard deviation band. $\langle E_V \rangle + \langle E_L \rangle$ has not been plotted since the extra
12 contribution of the contractile term, $\langle E_L \rangle$, does not modify the correlation function. **I:**
13 Cross-correlation between energy gradients ($\partial_s \langle E_A \rangle$ and $\partial_s \langle E_V \rangle$) and the gradient of
14 intercalations along the apico-basal axis ($\partial_s \langle i \rangle$). Color code as in **H**.

1 **Figure 2. Three-dimensional packing and connectivity properties of the Voronoi** 2 **tubular model**

3 **A:** (left) Schematic representation of a 3D histogram that accounts for the probability
4 that cells have n_a (number) of neighbors in the apical surface and n_b neighbors in the
5 basal surface. Cells with the same polygonal class in apical and basal surfaces
6 contribute to bins along the diagonal (red squares). The bins spreading away from
7 the diagonal (green squares) ensures the presence of scutoidal cells. E.g.: the red and
8 green cells shown in the plot contribute to the bins indicated in the 3D histogram
9 (red and green stars respectively). (right) 3D histograms of V5 tubes for increasing
10 values of the surface ratio. A larger value of the spreading coefficient, η^2 , (**STAR**
11 **Methods**) indicates an increasing number of scutoids. **B:** Density plot showing the
12 value of the spreading coefficient, η^2 , of 3D histograms as a function of the surface
13 ratio and the Voronoi class in *in silico* tubes ($n = 20$ tubes per CVT scale). **C:** Cross-
14 correlation between average energy profiles along the apico-basal axis, $\langle E_A \rangle$ (dark
15 grey), $\langle E_V \rangle$ (red), and $\langle E_A \rangle + \langle E_L \rangle$ (light grey), and the spreading coefficient, η^2 . Solid
16 lines stand for the averages among disorder configurations (i.e., CVT scale) and the
17 dotted lines delimit the standard deviation band. . $\langle E_V \rangle + \langle E_L \rangle$ has not been plotted
18 since the extra contribution of the contractile term, $\langle E_L \rangle$, does not modify the
19 correlation function.

1 **Figure 3. *Drosophila's* salivary gland analysis**

2 **A:** (top) Full projection of a wildtype salivary gland (cell contours stained by Cy3-

3 labeled phalloidin, **STAR Methods**). (middle) Computer rendering of the segmented

4 salivary gland shown on top. Scale bar $100\mu m$. (bottom) 3D rendering of a

5 representative segmented salivary gland. **B:** Density plot of the 3D distribution of

6 neighbor exchanges between apical and basal surfaces as a function of the number of

7 neighbors in apical, n_a , and basal, n_b , surfaces (as in **Fig. 2A**) in wildtype salivary

8 glands ($n = 20$ glands, 979 cells). **C:** Average profiles of the number of apico-basal

9 intercalations, $\langle i \rangle$, average lateral area, $\langle A \rangle$, and cellular volume fluctuations, σ_V^2 in *in*

10 *vivo* tubes as a function of the apico-basal coordinate, s ($n = 20$ glands, similar to

11 **Fig. 1D-E, G**). **D-E:** Cross-correlation analysis between energy and intercalation

12 profiles (same as **Fig. 1H-I**). The error band indicates in this case the variability among

13 experimental samples ($n = 20$ glands).

Figure 4. Biophysical model: *in silico* and *in vivo* results

A: (top) Cell intercalations along the apico-basal axis can be visualized as spatial T1 transitions (non-reversible: once a neighbor is won it cannot be lost). (bottom) The “poor get richer” principle (**STAR Methods**) suggests an increasing energetic cost (i.e., a larger activation energy) for recruiting new neighbors as a function of the number of neighbors already won. In our model, $\beta(s)$ accounts for the energetic cost per 3D neighbor (per apico-basal intercalation) to recruit a new neighbor (**STAR Methods**). **B:** The energy landscape shown in **B** (bottom) can be modeled by a stochastic dynamics (a Kolmogorov rate equation) where cells increase their 3D neighbors with a probability per unit of surface ratio, $r_{n,m}$, that depends on the activation energy, $\beta(s)$, a ‘bare’ transition rate, α , and the maximum cell connectivity N_{max} (**STAR Methods**). **C:** Results of the Kolmogorov model in V8 ($s_b = 1.75$) *in silico* tubes ($n = 20$). The left/center density plots represent the cellular connectivity distribution (i.e., the fraction/probability of cells with a given number of 3D neighbors) as a function of s obtained in the Voronoi simulation (left) and as predicted by the Kolmogorov model (center); the red circles (left/right) indicate the average number of 3D neighbors per cell $\langle n_{3D} \rangle$; the red line (center/right) shows $\langle n_{3D} \rangle$ as obtained by the Kolmogorov model. The density plot on the right shows the difference between the predicted and the actual connectivity distributions and the corresponding error, ε^2 (magenta lines). **D:** Same as panel **C** but results obtained in salivary glands ($n = 20$ glands). The maximum value of s in the analyzed radial sections of the glands is $s = 6.5$. This value being the largest radial section of the smallest gland (**STAR Methods**).

1 **Figure 5. Biophysical analysis of Δ Ecad salivary glands**

2 **A:** (top) Full projection of a Δ Ecad salivary gland (cell contours stained by Cy3-labeled

3 phalloidin, **STAR Methods**). (bottom) Computer rendering of the mutant salivary

4 gland shown on top. Scale bar $100\mu m$. **B:** Results of the Kolmogorov model for the

5 Δ Ecad salivary gland ($n = 10$ glands). The left/center density plots represent the

6 connectivity distribution (i.e., the fraction/probability of cells with a given number of

7 3D neighbors) as a function of s obtained in the Voronoi simulation (left) and as

8 predicted by the Kolmogorov model (center); the red circles (left/right) indicate the

9 average number of 3D neighbors per cell $\langle n_{3D} \rangle$; the red line (center/right) shows

10 $\langle n_{3D} \rangle$ as obtained by the Kolmogorov model. The density plot on the right shows the

11 difference between the predicted and the actual connectivity distributions and the

12 corresponding error, ε^2 (magenta lines). Same color code than in **Fig 4C-D**. The

13 maximum value of s in the analyzed radial sections of the glands is $s = 5.5$. This

14 value being the largest effective radial section of the smallest gland (**STAR Methods**).

15 **C:** Energy cost required to gain additional neighbors as a function of s (**STAR**

16 **Methods**) for wt glands (green), for Δ Ecad glands (red), and for the V8 ($s_b = 1.75$)

17 model (blue). The inset shows the values of the bare transition rates, α , and the

18 average value (along the apico-basal coordinate) of β .

1 STAR METHODS

2 Immunohistochemistry and confocal imaging of salivary glands

3 Flies were grown at 25 °C using standard culture techniques. The following lines
4 were used: *Oregon R* (*wt*), *UAS-shg-RNAi* (BL38207), *AB1-Gal4* (BL1824). *AB1-Gal4*
5 drives Gal4 protein in the third instar larva salivary gland. We dissected the salivary
6 glands from third instar larvae. After PBS dissection, the glands were fixed using 4%
7 paraformaldehyde in PBS for 20 min. The samples were washed three times for 10
8 min with PBT (PBS, 0.3% Triton) and then incubated for 1 hr 45 minutes at room
9 temperature with Cy3-labeled phalloidin (Sigma) to label the cell contours of the
10 epithelial cells. Stained larval salivary glands were mounted using Fluoromount-G
11 (Southern Biotech). We used two pieces of double-sided adhesive tape (one on top of
12 each other) as a spacer (Aldaz et al., 2013), so the salivary glands preserve their
13 shape. Images were taken using a Nikon Eclipse Ti-E laser scanning confocal
14 microscope. The images were captured using a ×20 dry objective and 2.5 μm steps
15 between slices. The image stacks were exported as 1024 × 1024 pixels TIFF files.

16

17 Quantification of fluorescence intensity

18 The E-cadherin fluorescence intensity was measured in Fiji by using the Plot Profile
19 tool. We used 3 *wt* and 3 Δ Ecad representative glands, taking 10 individual
20 measurements for each sample (**Fig. S7**). We used rectangular ROIs to measure the
21 intensity profiles of lateral cell membrane in the Z-depth where the lumen was
22 visible. In this way, we were able to capture the whole lateral cell membranes from
23 apical to basal. To ensure, a high-quality detection of the cell membrane we
24 developed a maximum Z-projection of those Z-slices where the cell outline of interest
25 and the lumen are clearly visible. Note that the output of the Plot Profile is a 2D plot
26 that displays a “column average plot”, where the *X* axis represents the horizontal
27 distance through the selection (apico-basal cell outline) and the *Y* axis the vertically
28 averaged pixel intensity.

29

1 **3D glands segmentation**

2 To segment the salivary gland stacks of images and reconstruct (semi-automatically)
3 the shape of cells in three dimensions we used the Fiji (Schindelin et al., 2012) plugin
4 LimeSeg (Machado et al., 2019). It infers cell outlines by using surface elements
5 (“Surfels”) obtained by manually placing single ellipsoidal-like seeds on every cell (see
6 <https://imagej.net/LimeSeg> for details). Once cell outlines were found, we exported
7 them as point clouds (output). We developed a custom-made Matlab code (2021a
8 MathWorks) to postprocess the output of LimeSeg in order to correct errors and
9 obtain perfectly segmented salivary glands. In addition, we manually segmented the
10 lumen of the glands using the Volume Segmenter app, in Matlab. To faithfully
11 represent the gland as a cylinder, we selected a subset of cells: cells that were not
12 ductal, neither located at the tip of the gland.

13 To segment mutant salivary glands we took advantage from the 20 segmented wt
14 salivary glands, and we used them as training dataset into a deep-learning
15 segmentation pipeline. We trained a stable 3D-U-Net CNN ((Franco-Barranco et al.,
16 2021), https://github.com/danifranco/EM_Image_Segmentation) using as input the
17 salivary glands phalloidin channel (actin filaments) staining cell outlines, and as target
18 the segmented cell outlines. The output (prediction) of this pipeline was a probability
19 map of cell outlines, that was post-process using the PlantSeg (Wolny et al., 2020)
20 segmentation module to extract individual instances. Here, again, we segmented the
21 lumen of the glands using the Volume Segmenter app, and segmentation errors were
22 curated using our custom-made Matlab code.

23 To obtain the cellular neighborhood relations of salivary glands for different values of
24 the radial expansion, we proceeded as follows. We calculated the cell height by
25 estimating the distance between the centroid of the cell apical surface with respect
26 to the centroid position of its basal surface, $d(s_a, s_b)$. Then, to capture a concentric
27 radial section of the gland, we linearly extrapolated the equivalent cell height to the
28 given surface ratio, s :

$$29 \quad d(s_a, s) = d(s_a, s_b) \frac{s}{s_b} \quad (2)$$

1 where $d(s_a, s)$ is the Euclidean distance between the position of the centroid of the
2 cell at the apical surface, $s_a = 1$, and the position of the centroid at a value
3 $s = R/R_a$ of the radial expansion. Finally, to obtain the gland cylindrical radial
4 section for a given value of the radial expansion, s , we collected all voxels between
5 apical and the upper bound of the calculated distance $d(s_a, s)$.

6

7 **Salivary glands measurements**

8 We quantified the following geometrical and topological/connectivity descriptors of
9 the segmented salivary glands using a custom-made Matlab code:

- 10 - Surface ratio (s): Assuming a cylindrical shape for glands, we estimated s by
11 measuring the minimum distance between each cell apical centroid and
12 lumen skeleton (R_a), and measuring h , the distance between apical cell
13 centroid and cell centroid of an outer cell layer (i.e., basal surface or a
14 concentric layer between apical and basal). Being, the individual surface ratio
15 of a cell, $s_{cell} = \frac{R_{a_{cell}} + h_{cell}}{R_{a_{cell}}}$, we averaged all the individual cell measurements
16 to calculate the representative s value corresponding to a gland, $s = \langle s_{cell} \rangle$.
- 17 - Cell apical perimeter, lateral surface area, and the cellular volume.
- 18 - Number of cell contacts: we measured the number of cell neighbors of each
19 cell surface, that is, apical, basal or lateral. In order to remove artefacts, 2
20 cells must share at least 0.5% of their lateral surfaces area to enable them to
21 be considered as neighbors. n_a , n_b , and n_{3D} of each gland were calculated
22 after averaging the number of cells neighbors along the gland.
- 23 - Percentage of scutoids, average of apico-basal transitions. We quantify the
24 percentage of scutoidal cells that conform the gland and the number of apico-
25 basal transitions in which each cell is involved.

26

27 All the measurements were carried along different concentric radial sections of the
28 glands. We captured the gland thicknesses starting at the apical surface ($s_a = 1$) and
29 increasing progressively the surface ratio by $\Delta s = 0.5$, until reaching the basal
30 surface (s_b). In this way, the number of the captured radial sections will depend on

the s_b value of each gland. To compare the glands of each phenotype (either wt or mutant) in terms of connectivity related with the surface ratio, we used a maximum radial section common to all the glands.

In $\Delta Ecad$ mutant glands, due to their phenotype (cells bulge at the basal surface), we removed the bulging tips of cells to quantify the *effective* surface ratio s^* : the maximum value of the surface ratio up to which cells are contacting (that is, $1 \leq s \leq s^* \leq s_b$). We noticed that the 3D connectivity of cells is not modified by this approach. To remove the volume of cell tips, we captured all lateral and apical surfaces of cells and we filled each cell volume using the *alphaShape* Matlab function.

Voronoi tubular model

Using custom-made Matlab code we generated a Voronoi model that simulates the surface of a cylinder unfolded over the Cartesian plane, see details in Gomez-Galvez et al. ((Gómez-Gálvez et al., 2018), **Methods**). The only difference with the cited methodology, is that in this work the Voronoi diagrams has been constructed by means of the Delaunay triangulation technique. Therefore, we just considered the cells' vertices information (Cartesian coordinates and connections) for a much faster computation. For each realization, we used an initial set of 200 randomly located seeds on a rectangular domain of 512 (X axis; transverse axis of cylinder) per 4096 (Y axis; longitudinal axis of cylinder). We performed this procedure for 10 different initial Voronoi diagrams (Voronoi 1 (V1, random seeds) to Voronoi 10 (V10, more ordered and homogeneous cells). These diagrams represent the apical (inner) surfaces of computational tubes, and they were obtained by applying N-1 times the Lloyd's algorithm (Lloyd, 1982) to the random seeds, where N is then the resulting Voronoi model. For instance, to compute a V1, we use purely random seeds, while to obtain a V4 diagram, it would be required to apply 3 times the Lloyd's algorithm to random seeds. In the limit of the CVT scale (iterations of the Lloyd's algorithm) going to infinity the organization of cells tends to a hexagonal lattice. Subsequent radial sections that define computational tubes with different surface ratios were obtained by implementing a radial projection of the Voronoi seeds. For each apical surface of the tube, we generated 40 expansions by incrementing the surface ratios (s_b) using

0.25 steps: 1 (apical), 1.25, 1.5, ... ,10 (19 s -steps \times 10 apical cell arrangements \times 20 realizations).

As for the 3D reconstruction of cells in Voronoi tubes, each set of seeds that characterizes cells on a given cylindrical section defines a unique 2D Voronoi diagram at every surface and hence the corresponding 2D cellular domains. The set of 2D Voronoi regions that belong to the same radially projected seed from the apical to the basal surface then define each 3D cellular shape. Each of the obtained 3D cells was further processed using the Matlab function '*alphaShape*' to transform the set of voxels into a compact, solid, object. This reconstruction pipeline was implemented using Matlab (2021a).

As for the connection of the CVT scale with the average elastic energy of cells, we first notice that for a given tube of length L , radiuses R and R_a , and with a fixed number of cells, N , the average cell volume, $\langle V \rangle$, is independent of the CVT scale:

$$\langle V \rangle = \frac{1}{N} \sum_{i=1}^N V_i = \pi L (R^2 - R_a^2) / N = \pi L R_a^2 (s^2 - 1) / N. \text{ On the other hand, if cells}$$

have a target volume V_0 then the elastic energy (linear regime) of cell i reads

$$E_{V_i} = \frac{Y}{2} (V_i - V_0)^2, \text{ where } Y \text{ is proportional to the Young's modulus. Consequently,}$$

$$\text{the average cell elastic energy, } \langle E_V \rangle = \frac{1}{N} \sum_{i=1}^N E_{V_i} = E_{\langle V \rangle} + \frac{Y}{2} \sigma_V^2, \text{ where } E_{\langle V \rangle} =$$

$$\frac{Y}{2} (\langle V \rangle - V_0)^2 \text{ is the elastic energy of a cell with an average cell volume } \langle V \rangle \text{ and}$$

$$\sigma_V^2 = \langle V^2 \rangle - \langle V \rangle^2 \text{ is the variance of the cellular volume (the cell size fluctuations).}$$

Since $E_{\langle V \rangle}$ is independent of the CVT scale and σ_V^2 decreases with the CVT scale (i.e., as the tissue becomes more ordered) then the average elastic cell energy necessarily

decreases as the CVT increases. In our simulations and experiments the cellular volume is computed by using the value of cell area sections $\mathcal{A}(s)$ as a function of the

$$\text{surface ratio, } s. \text{ Specifically, we used the trapezoidal rule, } V(s) = \int_{z=s_a}^{z=s} \mathcal{A}(z) dz \approx$$

$$\frac{\Delta s}{2} [\mathcal{A}(s_a) + 2\mathcal{A}(s_a + \Delta s) + \dots + 2\mathcal{A}(s_a + (n-1)\Delta s) + \mathcal{A}(s_a + n\Delta s)]. \quad \text{Where}$$

$$s_a + n\Delta s = s \text{ and } \Delta s = 0.25. \text{ Cell volumes were normalized considering Voronoi 1}$$

tubes from CVT scale as reference, such its average cell volume will represent the

$$\text{unity } \langle V(s_b = 10) \rangle = 1. \text{ Likewise, for estimating the surface lateral area we used the}$$

$$\text{trapezoidal rule using the value of the cellular perimeter, } L(s), \text{ that is: } A(s) =$$

1 $\int_{z=s_a}^{z=s} L(z) dz \approx \frac{\Delta s}{2} [L(s_a) + 2L(s_a + \Delta s) + \dots + 2L(s_a + (n-1)\Delta s) + L(s_a +$
2 $n\Delta s)]$. Besides, we normalized the lateral surface area following the same criterion
3 than with volumes. Additionally, we proceed in a similar way to estimate the cellular
4 lateral area and volume as a function of s in salivary glands.

5

6 **Cross-correlation definition**

7 Dimensionless cross-correlation, $C(s)$, between $X(s)$ (e.g. $\langle E_A(s) \rangle$) and $Y(s)$ (e.g.
8 $Y(s) = \langle i(s) \rangle$) is defined as follows: $C(s) = \frac{1}{N} \sum_{s'} X(s') Y(s + s')$ where $N =$
9 $(\sum_{s'} X(s')^2 \sum_{s'} Y(s')^2)^{1/2}$ is a normalization constant such that the auto-
10 correlation becomes one (at maximum) at zero lag. When required, spatial
11 derivatives were estimated as $\partial_s F(s) = \frac{F(s+\Delta s) - F(s)}{\Delta s}$.

12

13 **Voronoi tubular model measurements.**

14 We measured the following properties of cells in Voronoi tubular models: area,
15 perimeter and number of sides of cells for a given radial section, and total number
16 neighbors. Additionally, we computed the percentage of scutoids, the number of
17 apico-basal transitions, the polygon distribution of every surface (radial sections). In
18 these quantifications, we disregarded cells at the boundaries (tips of tubes) to avoid
19 'border effects'.

20

21 **Relation between total accumulated 3D neighbors and the number of** 22 **intercalation events**

23 Scutoids have a Euler characteristic $\chi = 2$ such that $V - E + F = 2$, where V , E ,
24 and F accounts for the number of vertexes, edges, and faces respectively. We
25 assumed that the apical, a , and basal, b , faces of scutoids tessellating a cylindrical
26 space have radial coordinates R_a and R_b respectively. Then, for any value of the
27 surface ratio expansion, $s = R/R_a$, these solids can be mapped into a connected
28 plane graph with the same Euler characteristic (a sort of projection of the vertexes
29 and connectors into the plane, see **Fig. S10**. Thus, as a function of s , the accumulated

1 number of 3D neighbors reads $n_{3D}(s) = E(s) - V(s)$. Since in tubular geometries
 2 the radially projected seeds from the apical to the basal surface never come closer,
 3 as s increases (i.e., apico-basal intercalations are not reversible).

$$4 \quad n_{3D}(s) = \max(\{V(s)\}) = \min(\{V(s)\}) + i(s) \quad (3)$$

5 where $\{V(s)\} = \{V(1), V(1 + ds), \dots, V(s_b)\}$ and $i(s)$ denotes the number of
 6 intercalation points in the interval $s \in [1, s_b]$. In the case of a 3D tessellation with N
 7 cells, where M of them do not show any intercalation, the total number of
 8 accumulated neighbors reads,

$$9 \quad n_{3D}(s) = \sum_{j=1}^N n_{3D}^{(j)}(s) = \sum_{j=1}^M V^{(j)}(1) + \sum_{j=1}^{N-M} \max(\{V^{(j)}(s)\}) = \\ 10 \quad \sum_{j=1}^M V^{(j)}(1) + \sum_{j=1}^{N-M} \{\min(\{V^{(j)}(s)\}) + i^{(j)}(s)\} \quad (4)$$

11 Given that each intercalation point is shared by four cells, two of them necessarily
 12 increase their number of vertices in a given s -plane and two of them decrease their
 13 number of vertices. Thus, in the case of a decrease $\max(\{V^{(j)}(s)\}) = V^{(j)}(1)$ and in
 14 the case of an increase $\min(\{V^{(j)}(s)\}) + i^{(j)}(s) = V^{(j)}(1) + i^{(j)}(s)$. Consequently,

$$15 \quad n_{3D}(s) = \sum_{j=1}^N V^{(j)}(1) + \sum_{j=1}^{(N-M)/2} i^{(j)}(s) = \sum_{j=1}^N V^{(j)}(1) + \frac{1}{2} \sum_{j=1}^{N-M} i^{(j)}(s) \quad (5)$$

16 where we used the fact that for every intercalation event that increases by one the
 17 number of neighbors there is one that decreases the number of neighbors in the
 18 same amount; consequently, we can add up all intercalation events and divide by
 19 two. Hence the average number of accumulated 3D neighbors, $\langle n_{3D}(s) \rangle = n_{3D}(s)/N$
 20 reads $\langle n_{3D}(s) \rangle = \langle V(1) \rangle + \langle i(s) \rangle / 2$; $\langle i(s) \rangle$ being the average number of apico-basal
 21 intercalations per cell. Finally, by considering that any s -surface, and in particular the
 22 apical surface $s = 1$, corresponds to a 2D tessellation of convex polygons, $\langle V(1) \rangle = 6$
 23 we conclude that,

$$24 \quad \langle n_{3D}(s) \rangle = 6 + \frac{1}{2} \langle i(s) \rangle \quad (6)$$

25

26 **The 3D neighbor's accumulation in tubular epithelia follows a “poor get richer”**
 27 **principle**

28 In order to investigate additional phenomena that could help to understand how
 29 the 3D cellular connectivity is regulated, we computed the net gain of cellular

1 neighbors in epithelial tubes as a function of the 2D polygonal cell class at the apical
2 surface. We observed, both in the salivary glands and in the Voronoi model (in
3 particular in the case V8 ($s_b = 1.75$) that compares the best with *in vivo* glands), that
4 the smaller the number of neighbors of a cell at the apical surface, the larger the net
5 gain of 3D cellular contacts (**Fig. S4**). This behavior was also obtained with respect to
6 the 2D polygonal cell class at the basal surface (**Fig. S4**). These results suggest that, in
7 terms of the cellular packing, tubular epithelia follow a “poor get richer” principle:
8 the less neighbors a cell has in a surface (apical or basal), the larger the net increase
9 of 3D cellular contacts.

10

11 In Voronoi tubes the net gain of 3D neighbors is bounded

12 The “poor get richer” behavior can be justified by mathematical arguments that
13 show that the probability to increase the cellular connectivity necessarily decreases
14 with the number of current neighbors (**Fig. S5**). Assuming a cylindrical geometry (e.g.,
15 epithelial tubes), each point at a given radial surface can be represented into the
16 Cartesian plane; where coordinate x accounts for the cylindrical transversal
17 coordinate and coordinate y for the longitudinal one (see **Fig. S5**). Thus, if the
18 coordinates of a point (e.g., a Voronoi seed) at the apical surface are given by (x, y) ,
19 the coordinates of that point at a surface with a value of the cylindrical radial
20 expansion $s \in [1, \infty)$ can be found by defining the function $f_s: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $f_s(x, y) =$
21 (sx, y) . Under these conditions, we aim to characterize the seeds that generate
22 scutoids (exchanges in the neighboring relations of seeds) as s changes.

23 *Lemma 1.* Given three non-colinear points $\{A, B, C\}$ that define a circle (a nearest-
24 neighbors relation), and another exterior point D , if $s > 1$ exists such that $f_s(D)$ is
25 interior to the circle defined by $\{f_s(A), f_s(B), f_s(C)\}$, then D is inside of the vertical
26 parabola containing $\{A, B, C\}$ (**Fig. S5**).

27 *Remark.* If two of the three points $\{A, B, C\}$ are on the same vertical line, then the
28 parabola considered in Lemma 1 degenerates as a vertical strip. Even in this case, the
29 thesis of the Lemma is true if we replace the interior of the parabola by the inside of
30 the strip.

1 *Proof.* Without loss of generality, we can suppose that $\{A, B, C\}$ are
2 counterclockwise oriented and that they have Cartesian coordinates (a_1, a_2) ,
3 (b_1, b_2) and (c_1, c_2) respectively.

4 Thus, the point $D(x, y)$ is outside the circle defined by $\{A, B, C\}$ if, and only if, the
5 sign of the following determinant is negative:

$$6 \begin{vmatrix} a_1 & a_2 & a_1^2 + a_2^2 & 1 \\ b_1 & b_2 & b_1^2 + b_2^2 & 1 \\ c_1 & c_2 & c_1^2 + c_2^2 & 1 \\ x & y & x^2 + y^2 & 1 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 & a_1^2 & 1 \\ b_1 & b_2 & b_1^2 & 1 \\ c_1 & c_2 & c_1^2 & 1 \\ x & y & x^2 & 1 \end{vmatrix} + \begin{vmatrix} a_1 & a_2 & a_2^2 & 1 \\ b_1 & b_2 & b_2^2 & 1 \\ c_1 & c_2 & c_2^2 & 1 \\ x & y & y^2 & 1 \end{vmatrix} < 0 \quad (7)$$

7 For the sake of simplicity, we represent the previous equation as:

$$8 \det(\mathcal{A}) = \det(\mathcal{B}) + \det(\mathcal{C}) < 0 \quad (8)$$

9 On the other hand, by considering x and y as variables, the equation $\det(\mathcal{A}) = 0$
10 corresponds to the circle defined by $\{A, B, C\}$, and $\det(\mathcal{B}) = 0$ corresponds to the
11 vertical parabola defined by the same three points. Consequently, the inequality
12 $\det(\mathcal{B}) > 0$ defines the locus of interior points to that parabola.

13 Now, assuming that $s > 1$ exists such that $f_s(D)$ is interior to the circle defined by
14 $\{f_s(A), f_s(B), f_s(C)\}$. Then,

$$\begin{vmatrix} sa_1 & a_2 & s^2a_1^2 + a_2^2 & 1 \\ sb_1 & b_2 & s^2b_1^2 + b_2^2 & 1 \\ sc_1 & c_2 & s^2c_1^2 + c_2^2 & 1 \\ sx & y & s^2x^2 + y^2 & 1 \end{vmatrix} = s^3 \det(\mathcal{B}) + s \det(\mathcal{C}) > 0 \quad (9)$$

15 Or, equivalently, $s^2 \det(\mathcal{B}) + \det(\mathcal{C}) > 0$, so, $s^2 \det(\mathcal{B}) > -\det(\mathcal{C})$. If $\det(\mathcal{B}) <$
16 0 , then $1 < s^2 < -\frac{\det(\mathcal{C})}{\det(\mathcal{B})}$ and therefore $\det(\mathcal{B}) > -\det(\mathcal{C})$. The latter is in
17 contradiction with $\det(\mathcal{B}) + \det(\mathcal{C}) < 0$. As a result, $\det(\mathcal{B}) > 0$, and the following
18 inequality holds,

$$s^2 > -\frac{\det(\mathcal{C})}{\det(\mathcal{B})} > 1 \quad (10)$$

19 Notice that if the circle defined by $\{A, B, C\}$ is surrounded by a set of points and we
20 change continuously the parameter s in the interval $[1, \infty)$, it is possible to detect the
21 first point touching the circle defined by $\{f_s(A), f_s(B), f_s(C)\}$. That point can be

1 obtained by computing all the points at $s = \sqrt{-\frac{\det(C)}{\det(B)}}$. Hence, the first point
2 contacting the circle will be that with the minimum value of s .

3 As for proving that the average of the number of neighbors of a cell induced by a
4 seed grows is bounded as a function of the surface ratio, we state the following
5 proposition:

6 *Proposition 1.* Given a Voronoi seed representing a cell, if $n_{3D}(s)$ is the total
7 number of accumulated cell neighbors as s increases from $s = 1$ (apical surface) to a
8 given value of s , then $\langle n_{3D}(s) \rangle$ is a bounded function for a finite cylinder.

9
10 *Proof.* We model the apical surface as the cylinder $2\pi r \times h$, where r represents the
11 inner radius and h the length of the cylinder. Given a seed A in that surface, in the
12 corresponding Delaunay triangulation it appears as a point surrounded by triangles
13 defining the neighborhood of A . By Lemma 1, each triangle defines a vertical
14 parabola and a circle. So, any other seed touching A in other layer must be inside of
15 one of the parabolas and outside of all circles (see **Fig. S5**). Let's denote $\mathcal{R}_{s,A}$ the
16 feasible region for a new neighbor of A in the layer represented by s , i.e., all points
17 inside one of the parabolas and outside all the circles. Thus, if $\#(\mathcal{R}_{s,A})$ is the number
18 of seeds in that region that are not neighbors of A in the apical surface, obviously, an
19 upper bound to the number of new neighbors to A is given by $\#(\mathcal{R}_{s,A}) \leq \#(\mathcal{R}_{1,A})$.

20
21 On the other hand, that number of seeds is, in average, proportional to the density
22 of seeds times the area of $\mathcal{R}_{s,A}$, therefore, the average number of accumulated
23 neighbors of A , denoted as $\langle n_{3D}(A) \rangle$, will be bounded by the change of the density of
24 points when growing s , this is to say,

$$25 \quad d\langle n_{3D}(A) \rangle \leq M \cdot \frac{\mathcal{R}_{s,A}}{2\pi sr \cdot h} ds \quad (11)$$

26 where M represents the total number of seeds (i.e., the total number of cells that is
27 a constant) and the quotient is the area of $\mathcal{R}_{s,A}$ divided by the area of a given radial
28 layer. In general, it is not possible to integrate equation (4), since the area of $\mathcal{R}_{s,A}$ is
29 known only in very few, particular, cases.

In the case of a finite cylinder, $\langle n_{3D}(A) \rangle \leq \#(\mathcal{R}_{s,A}) \leq \#(\mathcal{R}_{1,A})$ leads, summing up to all the seeds and dividing by M , to the upper bound

$$\langle n_{3D}(s) \rangle \leq \frac{1}{M} \cdot \sum_A \#(\mathcal{R}_{1,A}) \quad (12)$$

thus, $\langle n_{3D}(s) \rangle$ is necessarily a bounded function. This expression indicates that the number of new neighbors when increasing s exhausts since the number of cells is a resource shared by all the layers. It is possible to obtain an upper bound to $N_{max} = \lim_{s \rightarrow \infty} \langle n_{3D}(s) \rangle$ since, after a flip in the Delaunay triangulation, the edge disappearing (i.e., a cell contact loss) can never be recovered in a cylindrical geometry. Thus, $M \cdot (N_{max} - n_{3D}(1))$ is bounded by the number of edges that complement the original Delaunay triangulation on the apical surface, that is,

$$N_{max} - \langle n_{3D}(1) \rangle \leq \frac{1}{M} \cdot \left(\frac{M(M-1)}{2} - M \frac{\langle n_{3D}(1) \rangle}{2} \right) = \frac{M-1}{2} - \frac{\langle n_{3D}(1) \rangle}{2} \quad (13)$$

leading to

$$N_{max} \leq \frac{M-1}{2} + \frac{\langle n_{3D}(1) \rangle}{2} \leq \frac{M-1}{2} + 3 = \frac{M+5}{2} \quad (14)$$

Where we have assumed that $\langle n_{3D}(1) \rangle = 6$. The simulations of the computational Voronoi model and the data of the salivary gland show that N_{max} is in fact much smaller than the theoretical bound $\frac{M+5}{2}$.

17

18 A Kolmogorov rate equation for the 3D cellular connectivity

The equation for how the probability, P_m , of having m accumulated 3D neighbors (i.e., $m = n_{3D}$) changes as the surface ratio (apico-basal dimensionless radial coordinate) increases from s to $s + ds$ can be described by the following Markov equation (Fig. 4A-B),

$$P_m(s + ds) = P_m(s)T_{m,m} + P_{m-1}(s)T_{m-1,m} \quad (15)$$

where $T_{n,m}$ is the probability of changing the number of neighbors from n to m due to an apico-basal intercalation. Since $\sum_m T_{n,m} = 1$ (normalization of the transition probabilities) and $T_{n,m} = f(n, m) \{ \delta_{n-1,m} + \delta_{n,m+1} \}$ (each intercalation can only possibly induce to win one neighbor) then $T_{m,m} = 1 - T_{m,m+1}$ and the above Markov equation can be written as a Kolmogorov equation (a.k.a. Master equation):

$$\frac{dP_m(s)}{ds} = P_{m-1}(s)r_{m-1,m} - P_m(s)r_{m,m+1} \quad (16)$$

where $r_{n,m}$ accounts for the probability of apico-basal intercalations per unit of surface ratio, i.e., $T_{n,m} = r_{n,m}ds$. We point out that our model accounts for apico-basal intercalations that occur due to curvature effects such that $s = R/R_a$ changes along the apico-basal coordinate of cells (i.e., bending, folding). Thus, our model does not capture the apico-basal intercalations that develop due to active cellular processes (e.g. cellular extrusion, cell divisions) either in bended tissues or in the case of tissue planar geometries.

By following the Eyring model (Eyring, 1935), i.e., if we assume an Arrhenius-like kinetics such that to win neighbors there is an energy cost (see (Bi et al., 2014)) then $r_{m,m+1} = \hat{\alpha}e^{-\Delta E_m}$, where $\hat{\alpha}$ is the so-called pre-exponential factor that modulates the “bare” frequency of intercalations (per unit of surface ratio expansion, s) and ΔE_m is a dimensionless activation energy (in units of the effective thermal energy associated with membrane fluctuations ξ (Marmottant et al., 2009)). The observed “poor get richer” behavior suggests that the activation energy, ΔE_m , increases with m . This can be explained as a result of a cumulative process if we assume that each neighbor that is gained implies to overcome an energy barrier, $\beta(s)$, through an apico-basal intercalation. Consequently, $e^{-\Delta E_m} = \prod_{n=1}^{n=m} e^{-\beta(s)} = e^{-m \cdot \beta(s)}$. Thus, $\beta(s)$ represents the dimensionless activation energy of a cell per 3D neighbor or, in the context of the different energetic contributions reviewed in this manuscript, to the energy barrier required to perform a spatial T1-transition following a surface energy minimization process (Gómez-Gálvez et al., 2018; Mughal et al., 2018). As for the dependence of β on s , the simplest mathematical form that recapitulates the fact that the apical and basal surfaces accumulate more cell-cell adherent complexes (either in wt or mutant phenotypes) is quadratic (**Fig. S7**): $\beta(s) = \beta_0 \left(1 + \frac{\delta}{2}(s - s_0)^2\right)$. The average, along the apico-basal coordinate, of the energy cost then reads $\bar{\beta} = 1/(s_b - 1) \int_1^{s_b} \beta(s) ds$. On the other hand, the mathematical calculations indicate that the intercalation rate $r_{m,m+1}$ becomes null for a finite value of m or, alternatively, that the activation energy becomes infinite for a finite value of m . Otherwise, the net gain of new neighbors is not bounded. This fact can be accounted

1 for by assuming that the bare frequency is a function of the number of neighbors,
2 $\hat{\alpha} = \hat{\alpha}(m)$, such that $\frac{d\hat{\alpha}}{dm} < 0$ and becomes null for a finite value of m . For the sake of
3 simplicity, we assume that up to first order in m : $\hat{\alpha} = \alpha(N_{max} - m)$, where N_{max} is
4 the asymptotic, maximum, number of 3D neighbors a cell can possibly have.
5 Summarizing, the apico-basal intercalation rate $r_{m,m+1}$ reads,

$$6 \quad r_{m,m+1} = \alpha(N_{max} - m)e^{-m\beta(s)} \quad (17)$$

7 Under these conditions, the Kolmogorov equation reads,

$$8 \quad \frac{dP_m(s)}{ds} = \alpha(N_{max} - (m-1))e^{-\beta(s)(m-1)}P_{m-1}(s) - \alpha(N_{max} - m)e^{-\beta(s)m}P_m(s) \\ 9 \quad (18)$$

10 On the other hand, the equation satisfied by the average number of accumulated
11 3D neighbors, $\langle n_{3D} \rangle = \langle m \rangle$, reads,

$$12 \quad \frac{d\langle m(s) \rangle}{ds} = \sum_m m \frac{dP_m(s)}{ds} = \sum_m r_{m,m+1}P_m(s) = \langle r_{m,m+1} \rangle \quad (19)$$

13 We notice that this equation implies an important role of the disorder (i.e. the
14 distribution P_m): even in conditions under which the transition rate, $r_{m,m+1}$, is
15 “large”, the resulting growth of 3D neighbors, $\frac{d\langle m(s) \rangle}{ds}$, and, consequently, the net
16 accumulation of 3D neighbors, can be more prominent in conditions where the
17 transition rate is “small”. To illustrate this effect, we consider the following example.
18 For the sake of simplicity, we evaluate the initial growth of 3D neighbors starting
19 from the apical surface, i.e. we particularize Eq. (19) to the case $s = 1$ (and hence
20 according to Euler's formula $\langle P_m(1) \rangle = \sum_m mP_m(1) = 6$) and consider two possible
21 conditions: a fully ordered (o) distribution with $P_m^o = \delta_{m,6}$ (i.e., all hexagons) and a
22 disordered (d) condition that combines with equal probability cells with 3, 6, and 9
23 sides in the apical surface, i.e. $P_m^d = \frac{1}{3}(\delta_{m,3} + \delta_{m,6} + \delta_{m,9})$. We also assume that
24 $\beta(s) \simeq \bar{\beta}$ (i.e., we approximate the energy cost to gain new 3D neighbors by its
25 average) and that $\bar{\beta}^o < \bar{\beta}^d$, and also that $\alpha^o < \alpha^d$ (**Fig. S9**). Under these conditions,
26 for the same N_{max} , the following holds, $r_{m,m+1}^o > r_{m,m+1}^d$, that is, the transition rate
27 to gain new 3D neighbors is larger in the ordered case than in the disorder case. This
28 is in fact the situation that we observed in the Voronoi tubular model when we

1 estimated the value of the energy barrier to gain new neighbors: α and $\beta(s)$
2 decrease as the CVT scale increases even though the surface tension energy is
3 independent of the CVT scale (see **Fig. S9**, **Fig. 1**, and **Table S1**). However, it is
4 possible to find large regions in terms of the values of $\bar{\beta}^o$, $\bar{\beta}^d$, α^o , and α^d where
5 $\frac{d\langle m(1) \rangle}{ds} \Big|_d > \frac{d\langle m(1) \rangle}{ds} \Big|_o$ (**Fig. S11**). That is, the growth of 3D neighbors starting from the
6 apical surface (i.e. $s = 1$) in the disorder case can be actually larger than that of the
7 order case despite the fact that the transition rate to gain new 3D neighbors is
8 smaller in the former.

9 Also, from Eq. (19), it is possible to infer, approximately, the expected behavior of
10 $\langle m(s) \rangle = \langle n_{3D}(s) \rangle$ as follows. First, by performing a mean-field-like approximation,
11 i.e., $\langle F(m) \rangle \approx F(\langle m \rangle)$,

$$12 \quad \frac{d\langle m \rangle}{ds} \approx \alpha(N_{max} - \langle m \rangle)e^{-\beta(s)\langle m \rangle} \quad (20)$$

13 Second, assuming that $\beta(s) < 1$ (otherwise it is difficult to justify the observed
14 presence of apico-basal intercalations),

$$15 \quad \frac{d\langle m \rangle}{ds} \approx \alpha(N_{max} - \langle m \rangle)(1 - \beta(s)\langle m \rangle) + \mathcal{O}(\beta^2) \quad (21)$$

16 Eq. (21) is formally a logistic-like growth equation that can be solved subjected to the
17 condition $\langle m(1) \rangle = 6$ (the average number of neighbors in the apical surface is 6).

18 We notice that in this case, the disorder levels of the wt and the mutant glands are
19 similar. Consequently, the accumulation of 3D neighbors only depends on the
20 transition rates, $r_{m,m+1}$, that in turn are larger in the mutant background since the
21 energy barrier decreases.

22 For finding the parameters of the Kolmogorov model, Eq. (19), that better fit *in silico*
23 tubes and salivary glands we implemented an algorithm that solves, numerically, the
24 set of equations defined by Eq. (19) and the normalization condition $\sum_{m=1}^{\infty} P_m(s) = 1$
25 to obtain $\langle m(s) \rangle = \sum_m m P_m(s)$. Such algorithm minimizes the error between the
26 curves $\langle m(s) \rangle$ obtained in the model and in experiments.

27 The values of the parameters obtained were further used to compare the predicted
28 probability distribution of having m accumulated 3D neighbors for a given value of s :
29 $\{P_m(s)\}$. We evaluated the relative error of this prediction with respect to the actual

1 distribution from data, $P_m^{actual}(s)$, by computing $\varepsilon^2 = \frac{1}{2} \sum_m \left(P_m^{actual}(s) - P_m(s) \right)^2$.
 2 This quantity is normalized such that in case of the following situation of full
 3 disagreement between the distributions, $P_m^{actual}(s) = \delta_{m,i}$ and $P_m(s) = \delta_{m,j}$ with
 4 $i \neq j$, provides $\varepsilon^2 = 1$ (i.e., 100% error).

5

6 **Quantitative characterization of spreading in neighbor exchange distributions** 7 **between apical and basal surfaces**

8 In order to characterize the spreading away from the diagonal in the neighbor
 9 exchange distributions between apical and basal surfaces, e.g., **Fig. 2A**, we followed
 10 the same approach used to quantify intrinsic noise during gene expression processes,
 11 see (Elowitz, 2002). Thus, $\eta^2 = \frac{\langle (n_a - n_b)^2 \rangle}{2\langle n_a \rangle \langle n_b \rangle}$ where
 12 $\langle z(n_a, n_b) \rangle = \sum_{n_a, n_b} z(n_a, n_b) p(n_a, n_b)$; z representing any function of n_a and n_b
 13 and $p(n_a, n_b)$ being the probability of neighbor exchange events. We point out that
 14 bins in the diagonal do not correspond necessarily to prismatic cells since a fraction
 15 of cells can conserve the polygonal class in apical and basal surfaces and yet
 16 undergo apico-basal intercalations.

17

18 **Statistical comparisons**

19 The characteristics extracted from wildtype and mutant glands were compared by
 20 using a univariate statistical protocol (**Table S1**). This procedure allows to study if the
 21 data from two different groups of data follow a similar distribution: 1) we evaluated
 22 whether features values of these two kinds of glands presented normal distribution
 23 and similar variance using the Shapiro-wilk test and two-sample F-test respectively.
 24 2) If data followed a normal distribution and had similar variance, we employed the
 25 two-tailed Student's t-test. 3) In case, data presented a normal distribution but not
 26 equal variance we employed the two-tailed Welch test to compare means from both
 27 groups. 4) When data did not present normal distribution, we used the Wilcoxon test
 28 to compare medians from both groups.

29 In a different statistical analysis, we tested polygon distribution similarity from
 30 apical and basal surfaces of wildtype and mutant glands and V8 at $s_a = 1$, $s_b = 1.75$

1 and $s_b = 10$ (**Table S1**). Following the guidelines from (Sánchez-Gutiérrez et al.,
2 2016), we implemented chi-squared tests across all samples, being corrected for
3 multiple testing using the method of Benjamini and Hochberg. To develop a more
4 robust analysis, we used the distribution of 5-, 6- and 7-sided polygons due to the
5 low presence (or inexistence) of the other kind of polygons (3-, 4-, 8-, 9-sided cells).

6

7 **Data and code availability**

8 All the necessary materials to reproduce this study are available at Mendeley Data
9 repository: DOI: 10.17632/gpz68wzhc2.1 and <https://osf.io/nd5t6/>.

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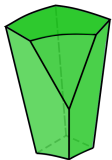
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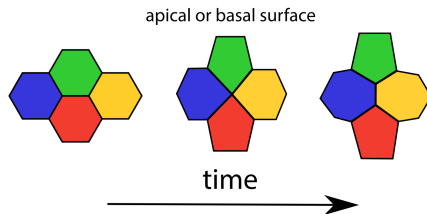
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A



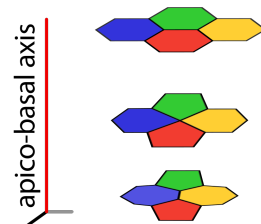
Scutoids

B



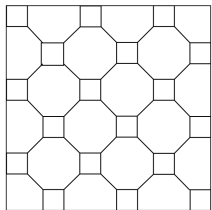
T1-transition

C



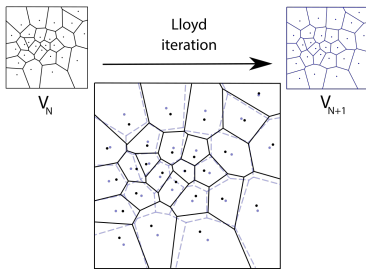
Apico-basal transition

D



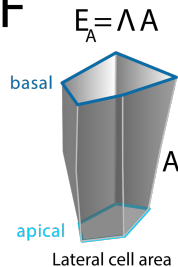
Tessellation

E

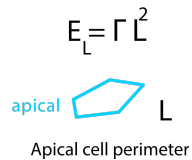


Voronoi diagram

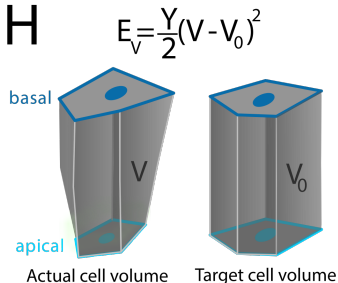
F

Surface tension
energy

G

Contractile
energy

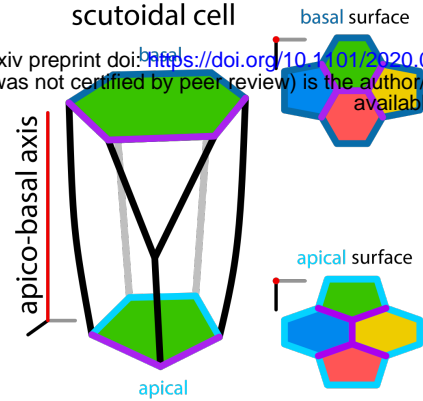
H



Elastic energy

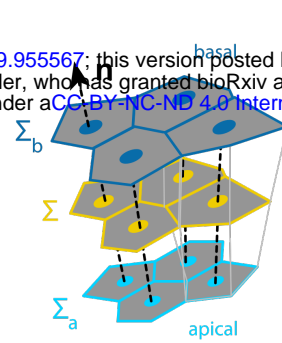
A

scutoid cell



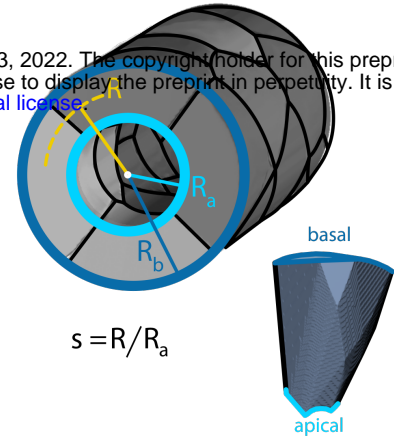
B

Voronoi model

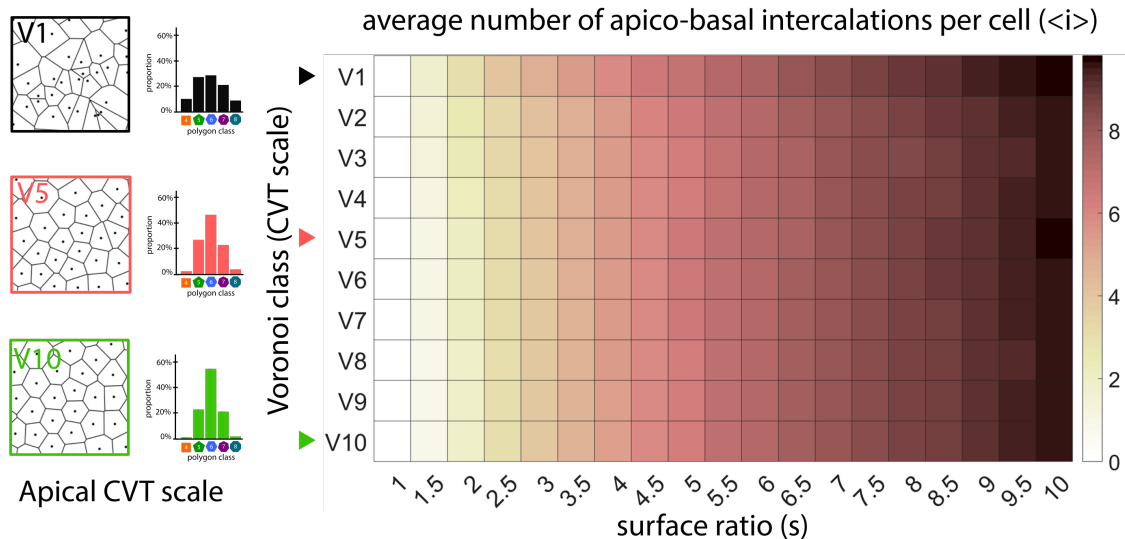


C

Voronoi tube

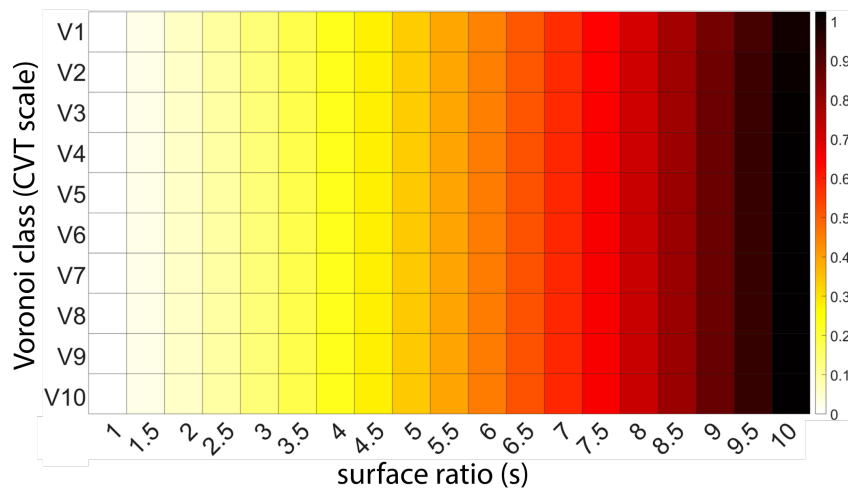


D



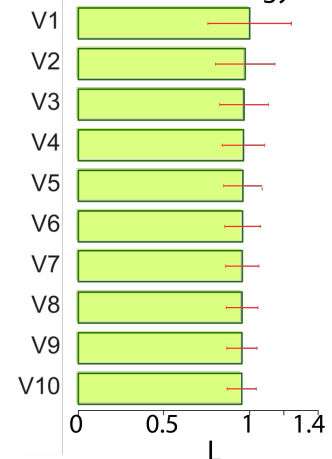
E

cell lateral area: surface-tension energy



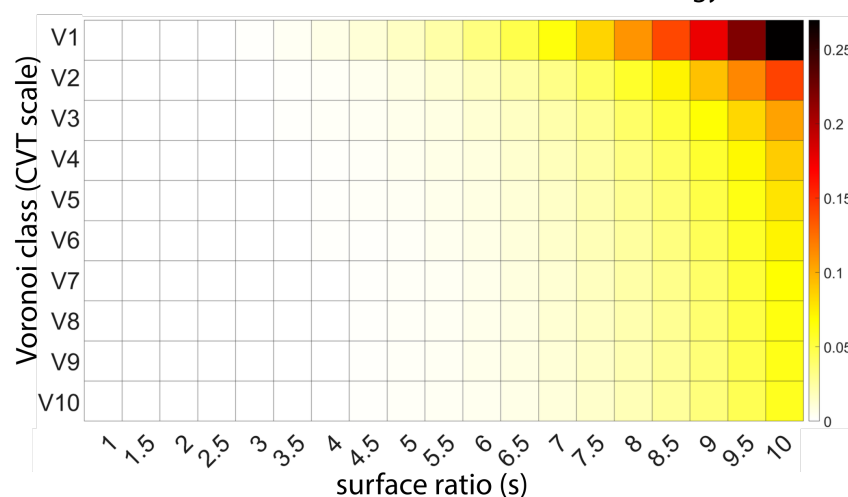
F

apical perimeter: contractile energy

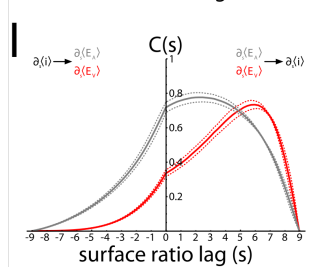
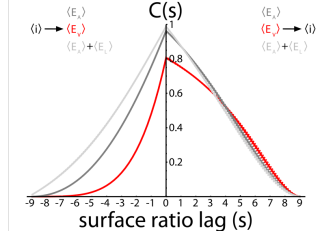


G

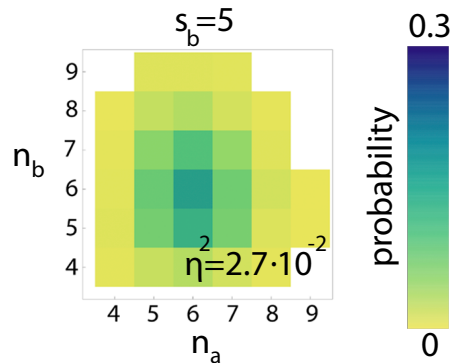
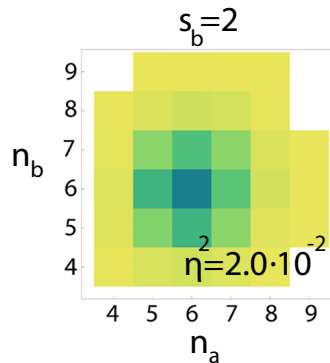
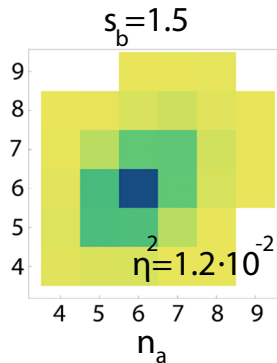
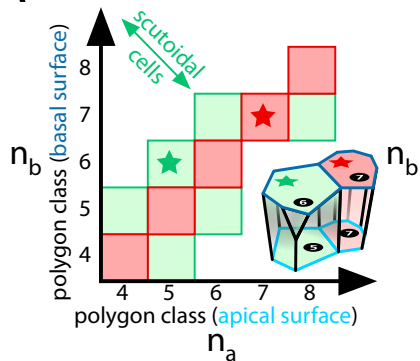
cellular volume fluctuations: elastic energy



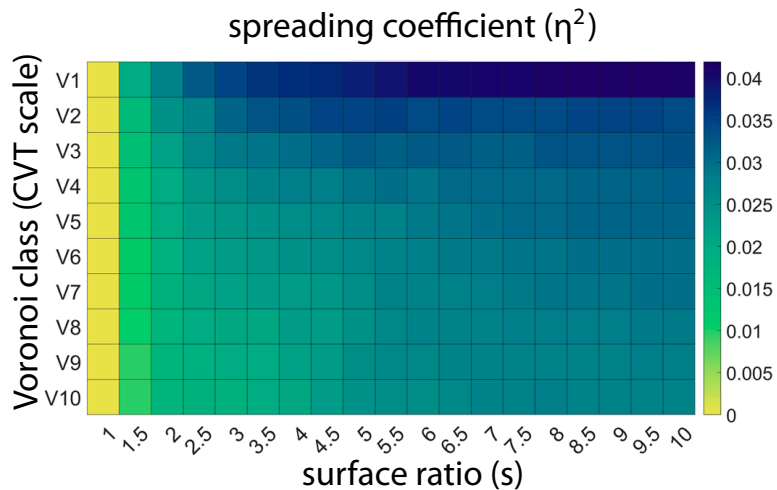
H



A



B



C

